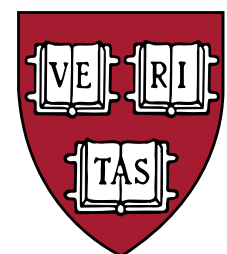


# Leveraging neural simulation-based inference for astrophysical dark matter searches

Based on:

J. Brehmer\*, SM\*, J. Hermans, G. Louppe, K. Cranmer [ApJ, 1909.02005]  
SM, K. Cranmer [PRD, 2110.06931]

Siddharth Mishra-Sharma



NSF Institute for Artificial Intelligence  
and Fundamental Interactions

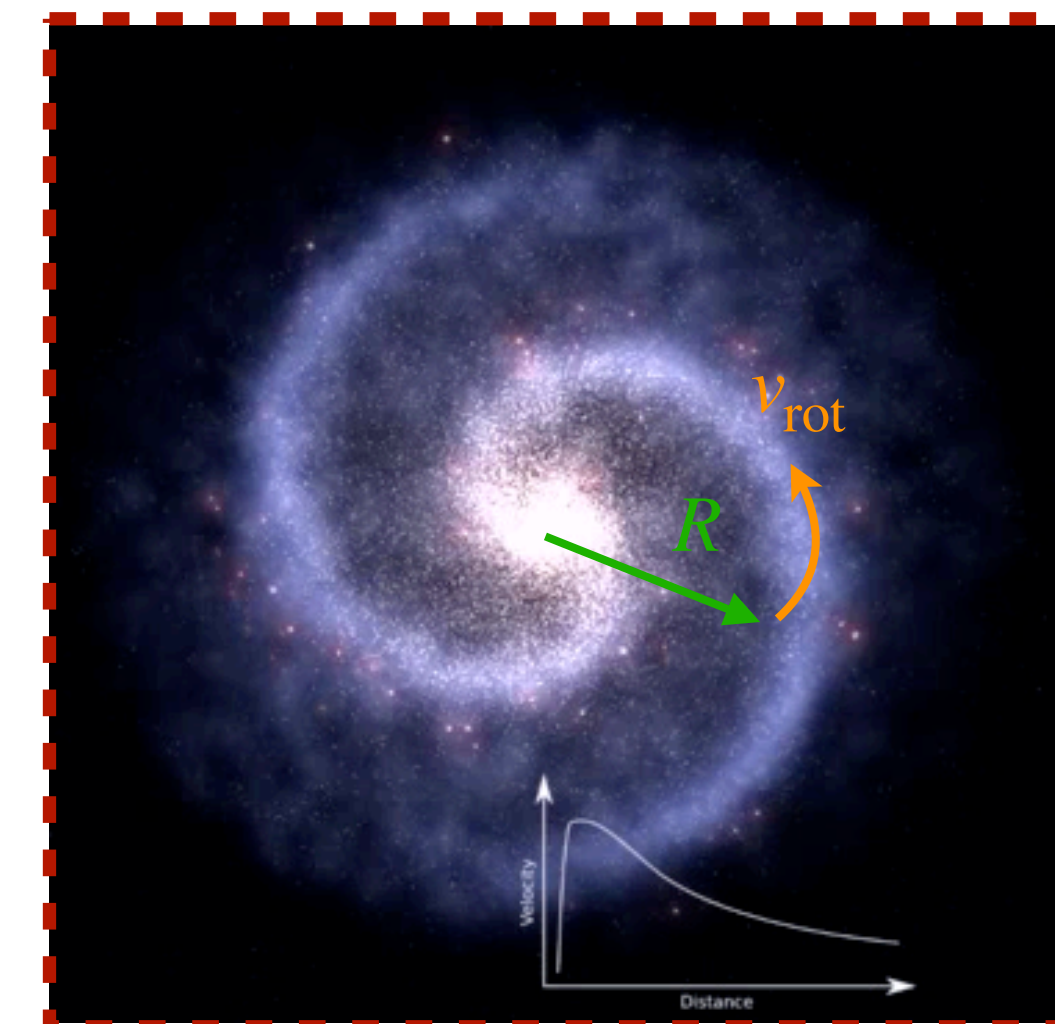
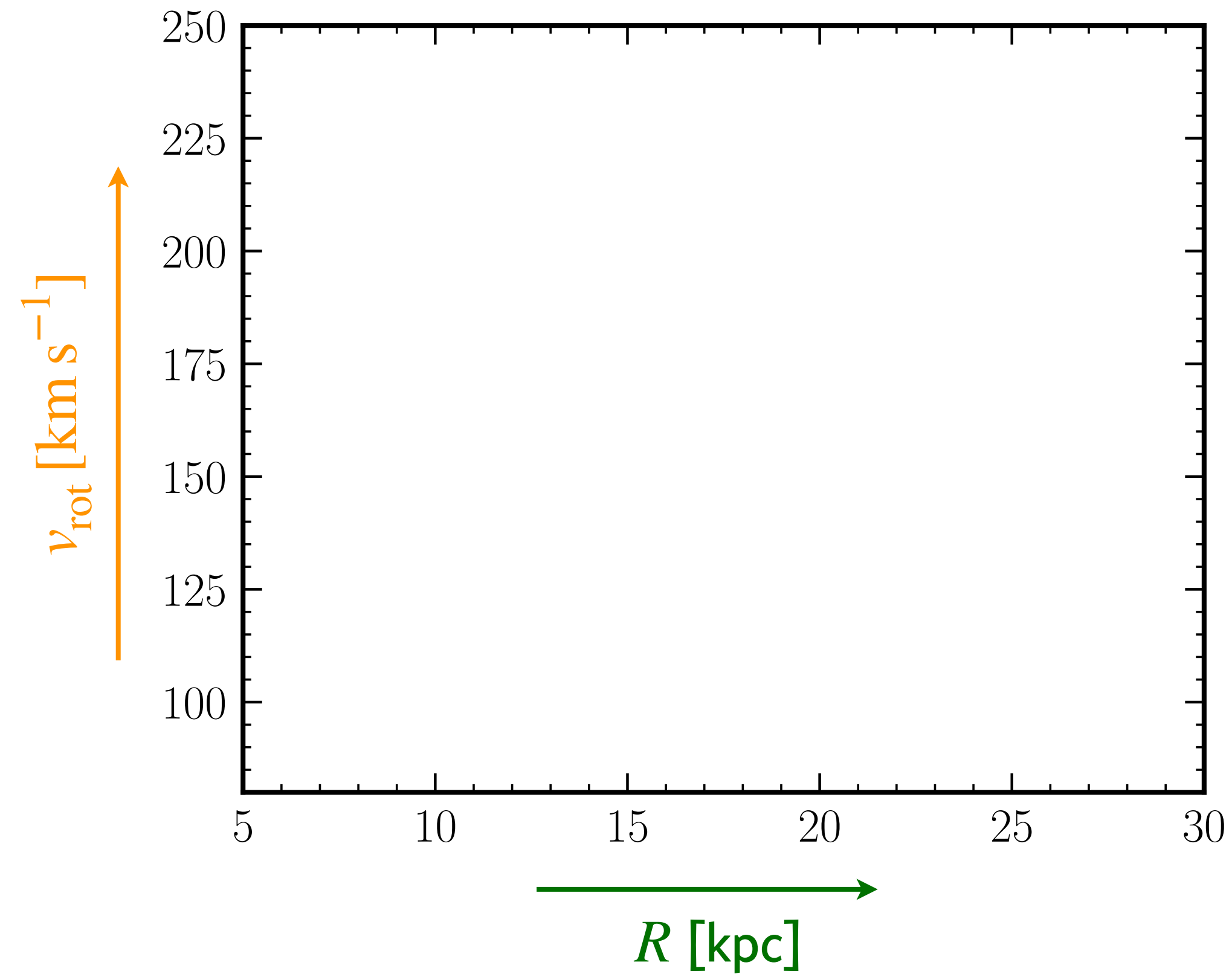
CHASC Astrostatistics Seminar

April 5, 2022

# Evidence for dark matter

## Galactic rotation curves

$$v_{\text{rot}}(r) = \sqrt{\frac{GM_{\text{enc}}}{r}}$$

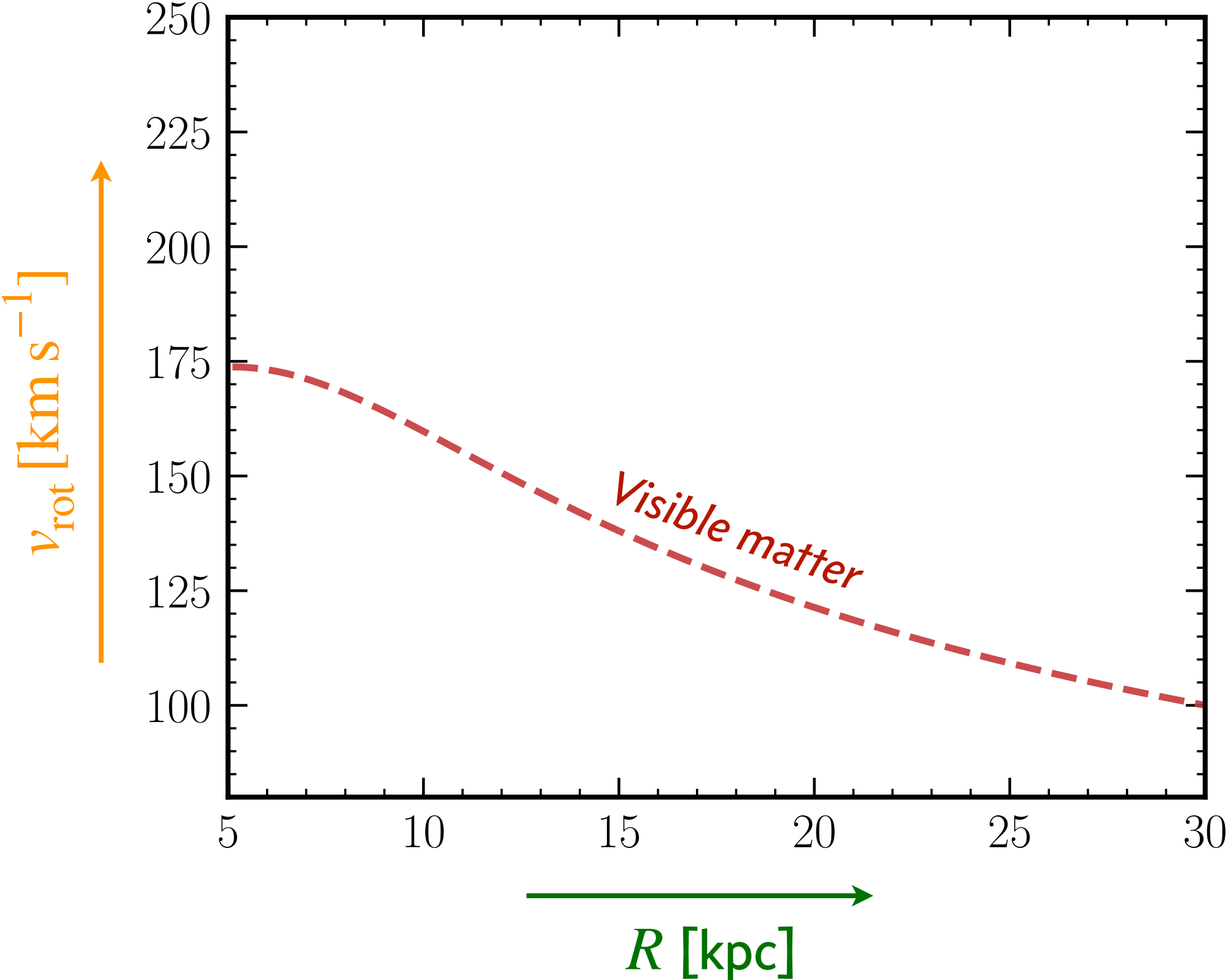


[https://beltoforion.de/en/spiral\\_galaxy\\_renderer/](https://beltoforion.de/en/spiral_galaxy_renderer/)

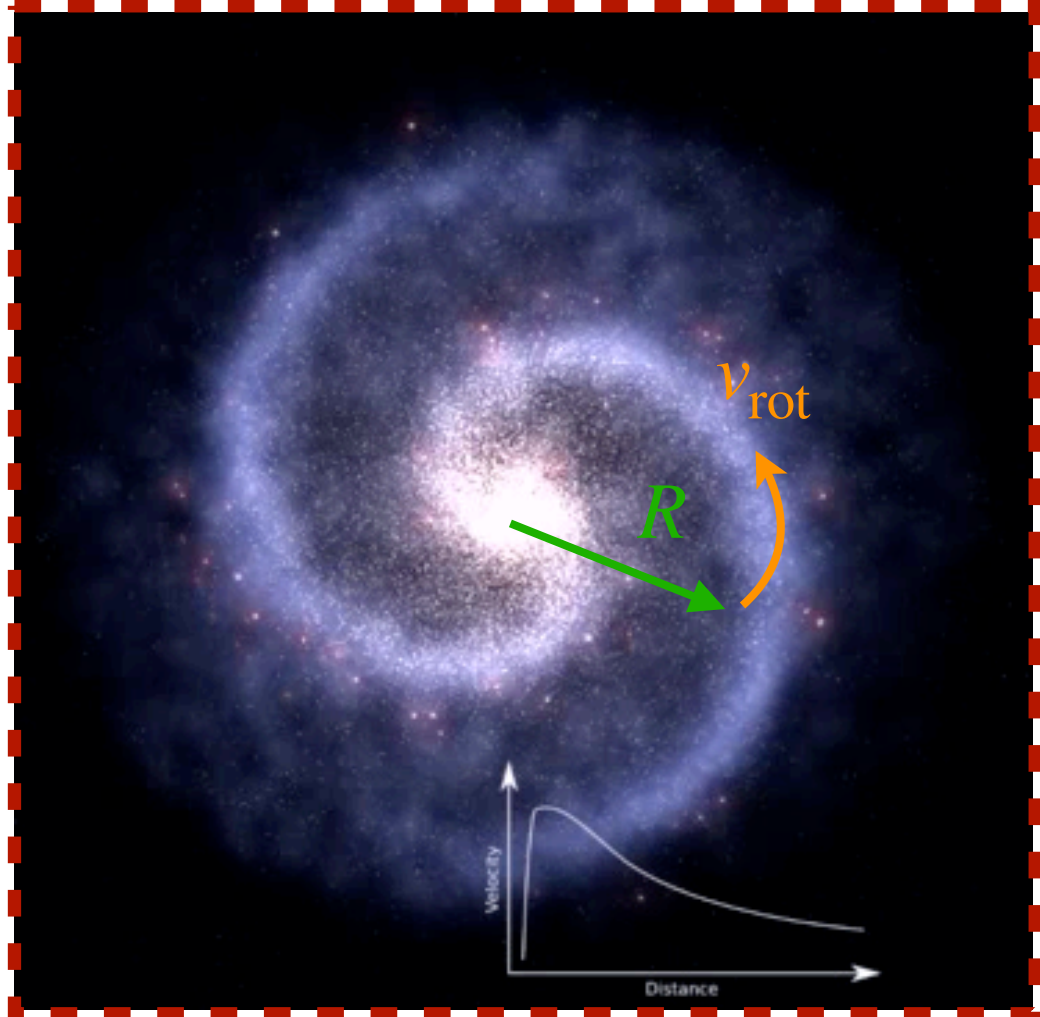
# Evidence for dark matter

## Galactic rotation curves

$$v_{\text{rot}}(r) = \sqrt{\frac{GM_{\text{enc}}}{r}}$$



*Only visible matter*

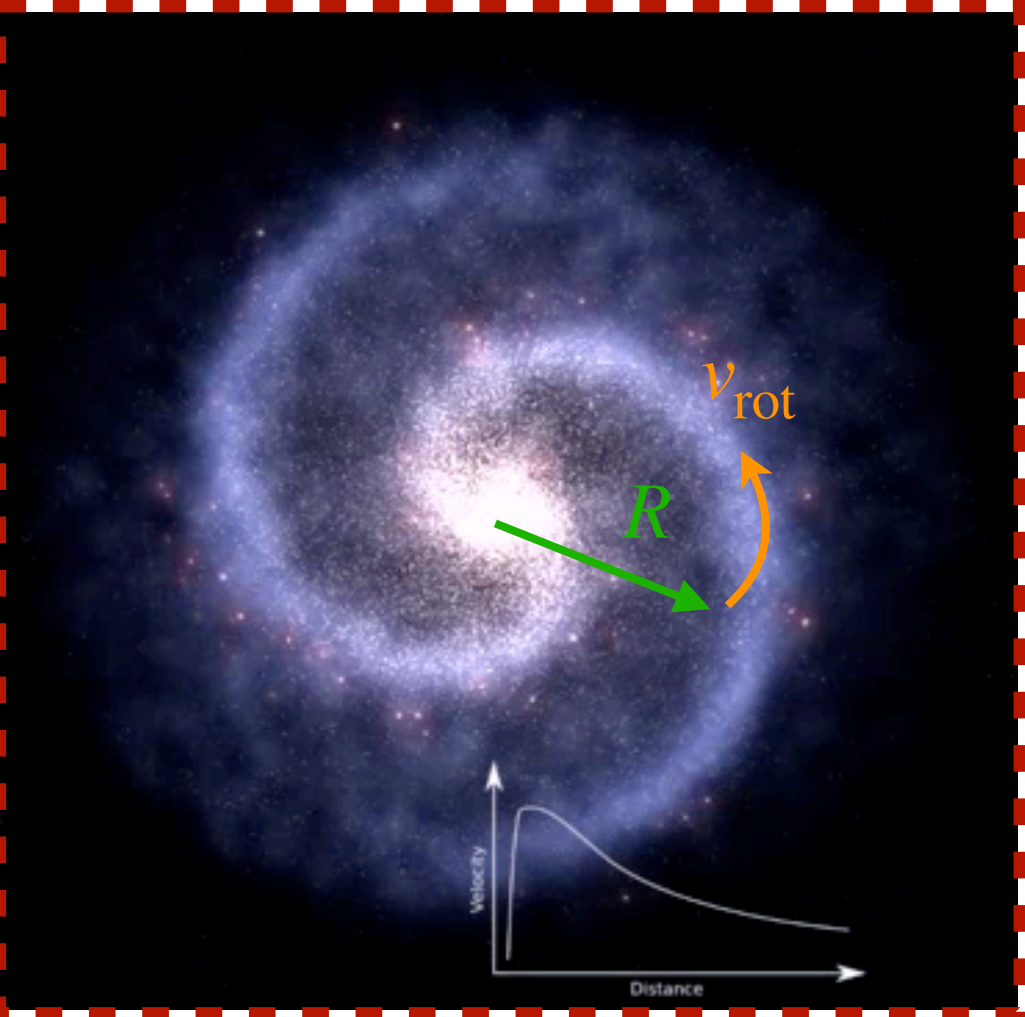
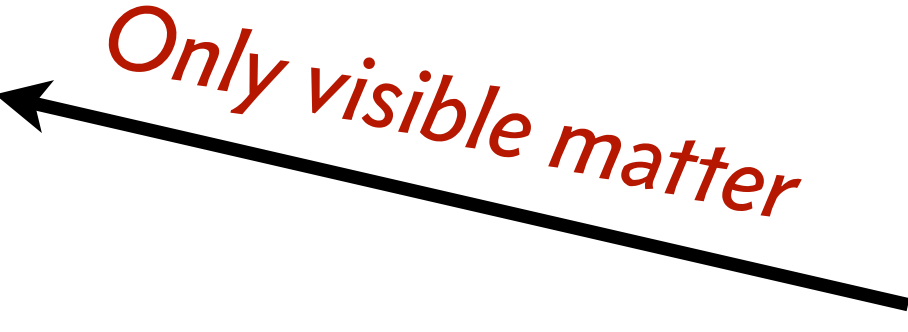
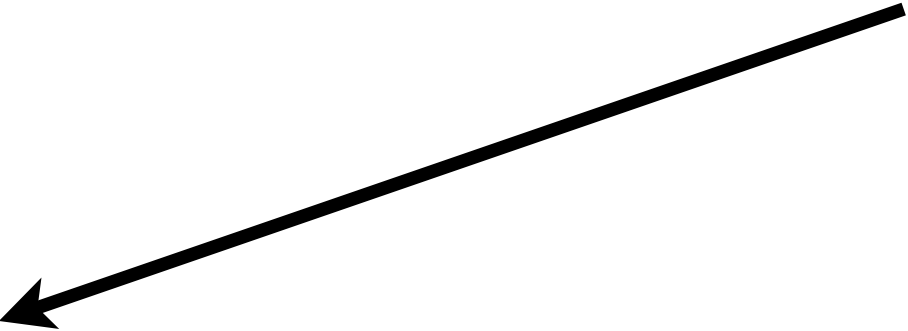
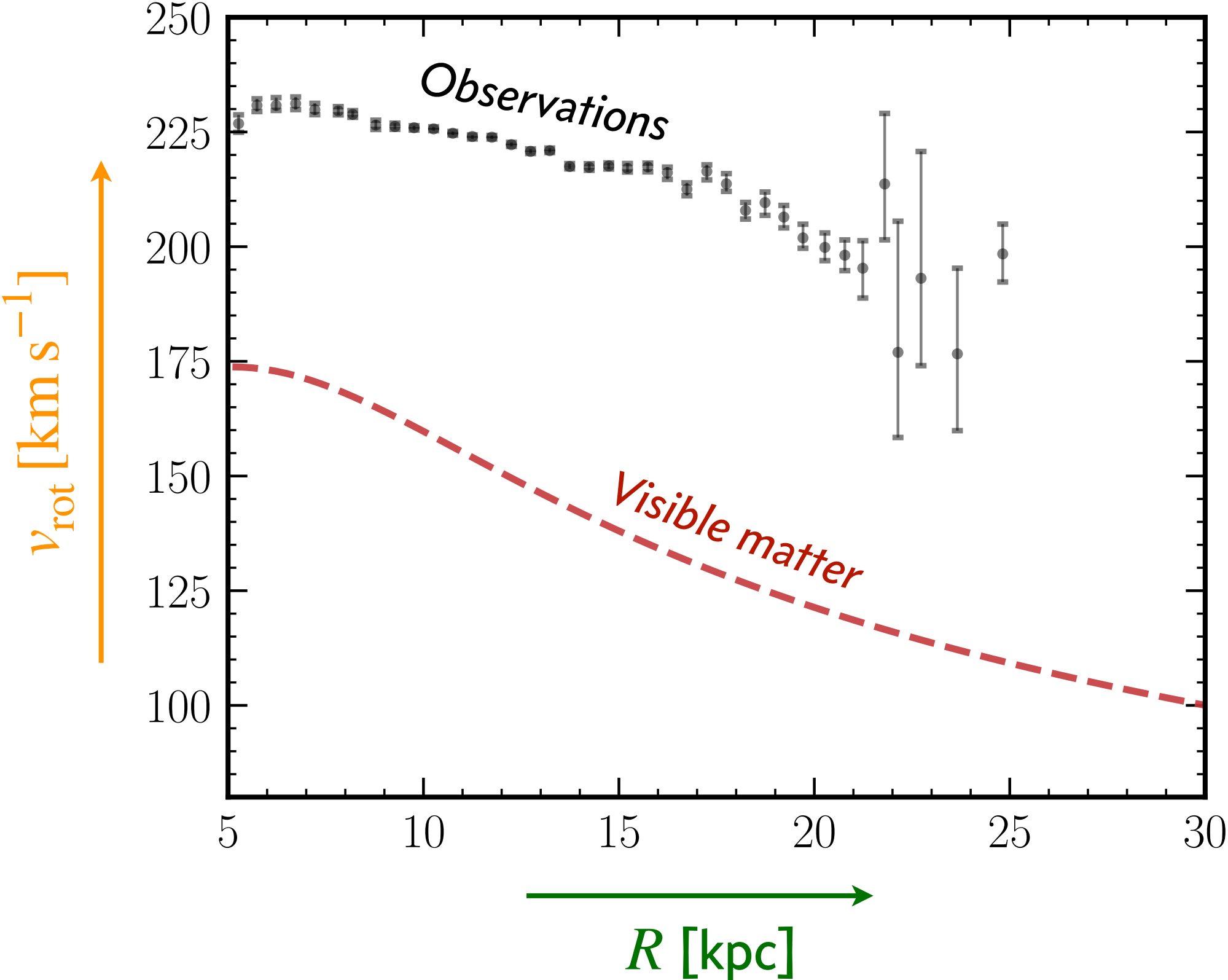


[https://beltoforion.de/en/spiral\\_galaxy\\_renderer/](https://beltoforion.de/en/spiral_galaxy_renderer/)

# Evidence for dark matter

## Galactic rotation curves

$$v_{\text{rot}}(r) = \sqrt{\frac{GM_{\text{enc}}}{r}}$$

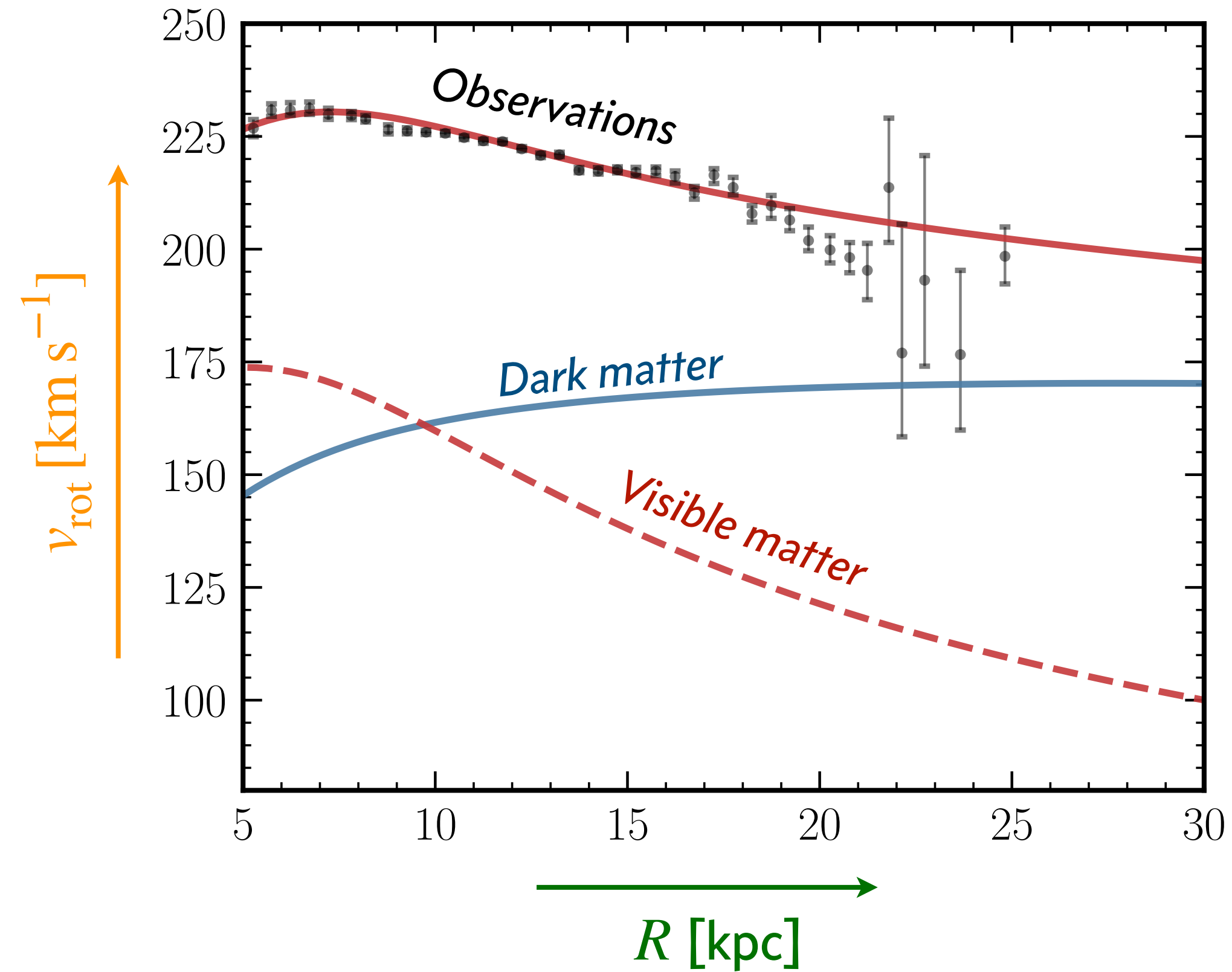


[https://beltoforion.de/en/spiral\\_galaxy\\_renderer/](https://beltoforion.de/en/spiral_galaxy_renderer/)

# Evidence for dark matter

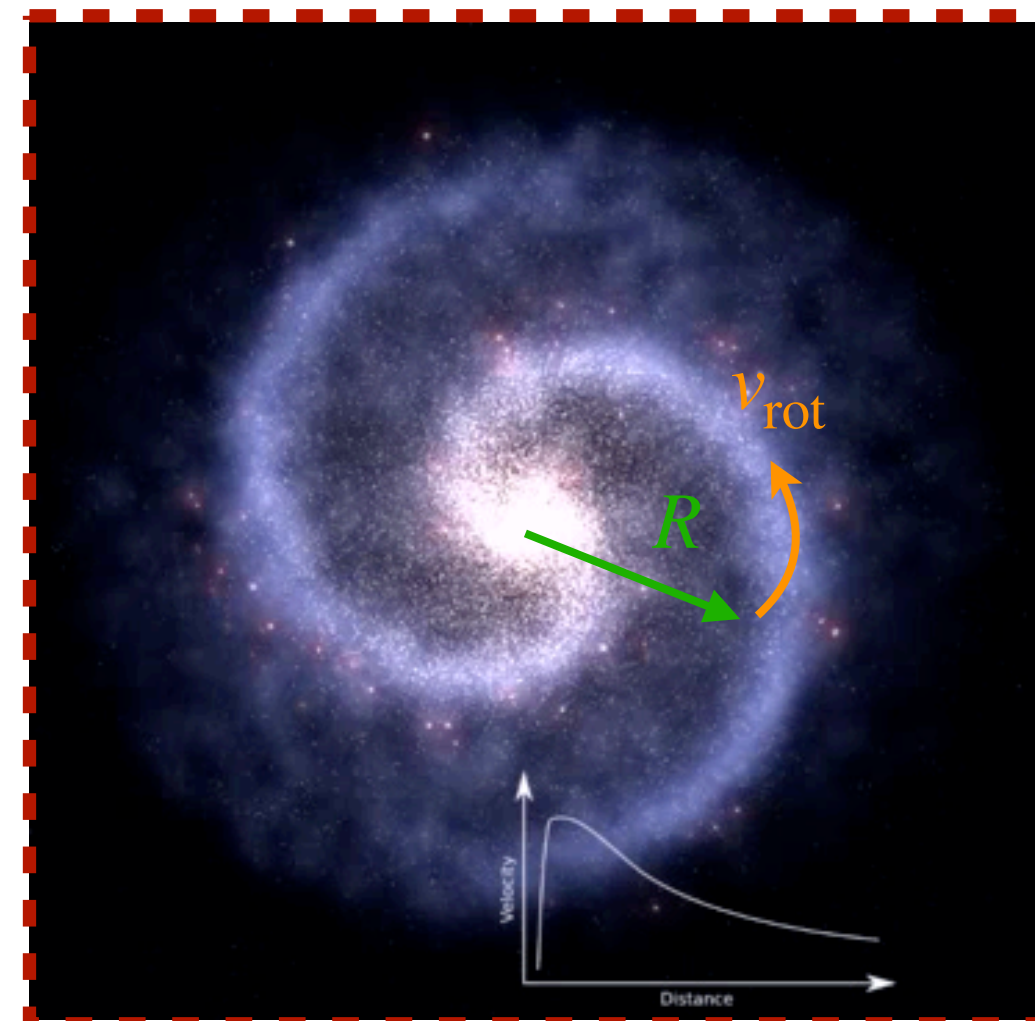
## Galactic rotation curves

$$v_{\text{rot}}(r) = \sqrt{\frac{GM_{\text{enc}}}{r}}$$



With dark matter

Only visible matter

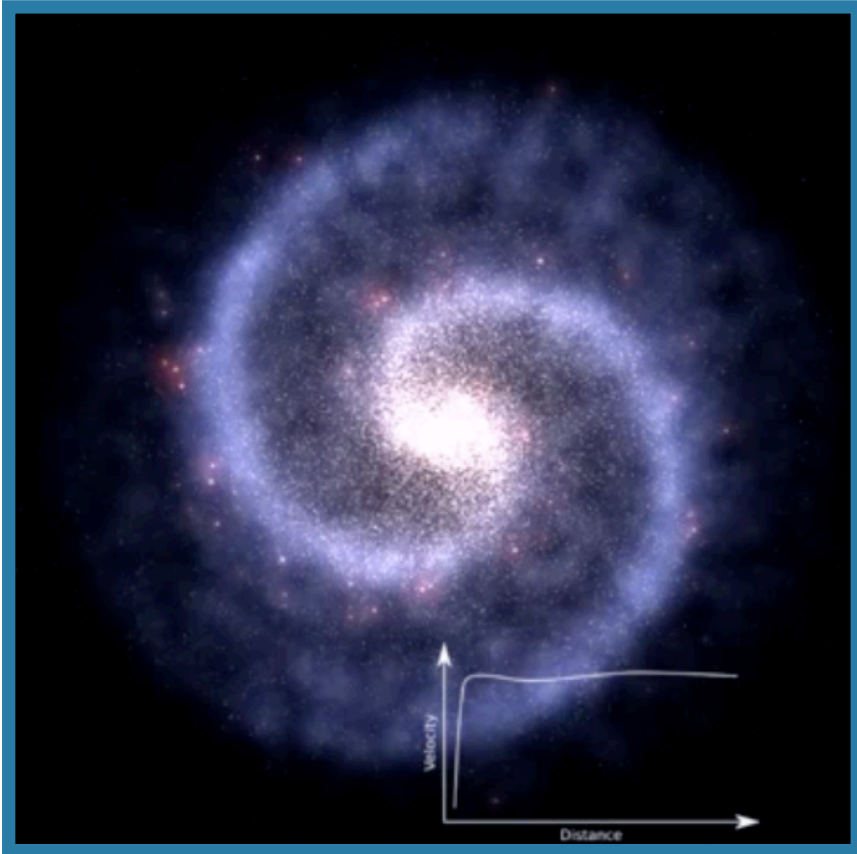


[https://beltoforion.de/en/spiral\\_galaxy\\_renderer/](https://beltoforion.de/en/spiral_galaxy_renderer/)

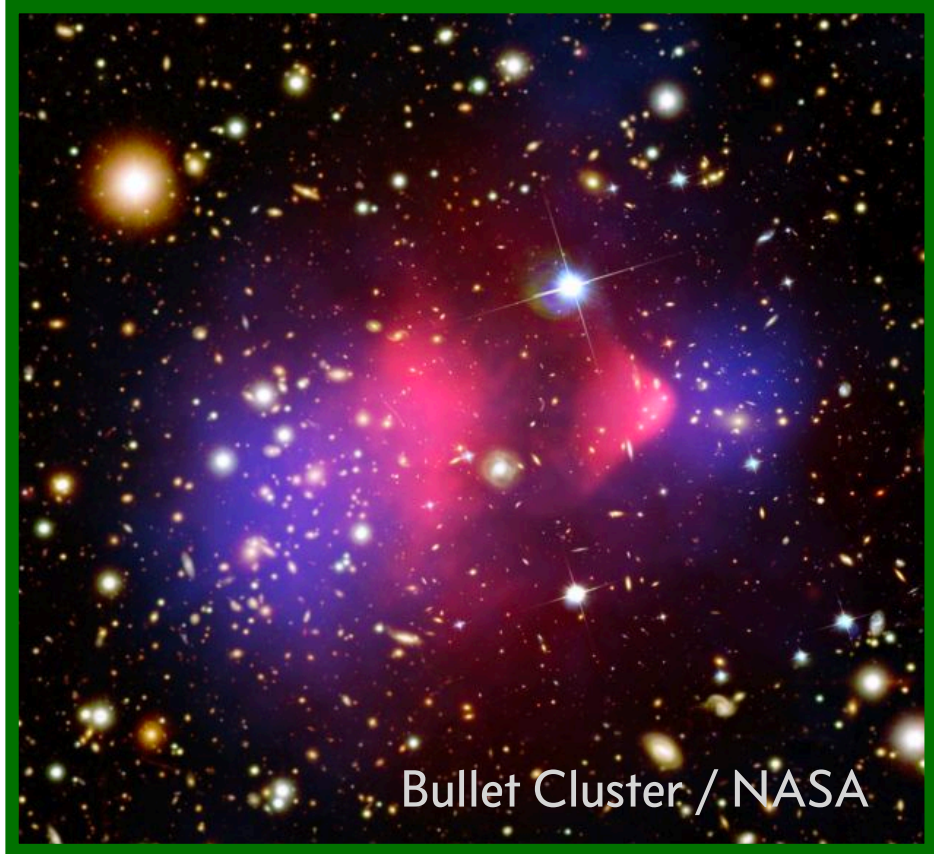
# Evidence for dark matter...

...exists over a diversity of scales and physical systems

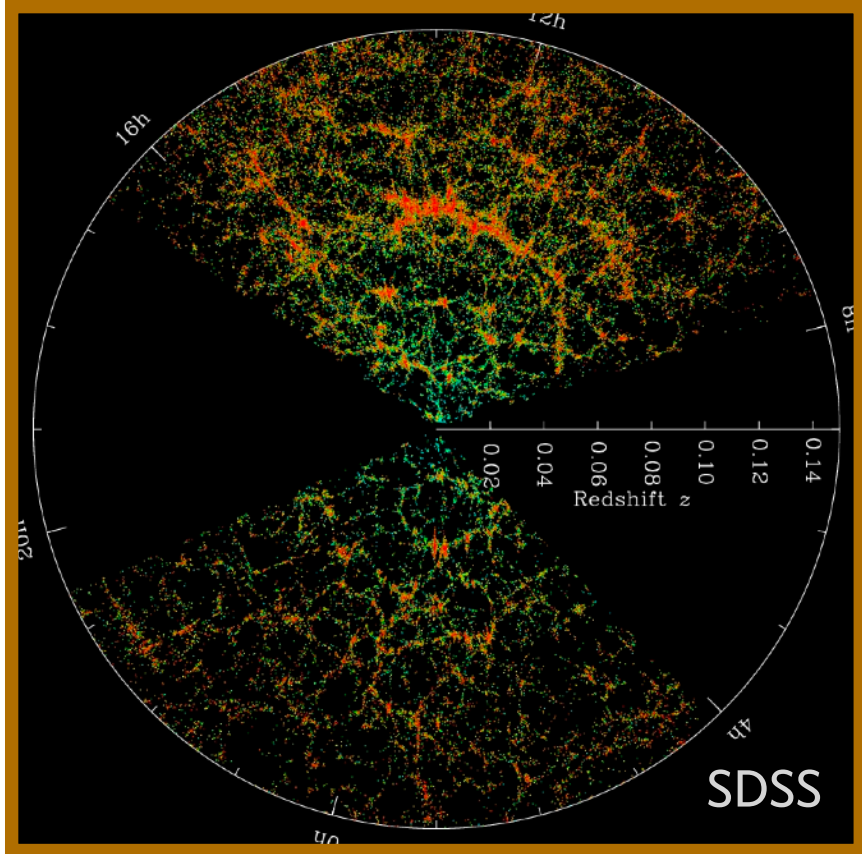
*Galaxy rotation curves*



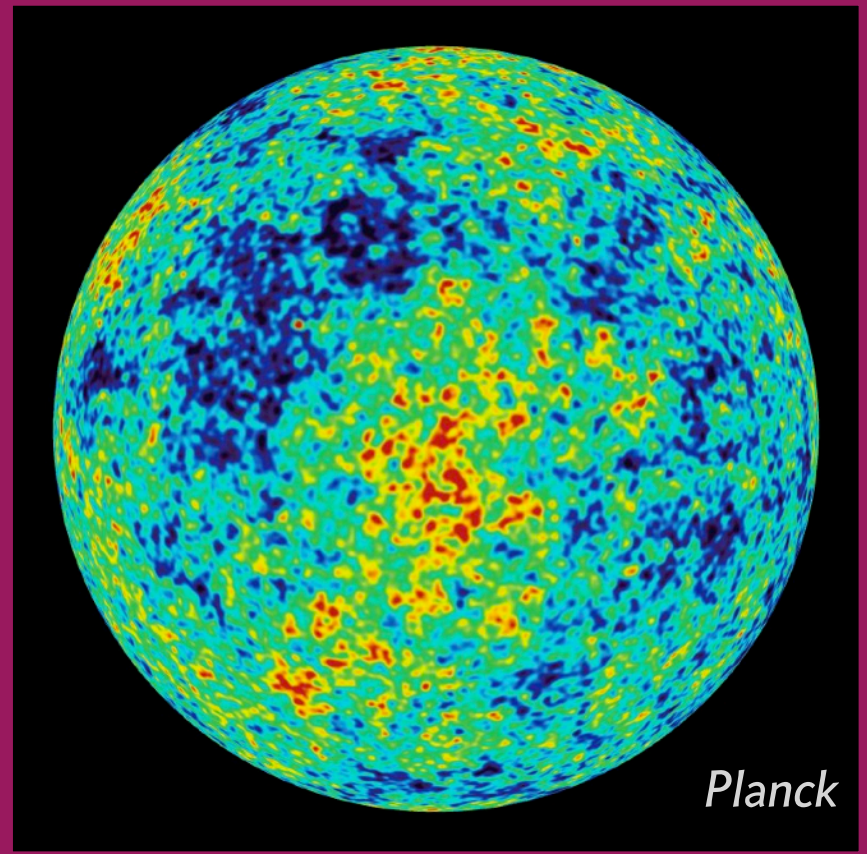
*Galaxy clusters*



*Large-scale structure*

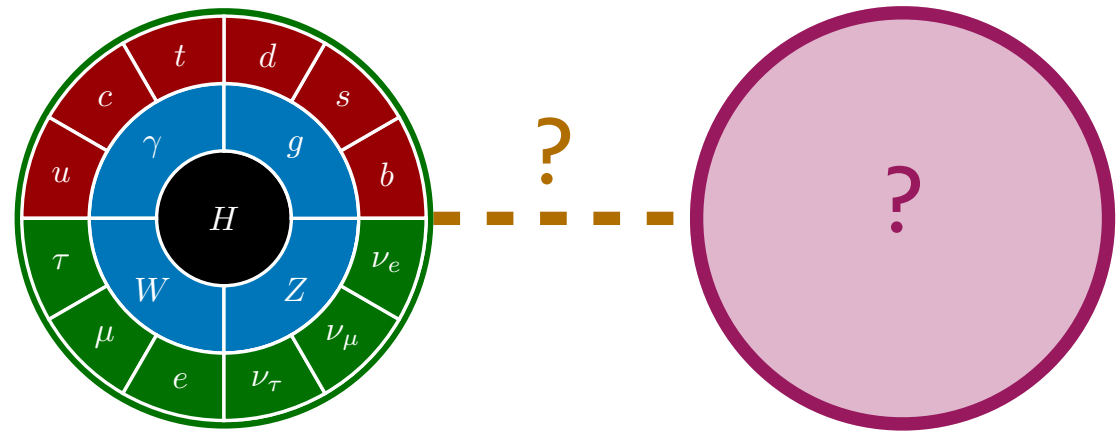


*Cosmic Microwave Background*

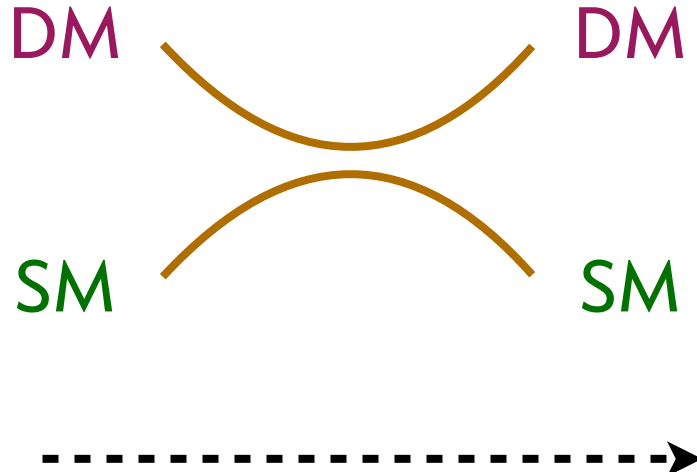


*Increasing scale*

# Searches for dark matter



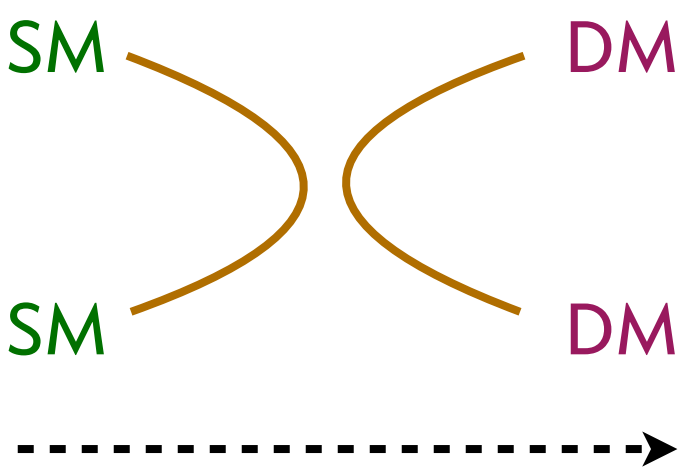
Scattering of DM against SM



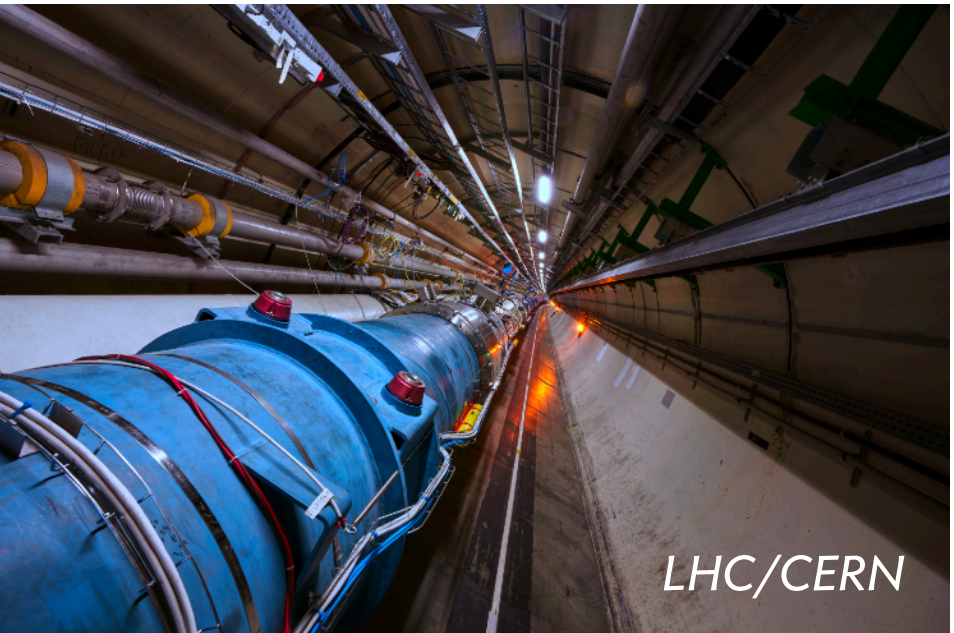
Direct detection



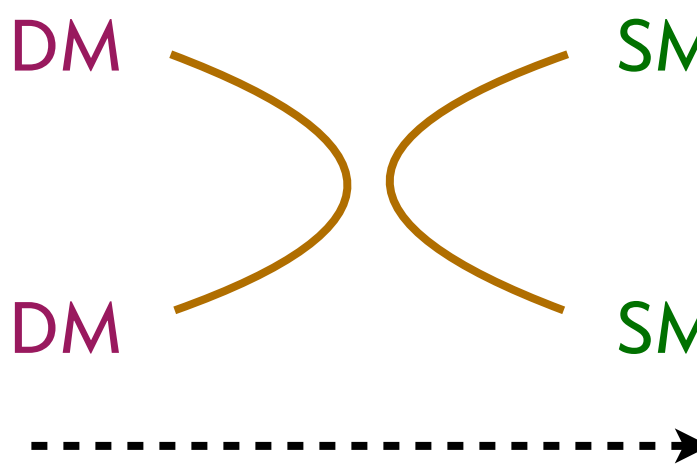
Production of DM from SM



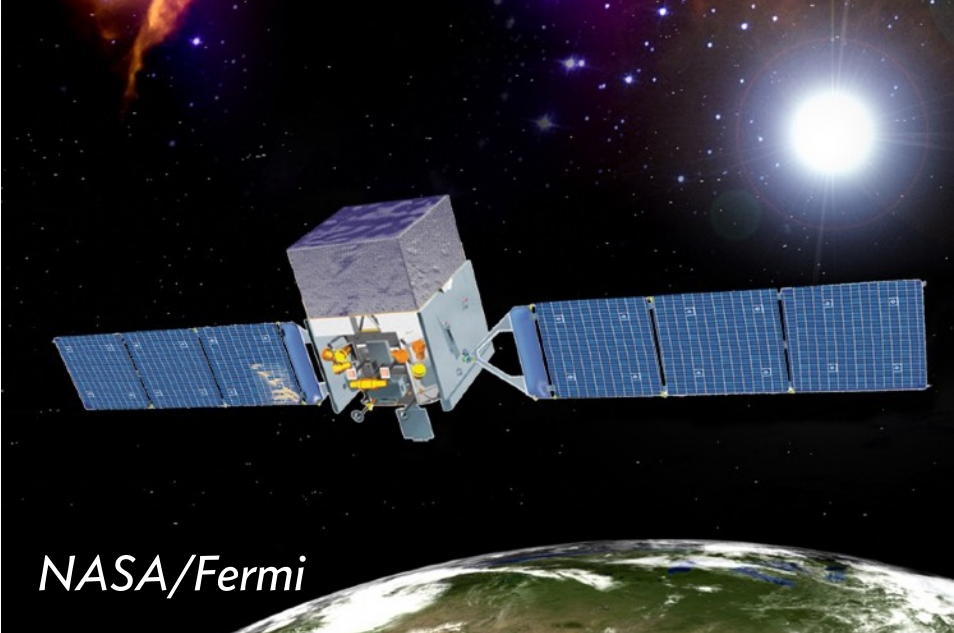
Particle colliders



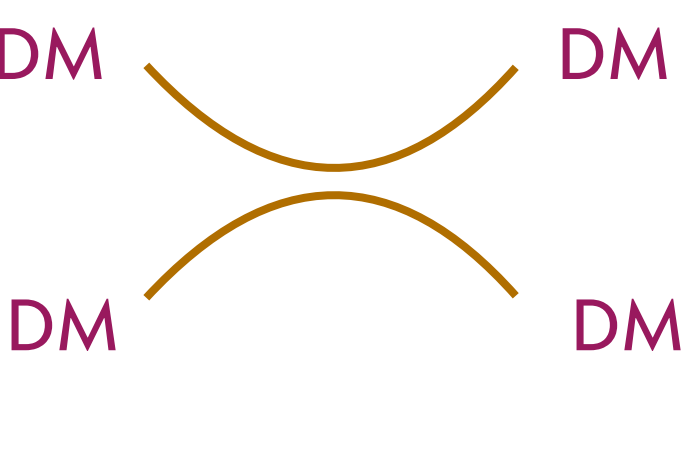
Production of SM from DM



Indirect detection



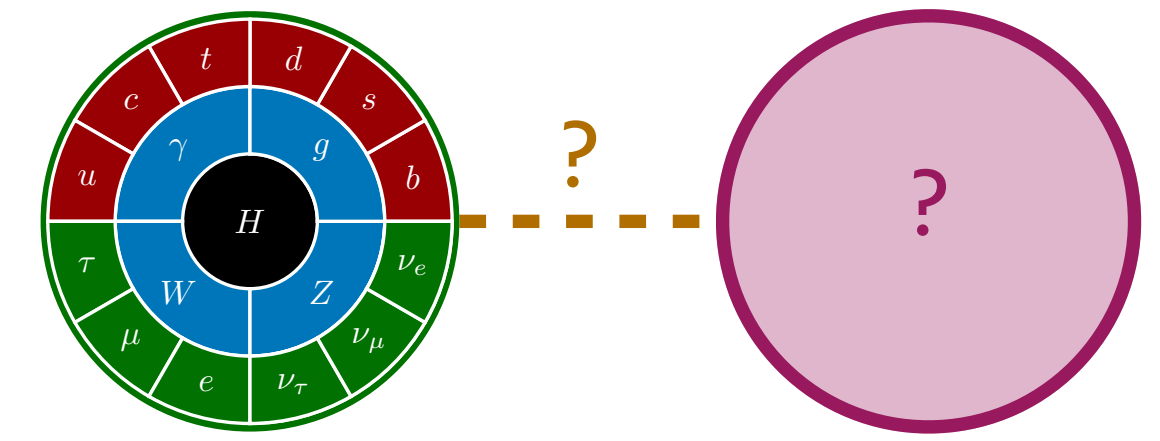
Gravitational effects of DM interaction



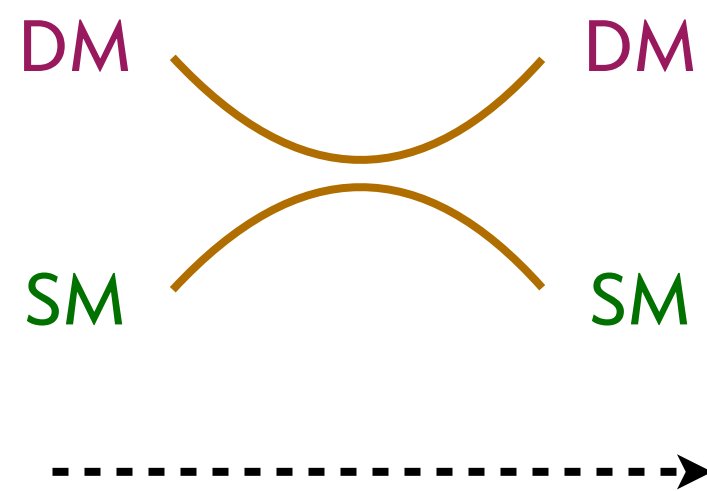
Astrophysical probes



# Searches for dark matter



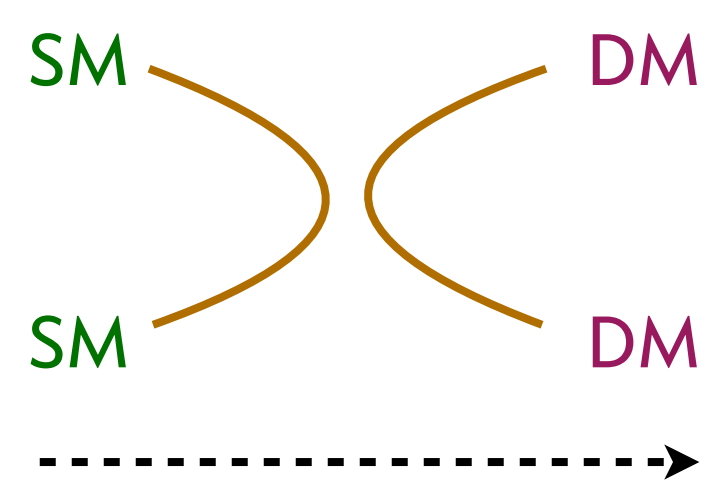
## Scattering of DM against SM



Direct detection



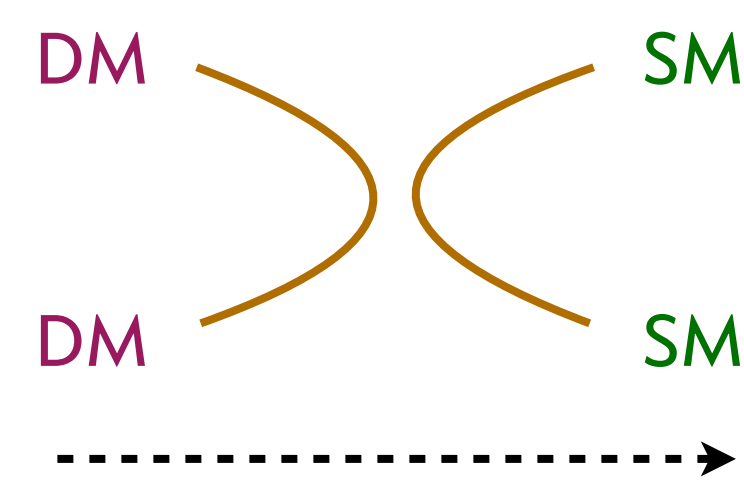
## Production of DM from SM



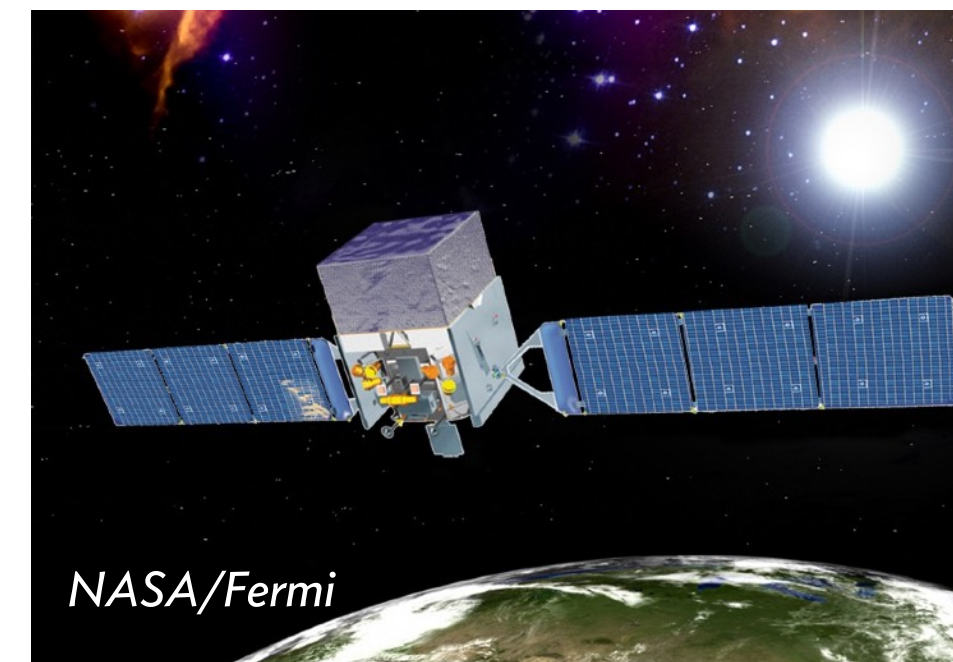
Particle colliders



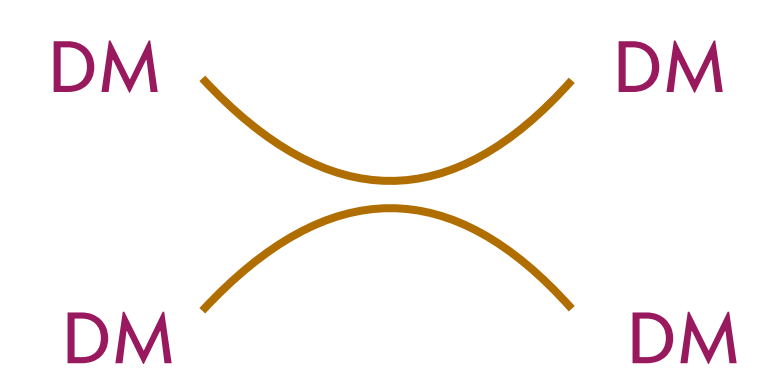
## Production of SM from DM



Indirect detection



## Gravitational effects of DM interaction

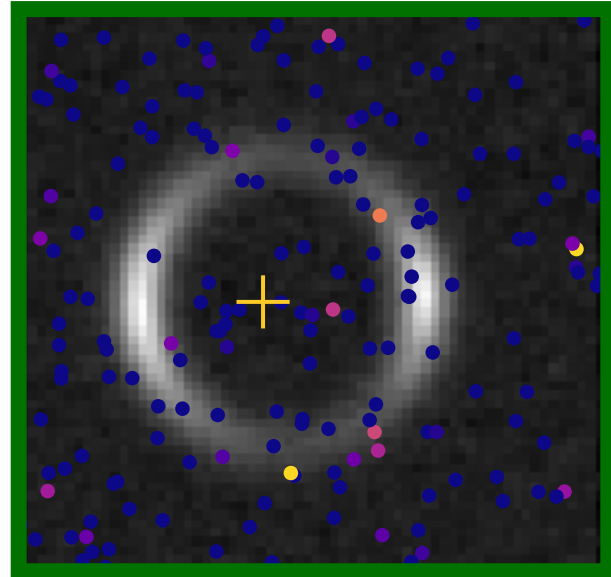


Astrophysical probes



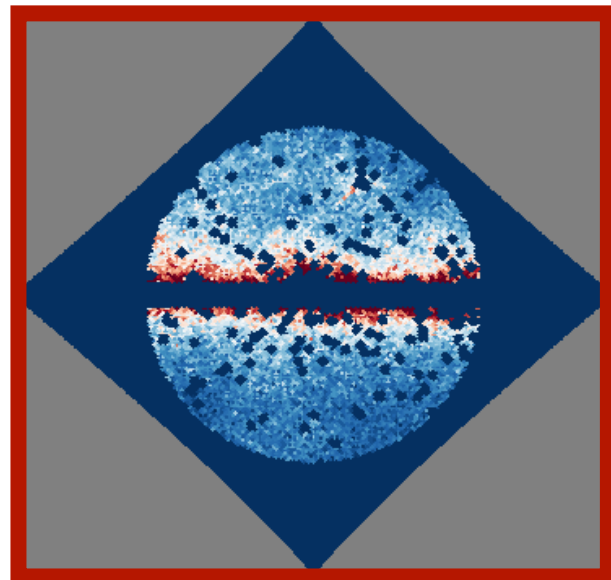


# Outline



## Detecting extragalactic dark matter in strong lenses

*Combining information from thousands of systems*

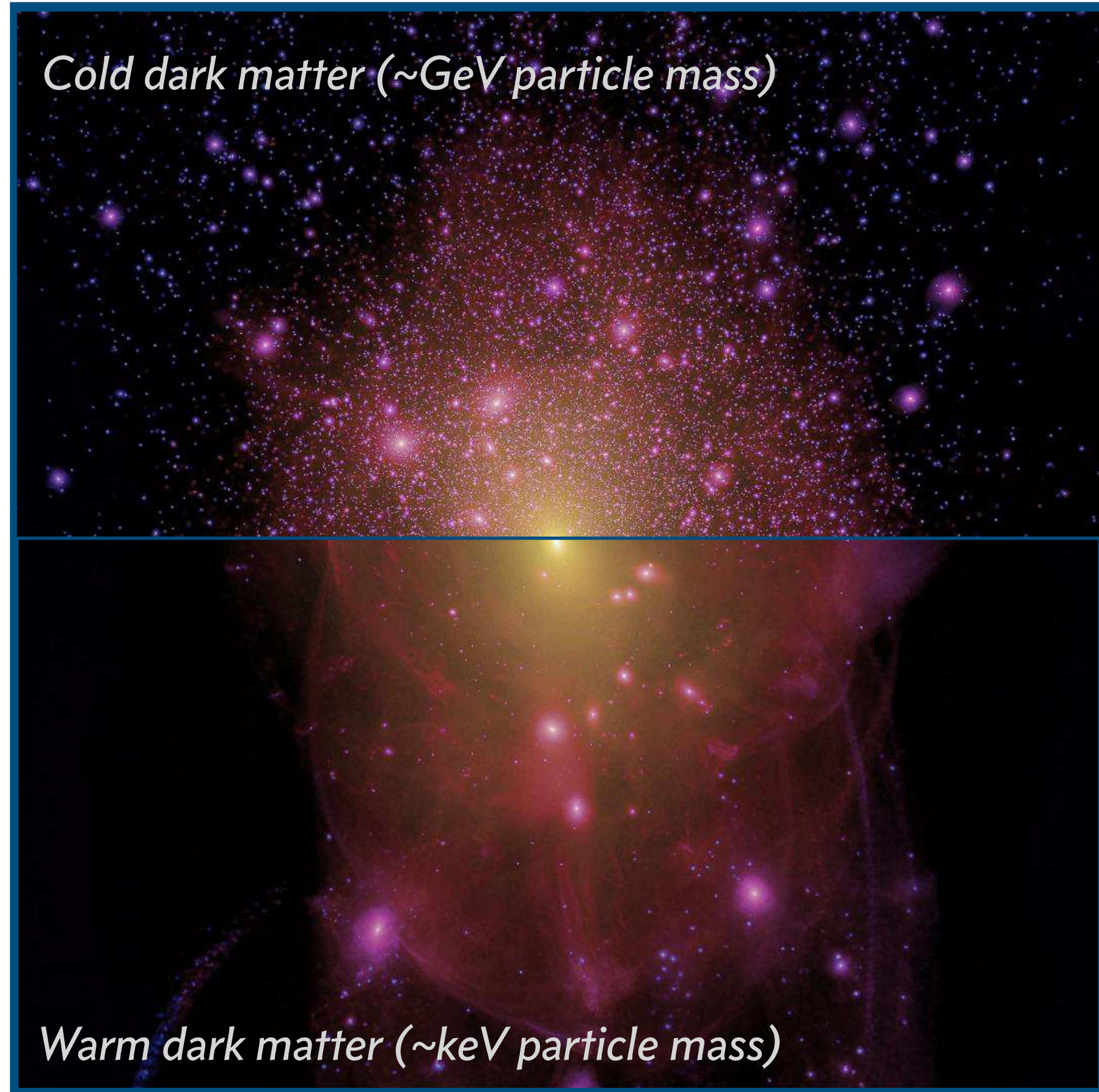


## Characterizing $\gamma$ -ray point sources in the Galactic Center

*Exploiting more information to reduce model misspecification*

# Microphysics from macrophysics

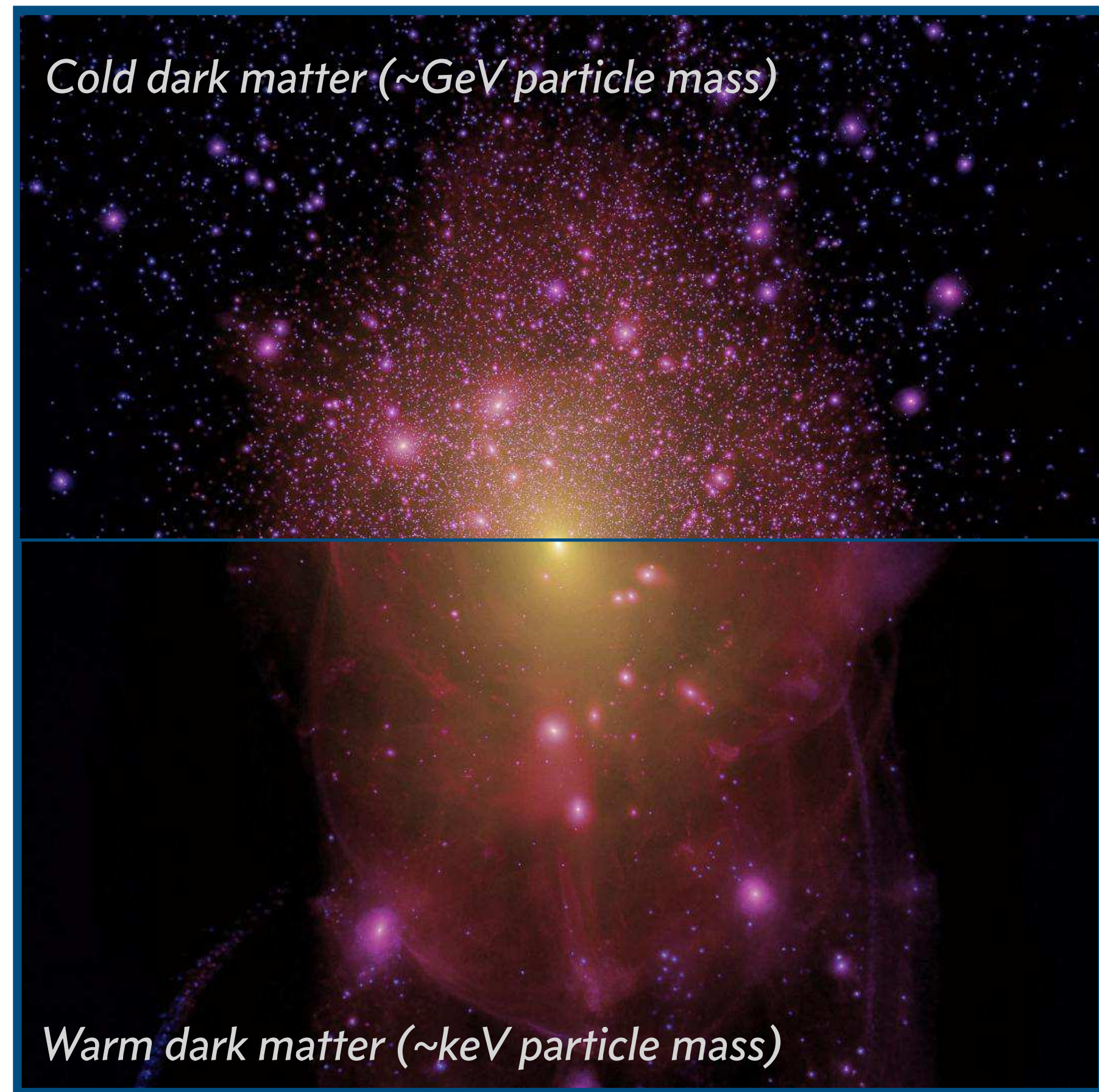
Signs of new physics can show up in the macroscopic distribution of matter



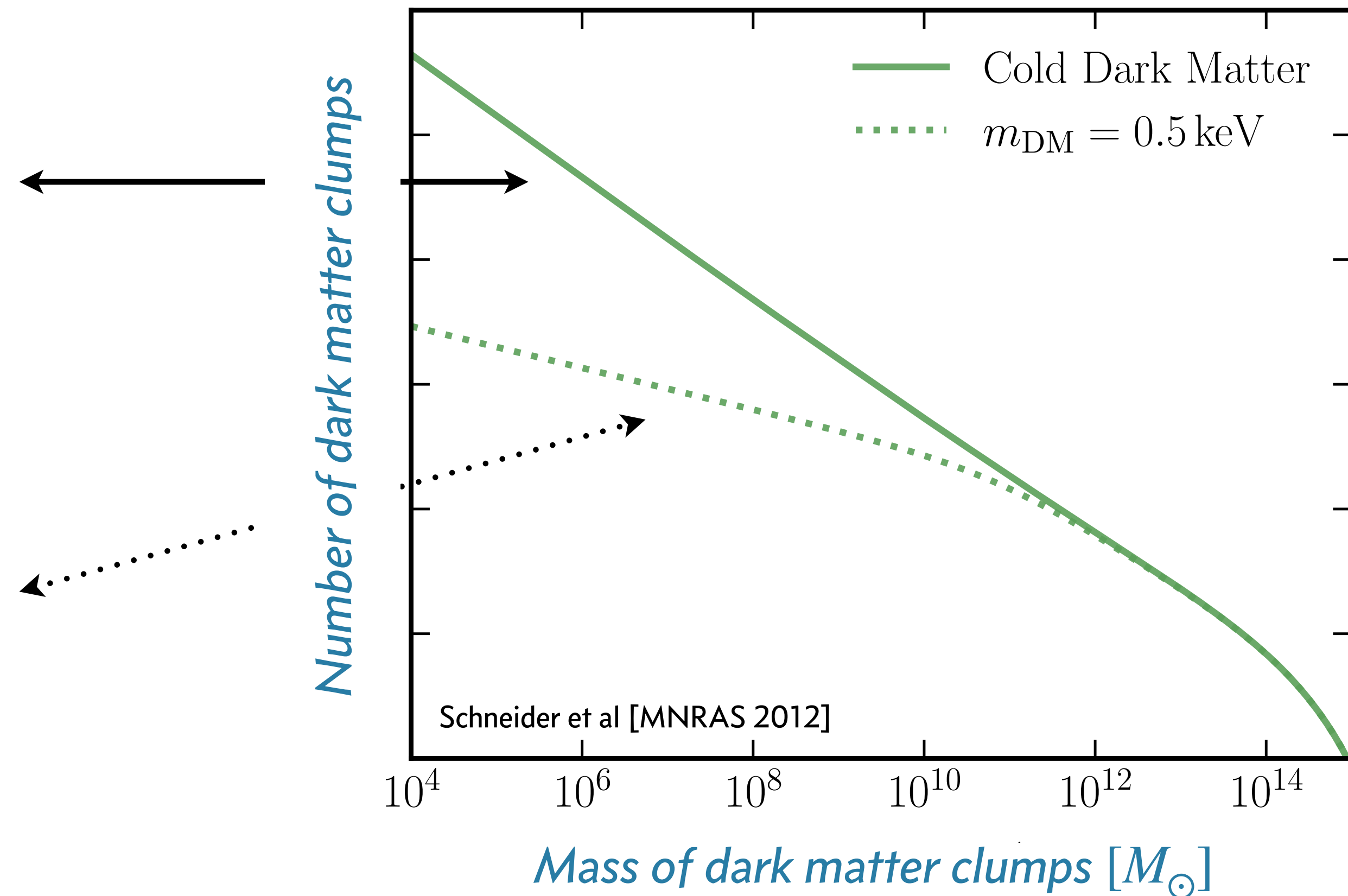
*Aquarius simulation*

# Microphysics from macrophysics

Signs of new physics can show up in the macroscopic distribution of matter

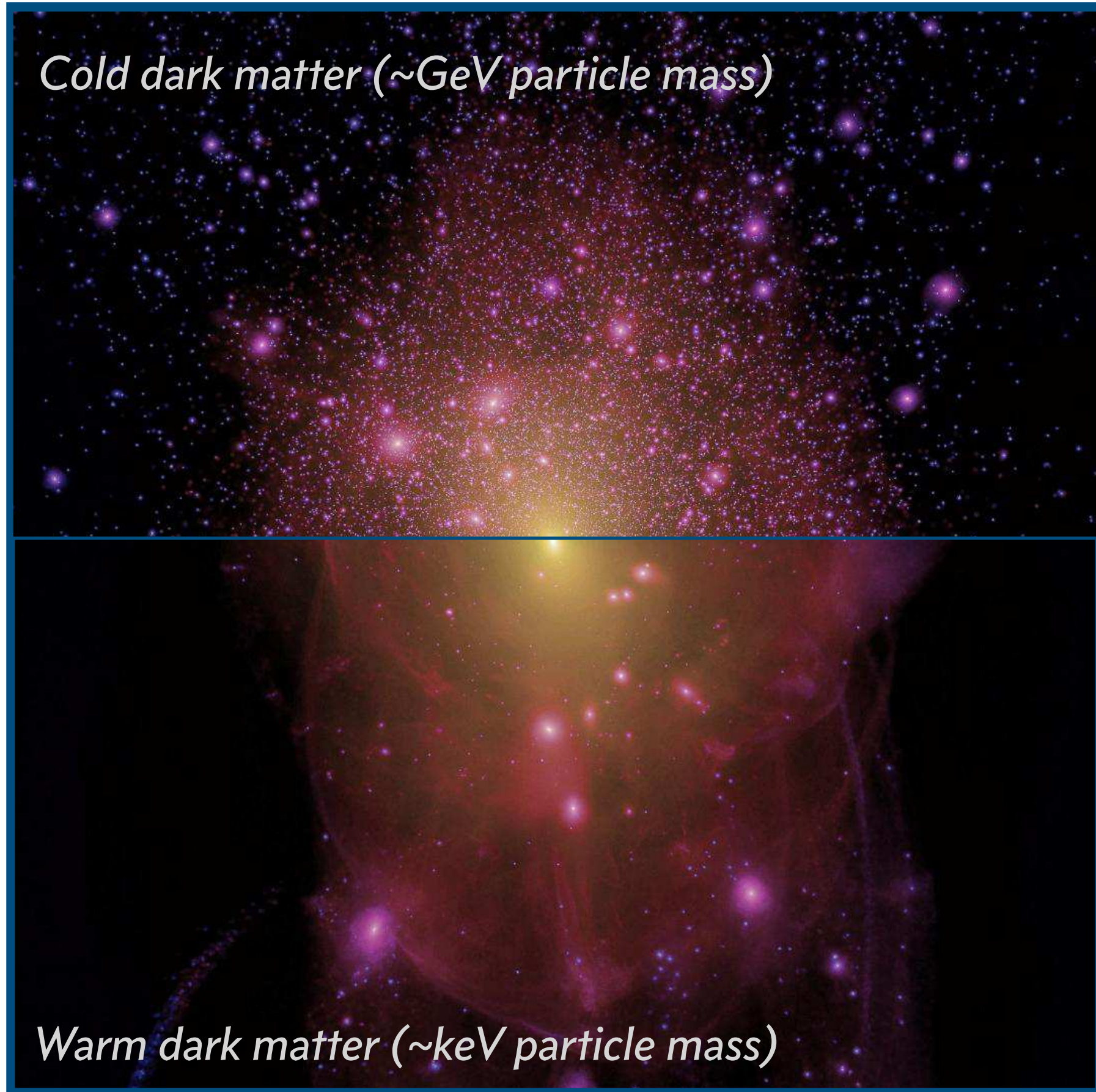
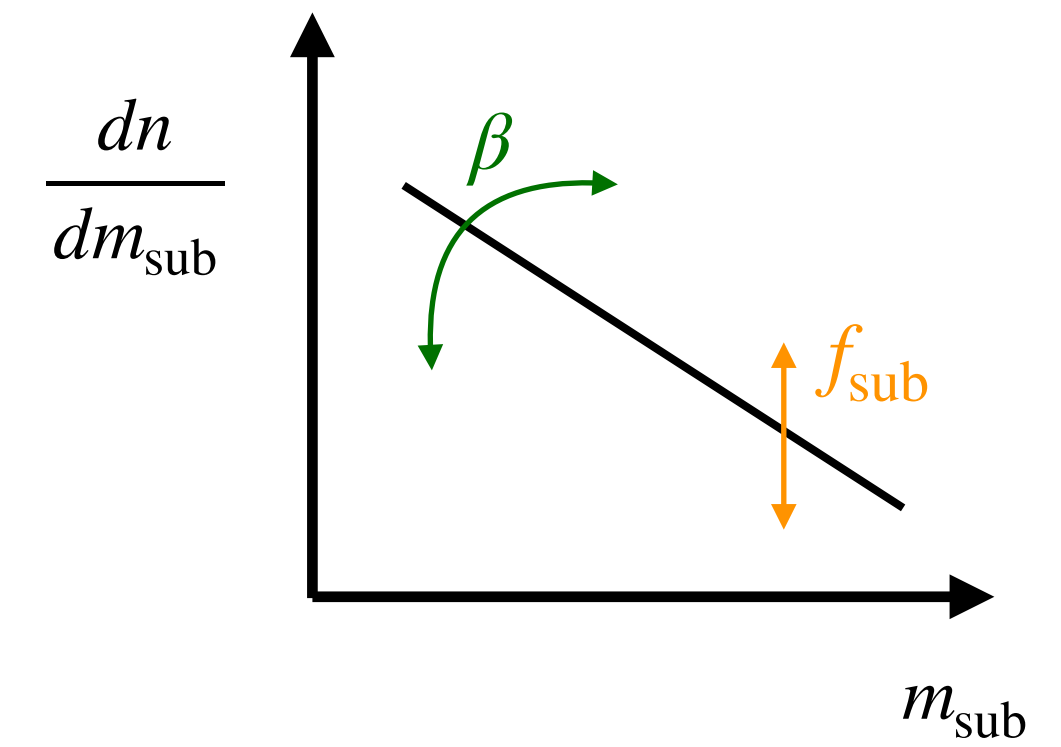


Aquarius simulation

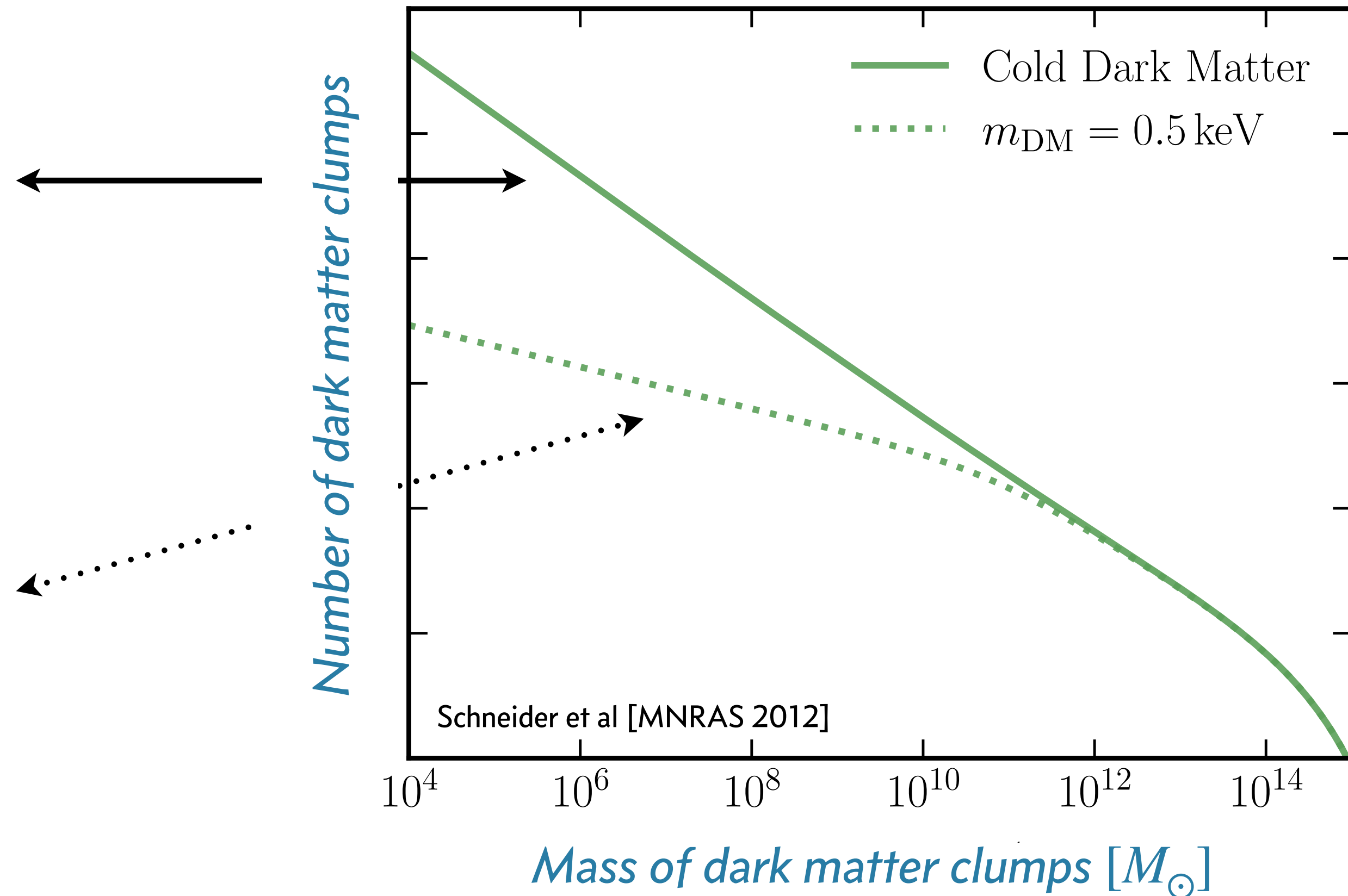


# Microphysics from macrophysics

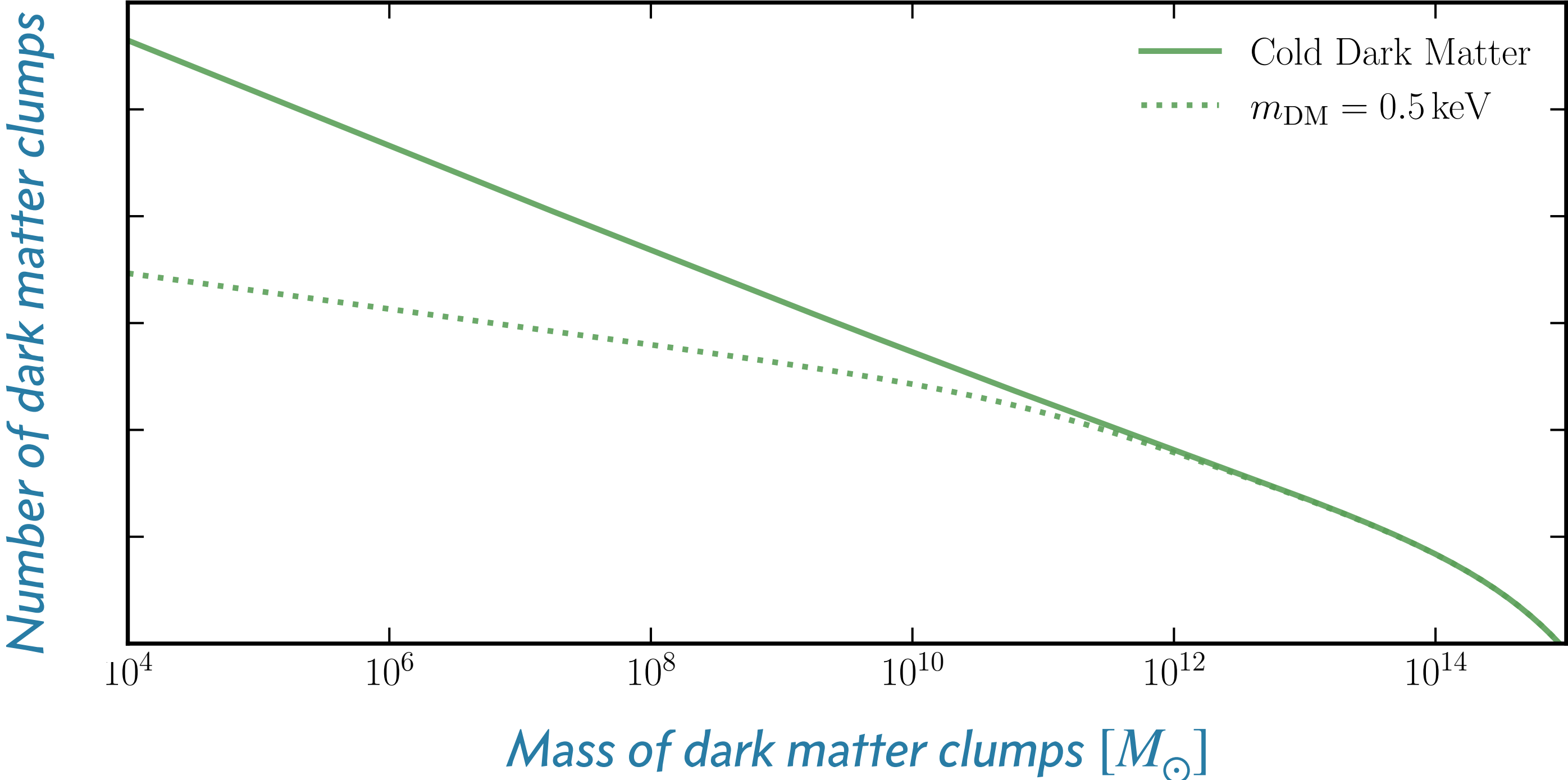
Signs of new physics can show up in the macroscopic distribution of matter



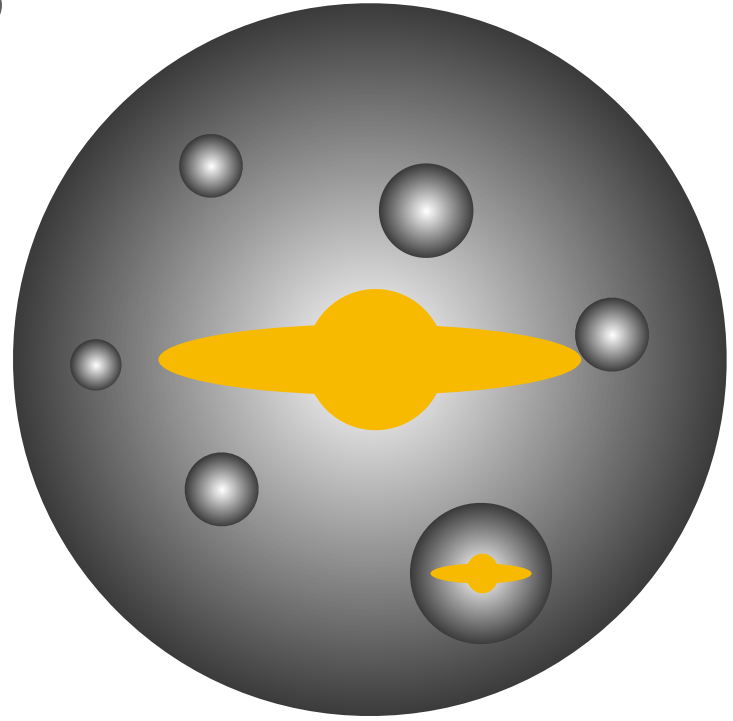
Aquarius simulation



# Finding dark matter subhalos



# Finding dark matter subhalos

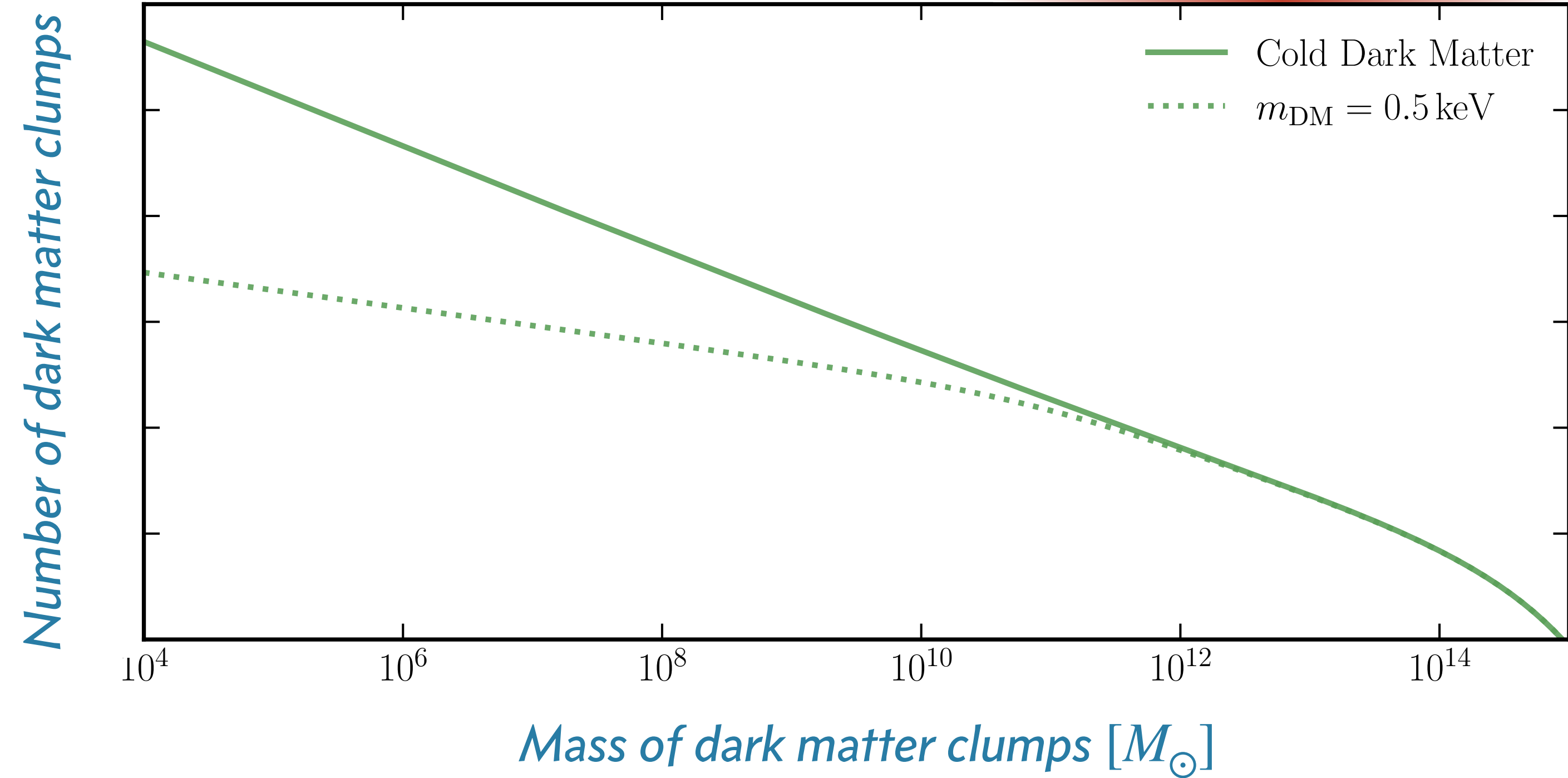


Galaxies and clusters

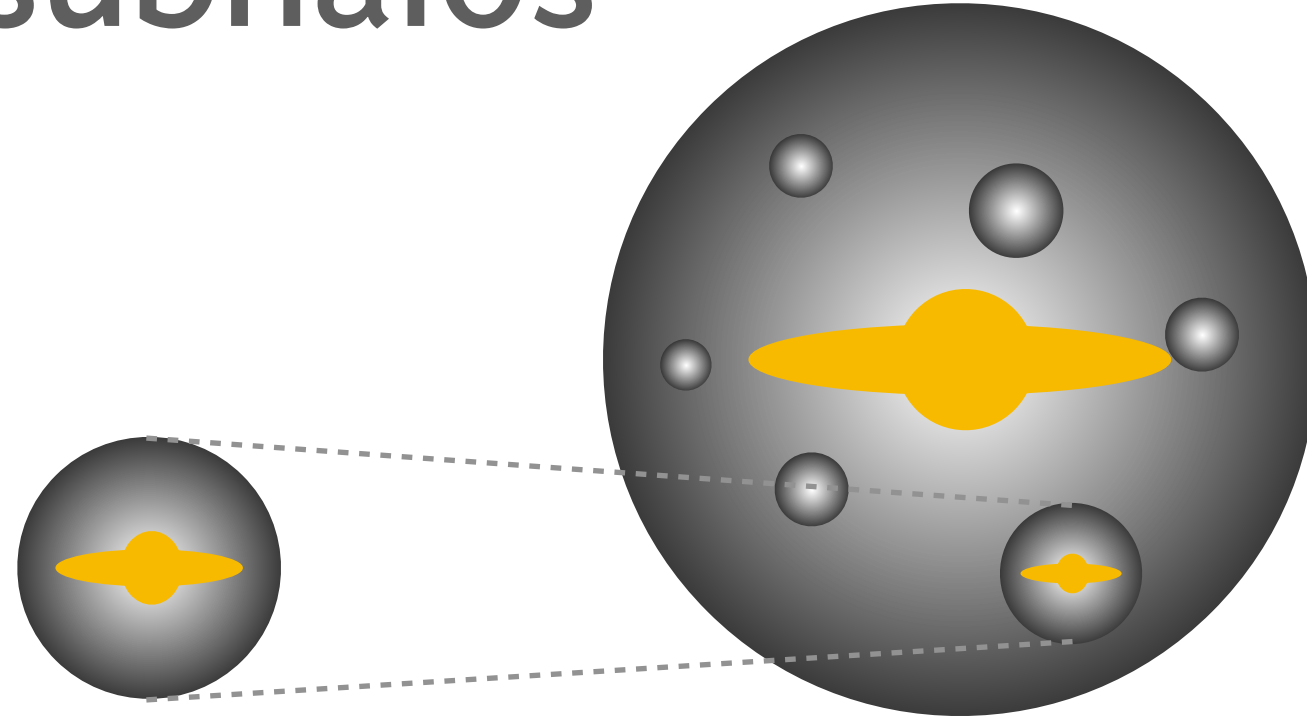
Clusters



Galaxies



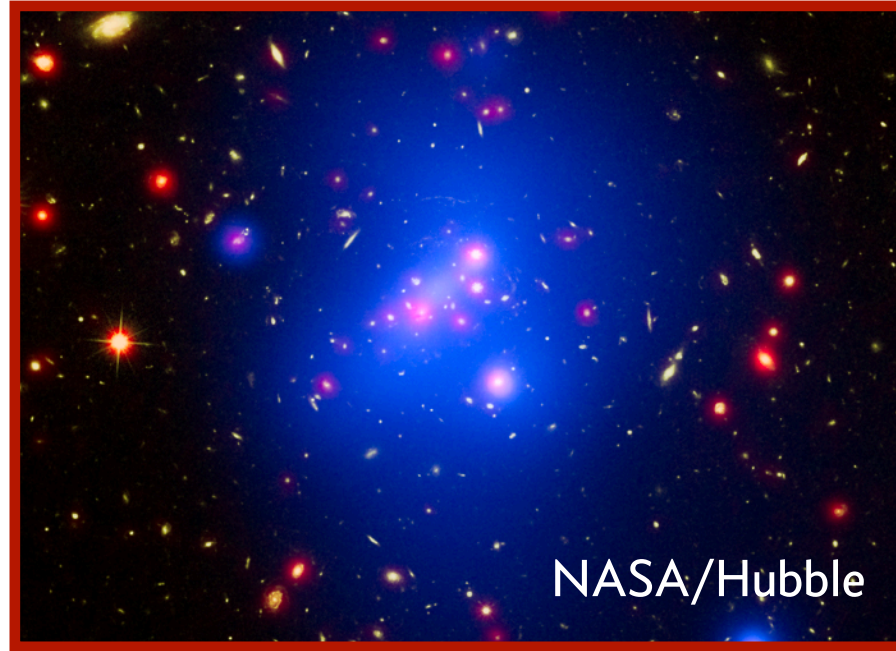
# Finding dark matter subhalos



*Dwarf galaxies*

*Galaxies and clusters*

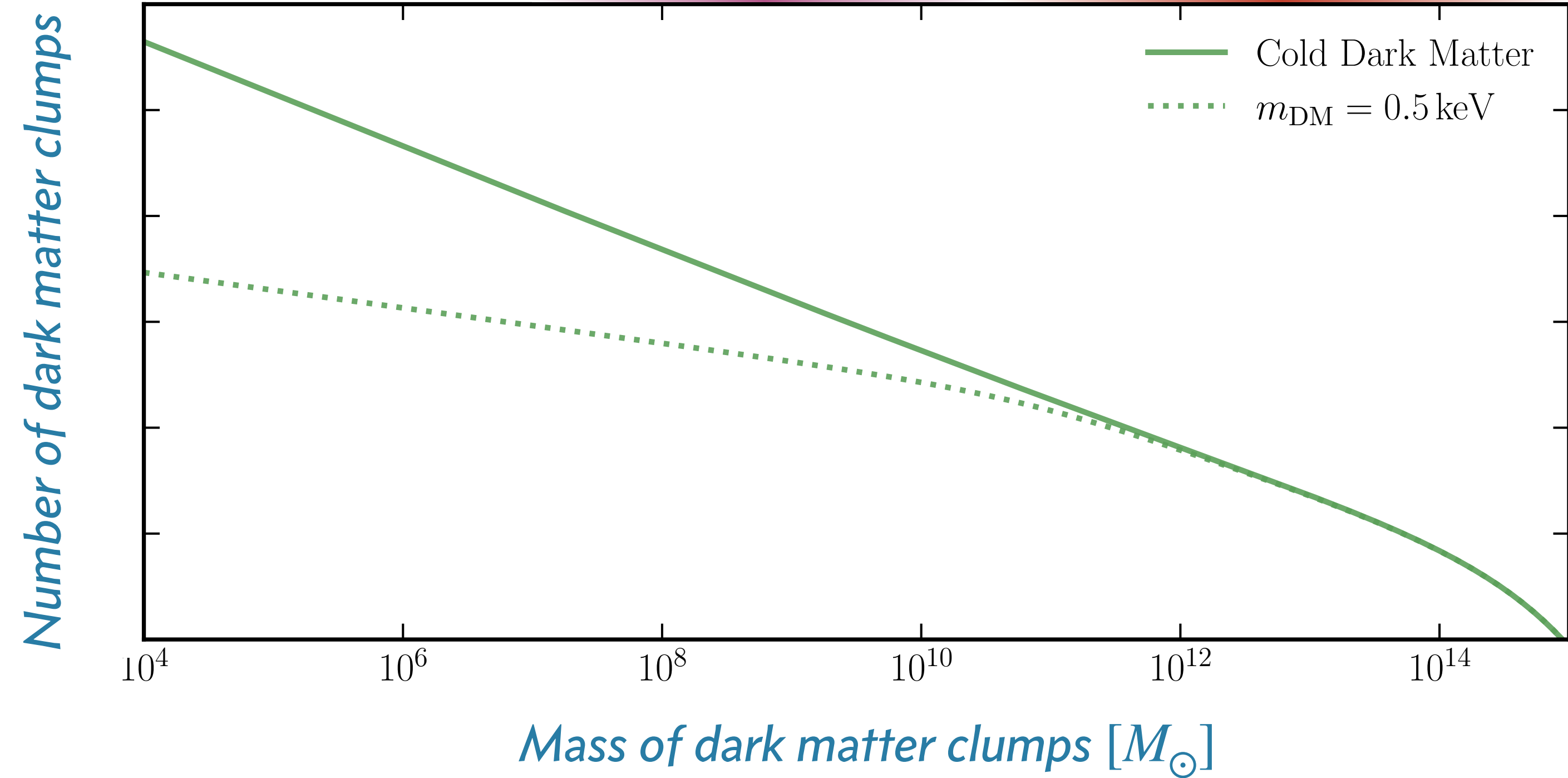
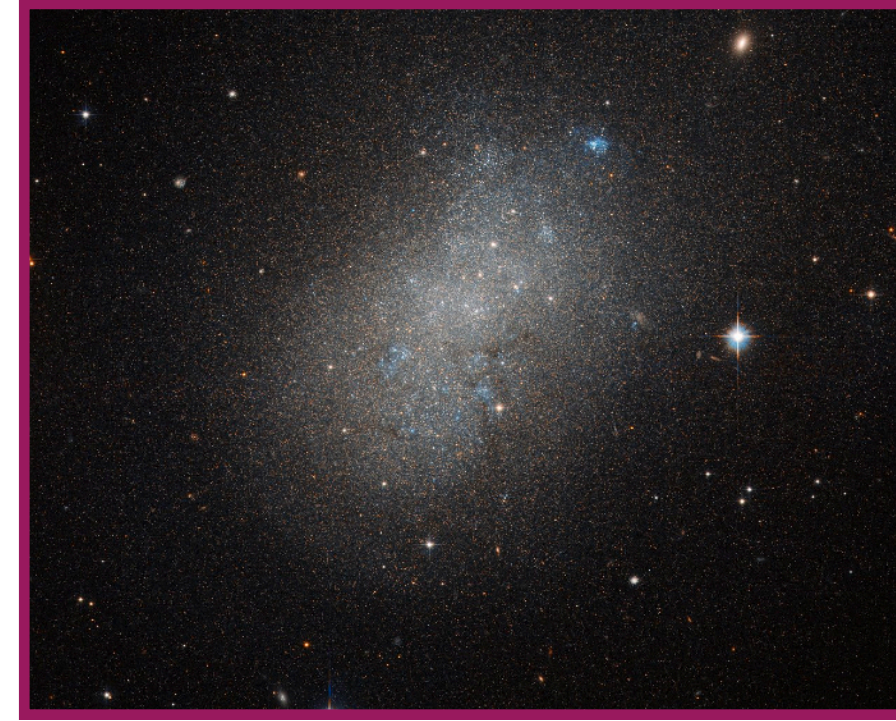
*Clusters*



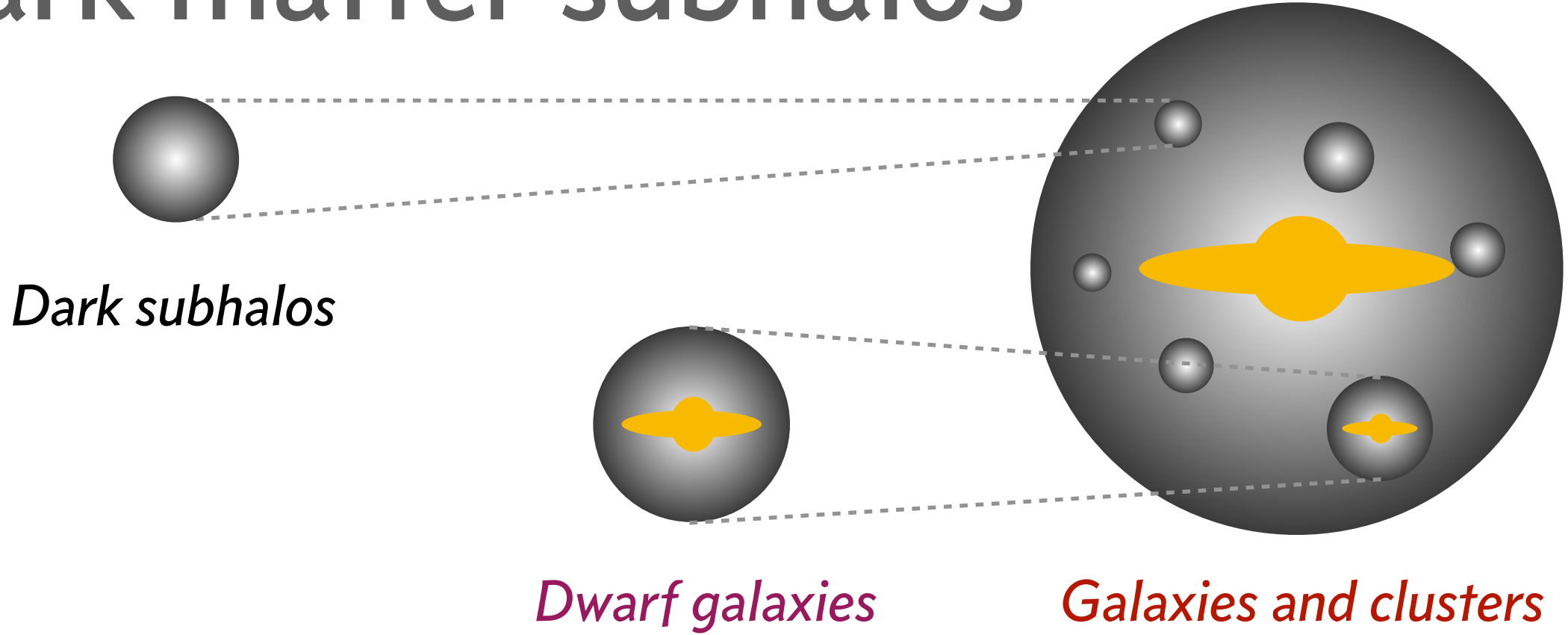
*Galaxies*



*Dwarf galaxies*



# Finding dark matter subhalos



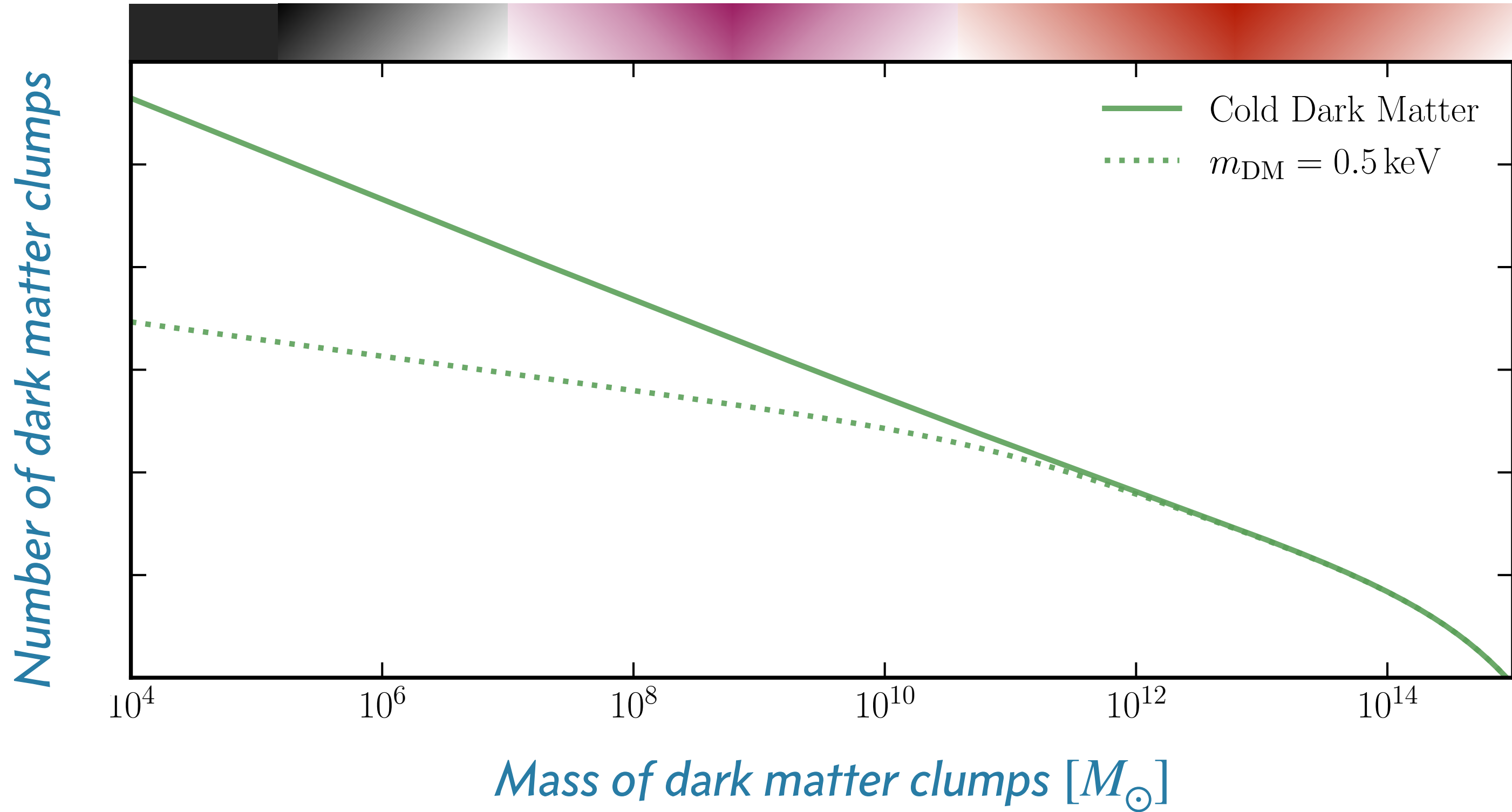
Clusters



Galaxies

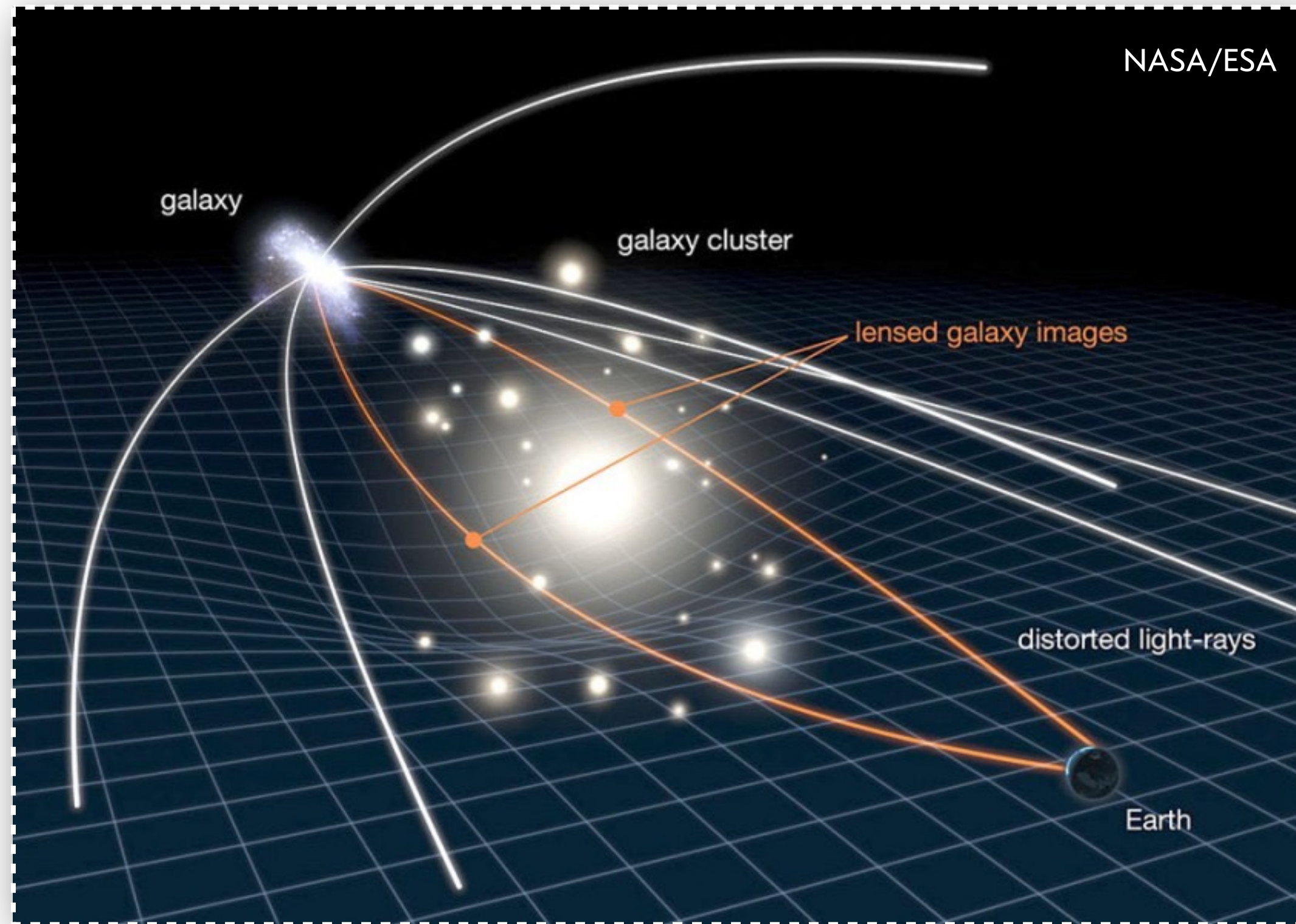


Dwarf galaxies



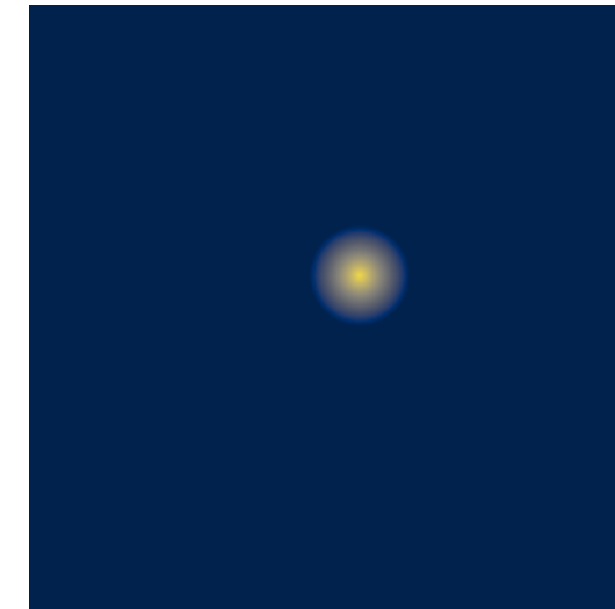


# Gravitational lensing



Strong lensing: extended arcs, multiple images

*Original source*



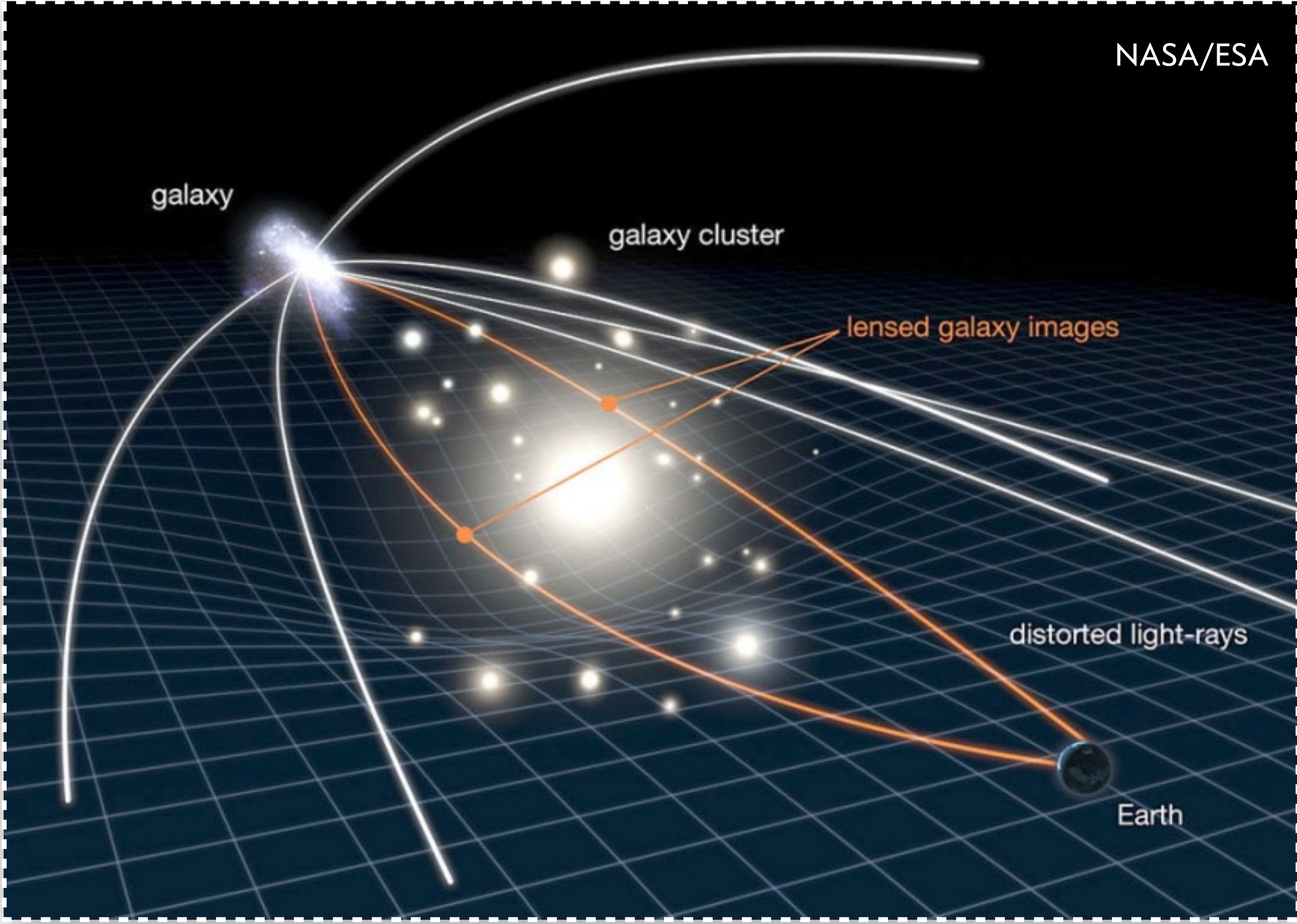
*Lensed source*



Intervening mass causes a shift in the *apparent position* of background light

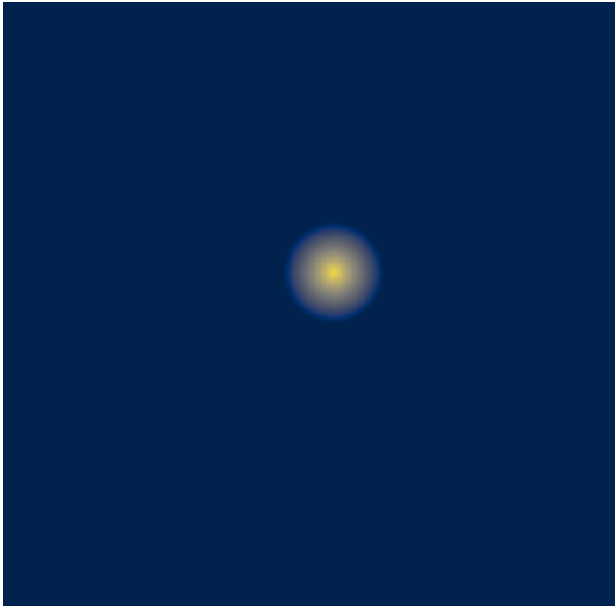
$$\vec{\Delta\theta} \sim \vec{\nabla}_\theta \Psi_G(\vec{r})$$

# Gravitational lensing

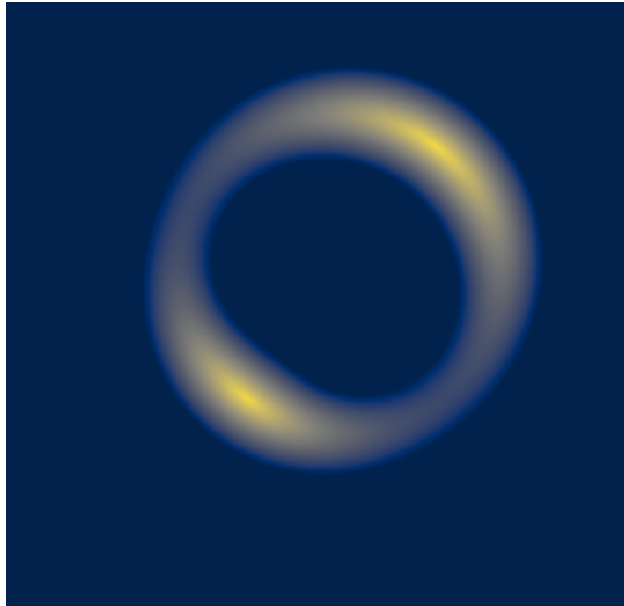


Strong lensing: extended arcs, multiple images

Original source

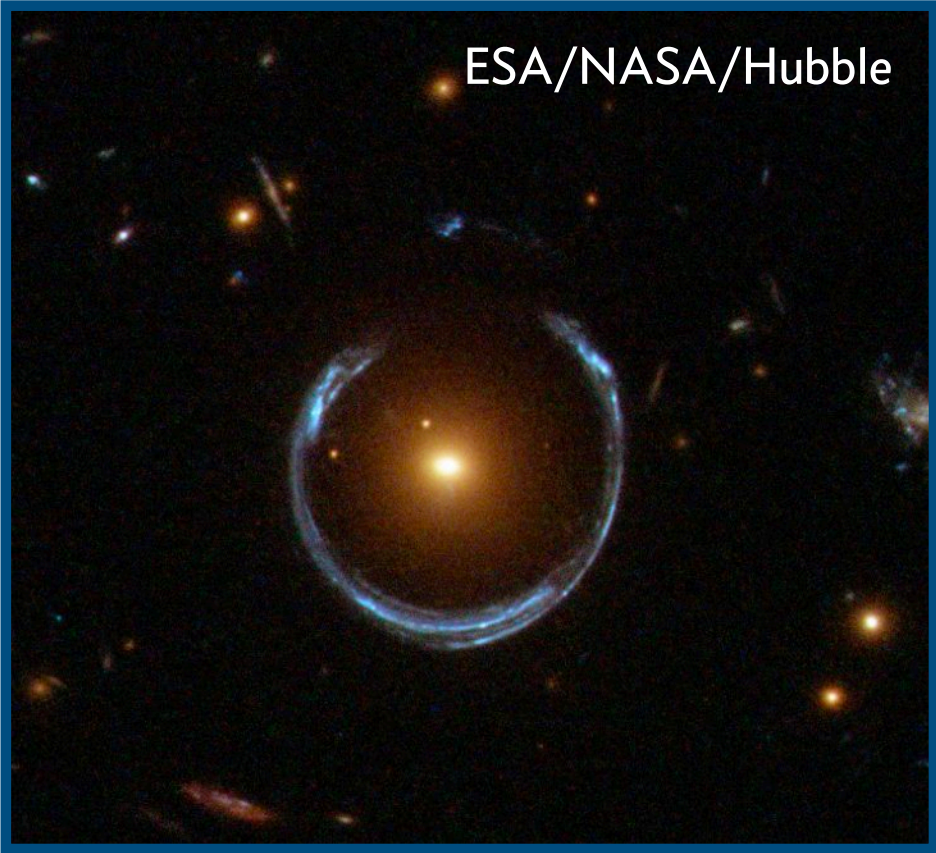


Lensed source

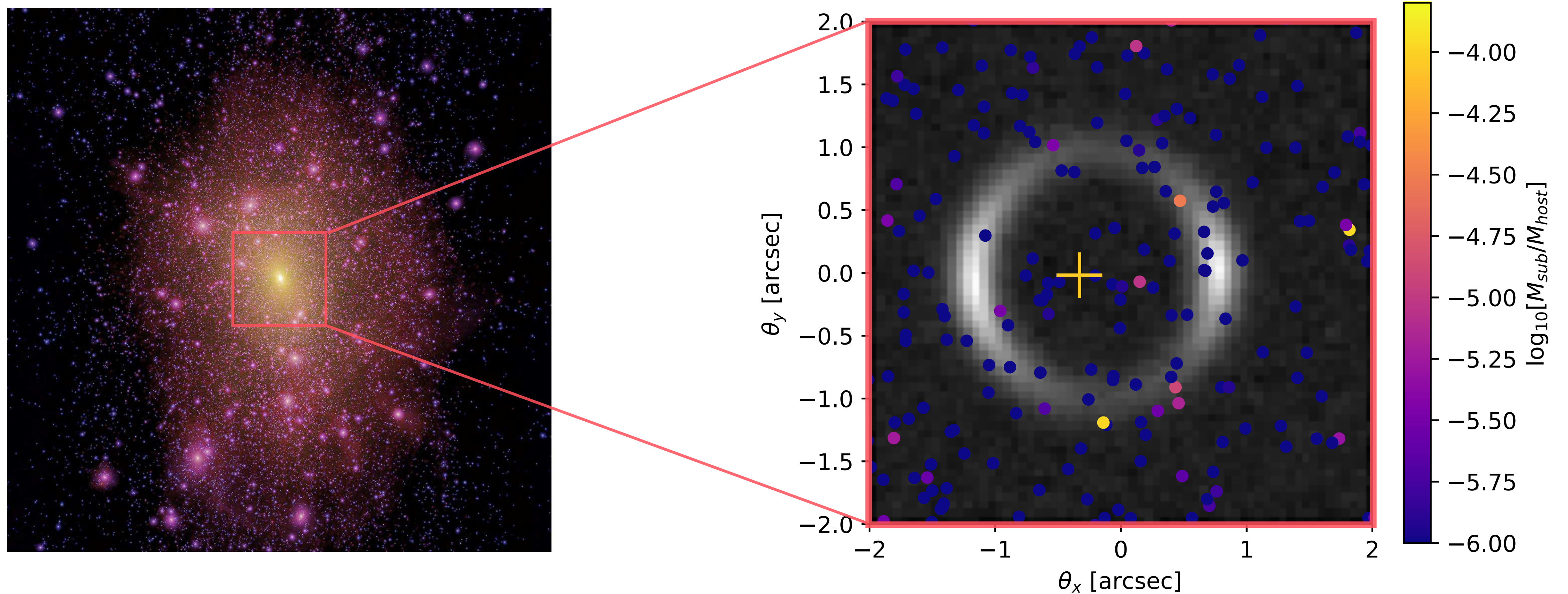


Intervening mass causes a shift in the *apparent position* of background light

$$\vec{\Delta\theta} \sim \vec{\nabla}_\theta \Psi_G(\vec{r})$$



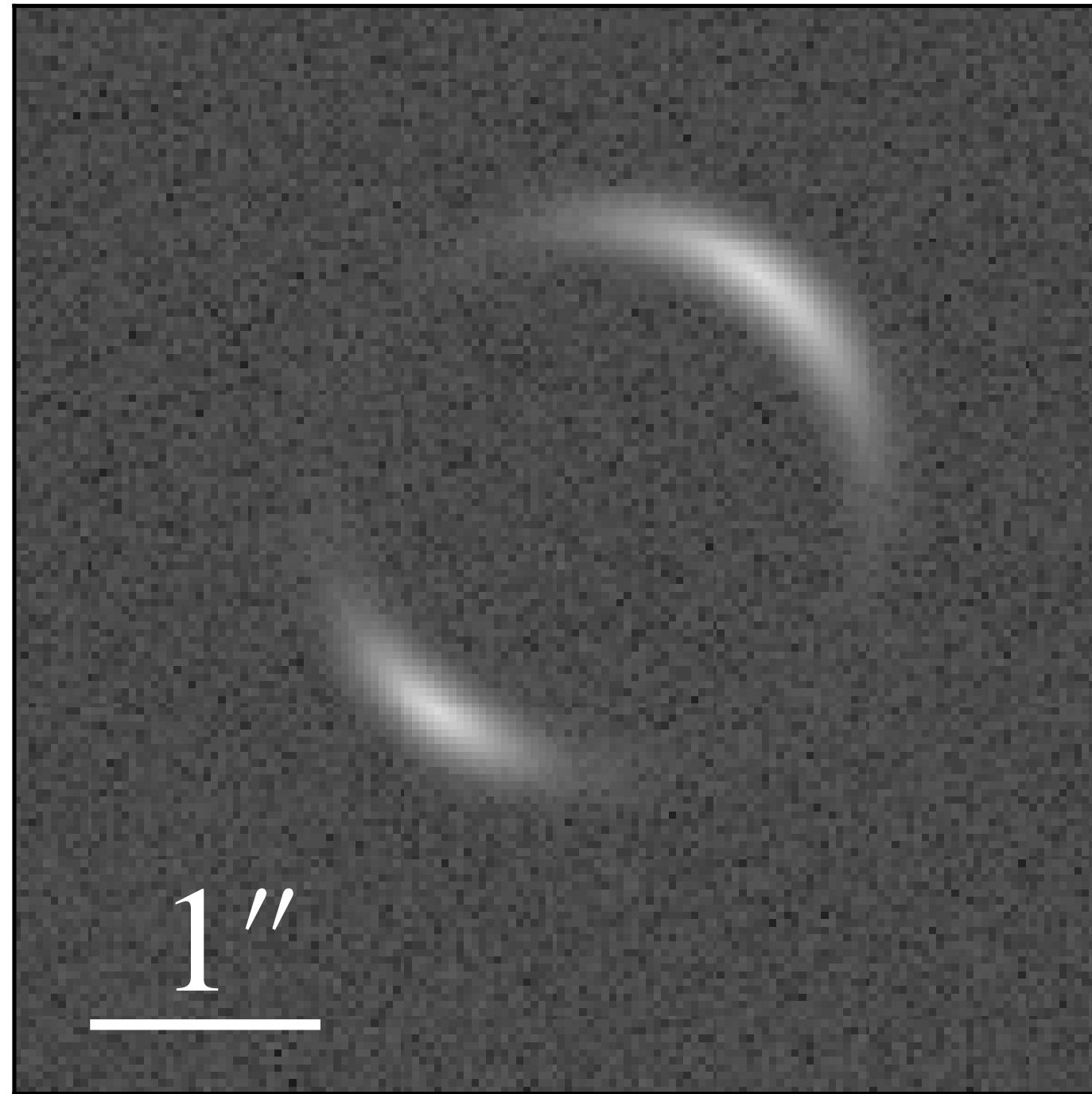
# Strong lensing: effect of substructure



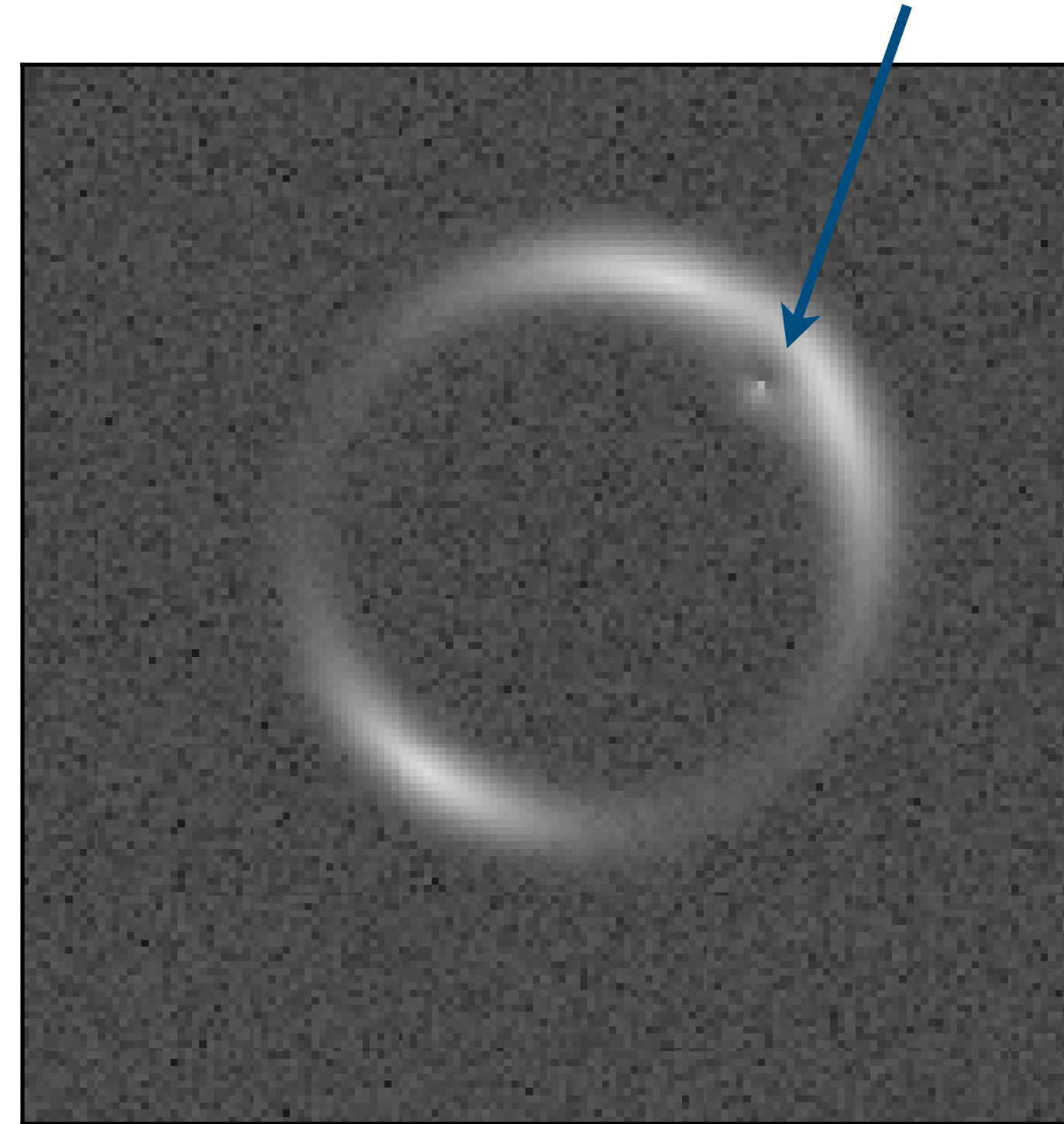
*Substructure causes percent-level shifts in strongly lensed image*

# Strong lensing: effect of substructure

Smooth halo only



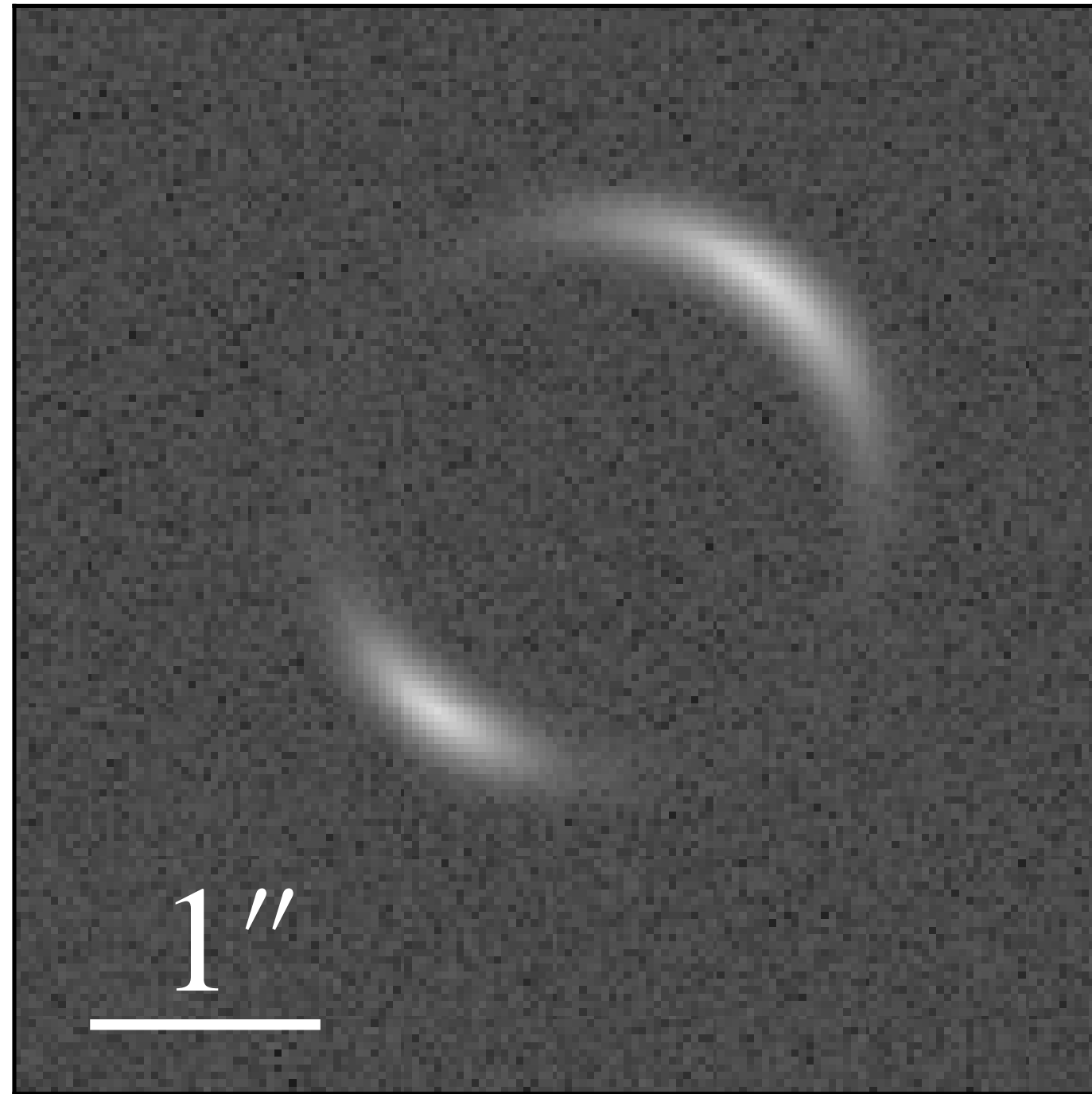
Smooth halo + *subhalo*



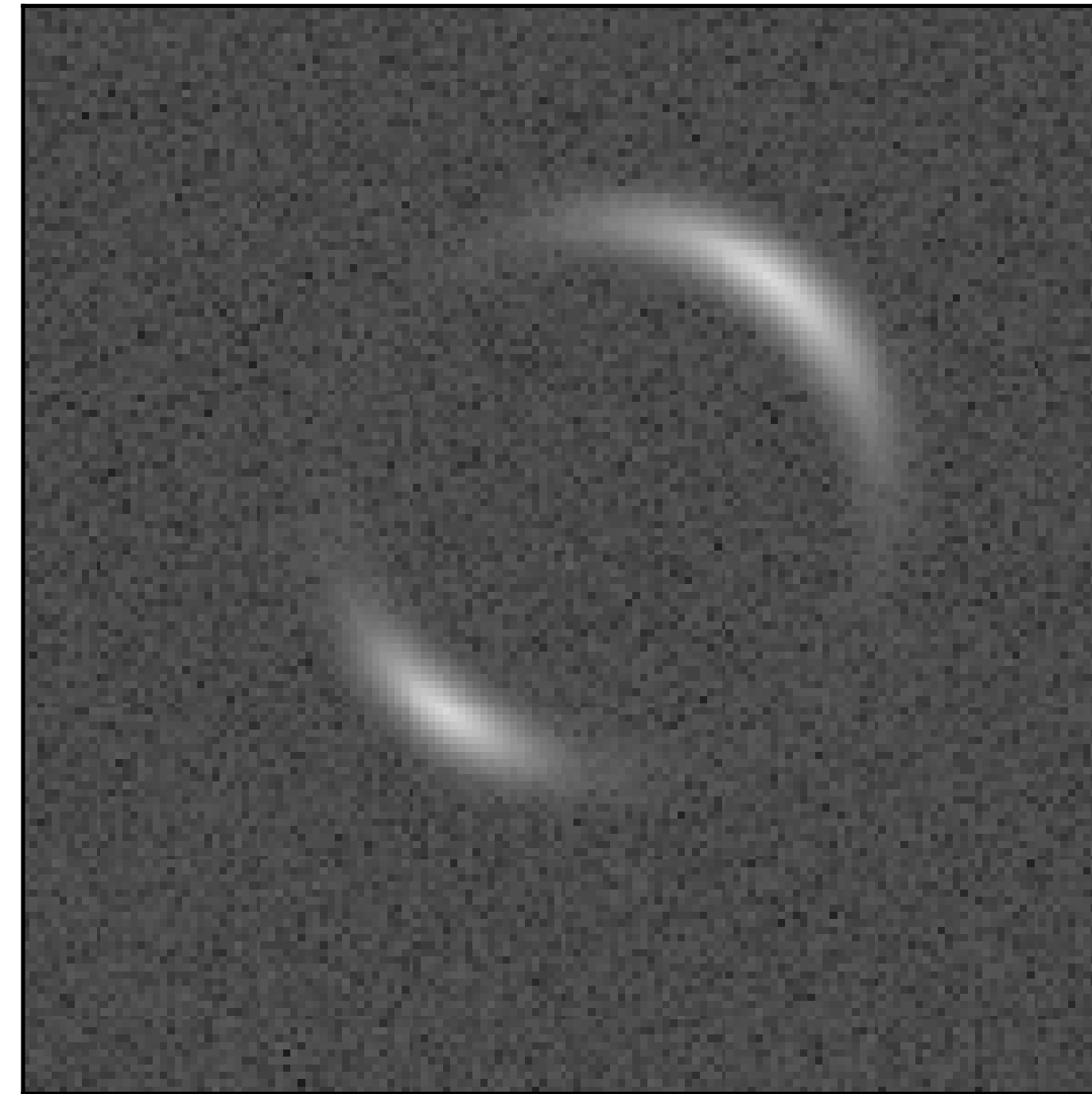
*Substructure perturbs lensing rings compared to only smooth halo*

# Strong lensing: effect of substructure *in reality*

Smooth halo only



Smooth halo + *subhalos*

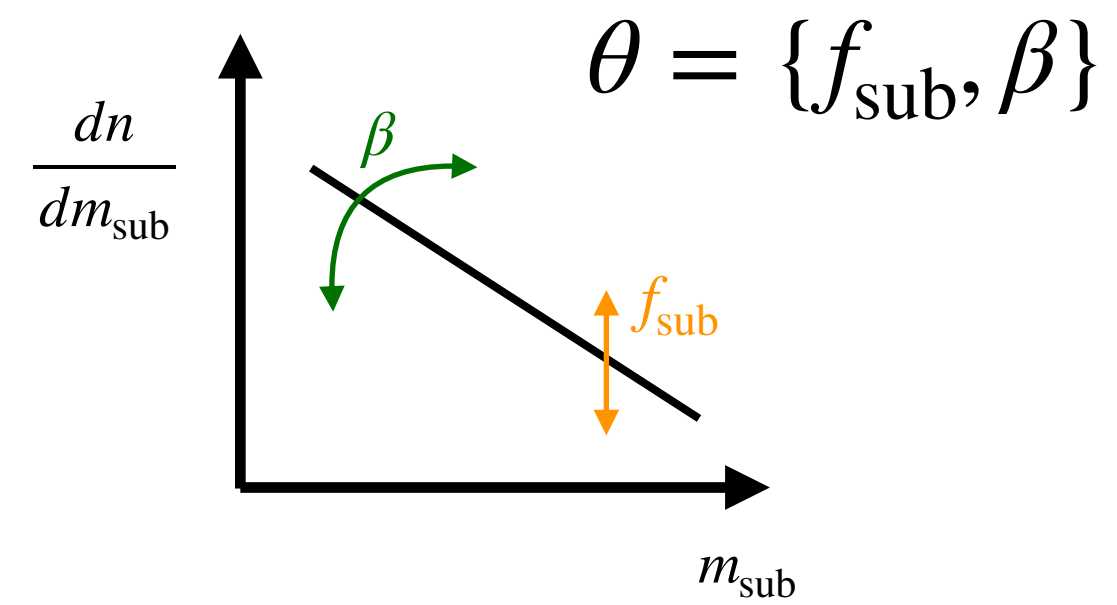


*Effect is very subtle for realistic dark matter substructure*

# Modeling substructure in strong lenses

## Parameters of interest

Subhalo population parameters

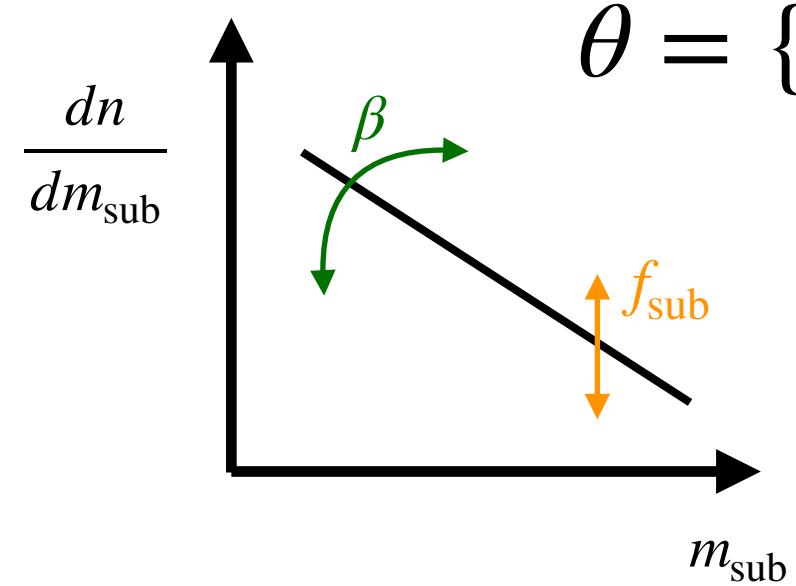


# Modeling substructure in strong lenses

## Parameters of interest

Subhalo population parameters

$$\theta = \{f_{\text{sub}}, \beta\}$$



## Latent variables

Source/host properties

$$z_{\text{src}}, z_{\text{lens}}$$

Subhalo properties

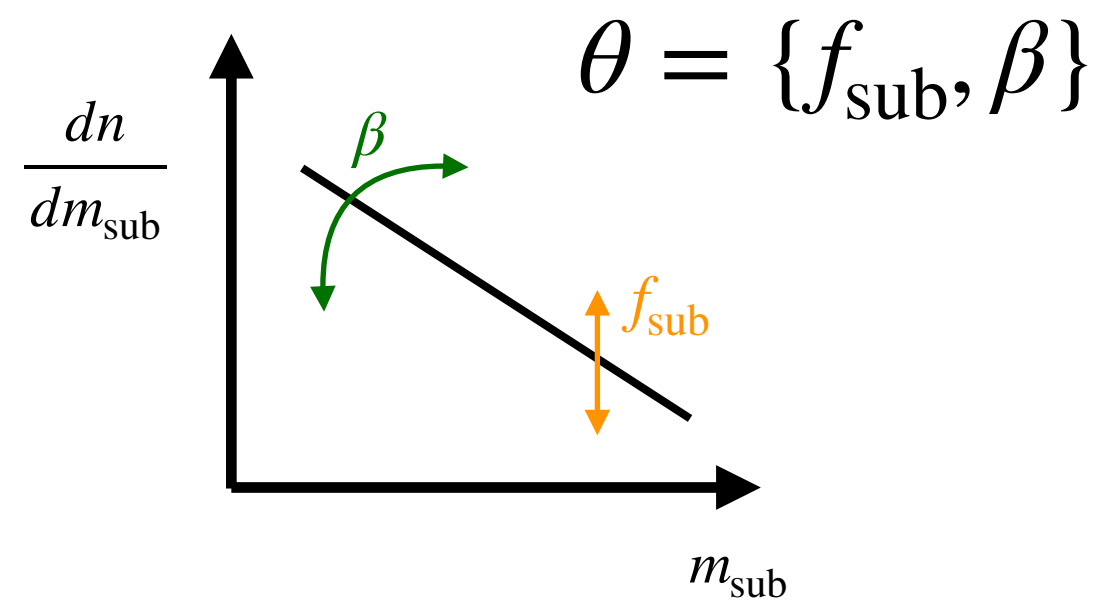
$$n_{\text{sub}}, \{z_{\text{sub}, i}\}$$

$$p(z_{\text{src}}) p(z_{\text{lens}}) p(n_{\text{sub}} | \theta) \prod_i^{n_{\text{sub}}} p(z_{\text{sub}, i} | \theta)$$

# Modeling substructure in strong lenses

## Parameters of interest

Subhalo population parameters



## Latent variables

Source/host properties

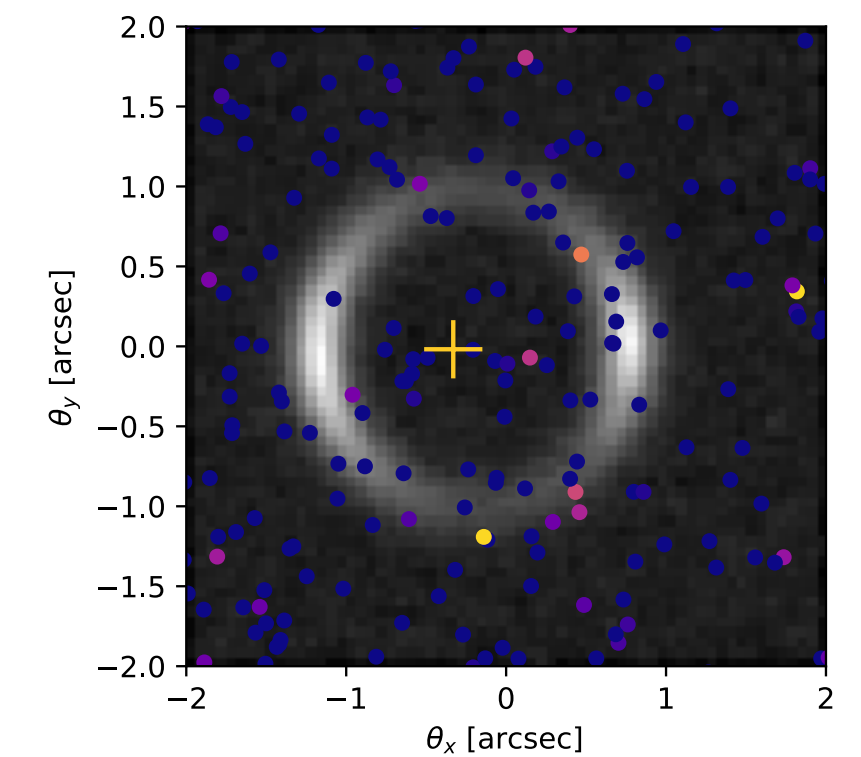
$z_{\text{src}}, z_{\text{lens}}$

Subhalo properties

$n_{\text{sub}}, \{z_{\text{sub}, i}\}$

## Observables

Lensing image  $x$



$$p(z_{\text{src}}) p(z_{\text{lens}}) p(n_{\text{sub}} | \theta) \prod_i^{n_{\text{sub}}} p(z_{\text{sub}, i} | \theta)$$

$$p(x | z_{\text{src}}, z_{\text{lens}}, \{z_{\text{sub}, i}\})$$

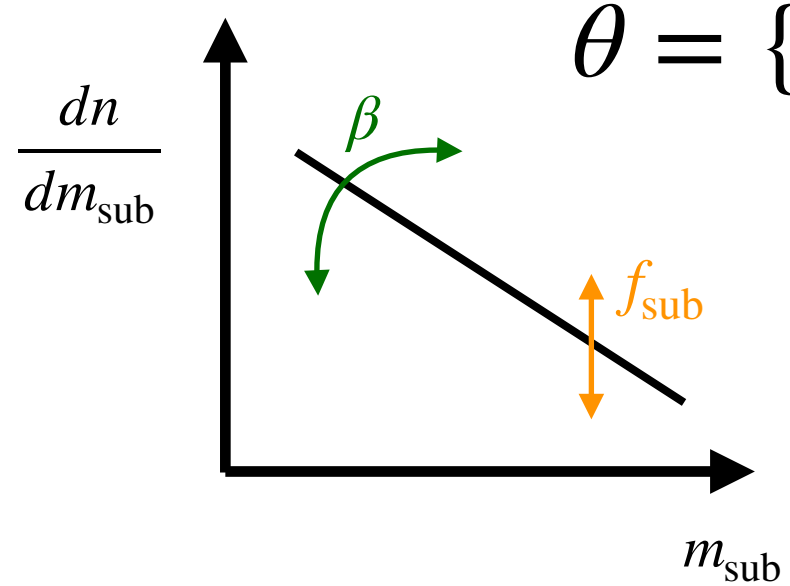


# Modeling substructure in strong lenses

## Parameters of interest

Subhalo population parameters

$$\theta = \{f_{\text{sub}}, \beta\}$$



## Latent variables

Source/host properties

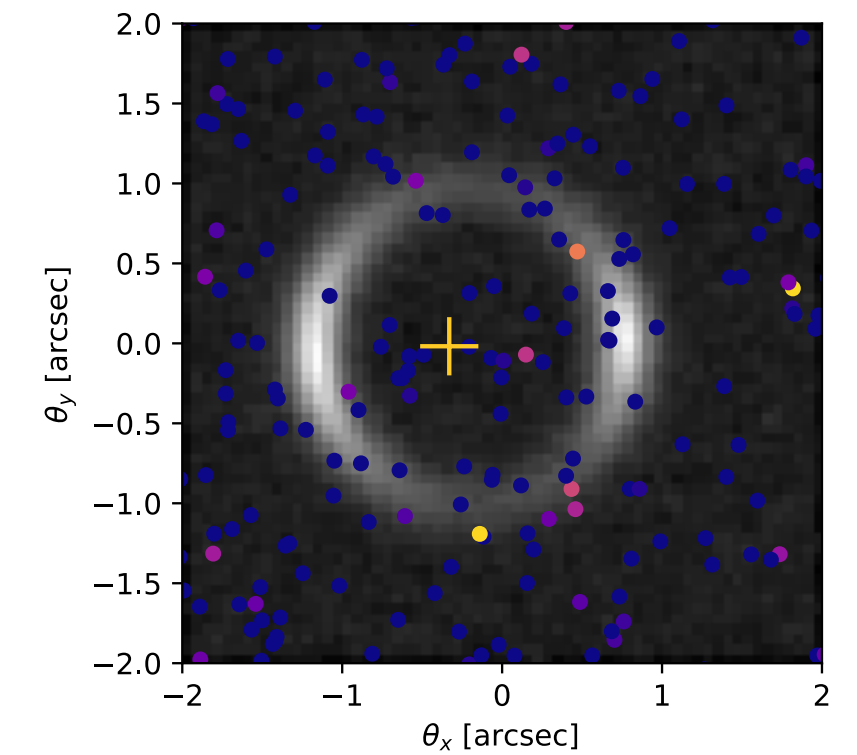
$$z_{\text{src}}, z_{\text{lens}}$$

Subhalo properties

$$n_{\text{sub}}, \{z_{\text{sub}, i}\}$$

## Observables

Lensing image  $x$



We can easily write a simulator to sample from

$$p(x, z | \theta) = p(z_{\text{src}}) p(z_{\text{lens}}) p(n_{\text{sub}} | \theta) \prod_i^{n_{\text{sub}}} p(z_{\text{sub}, i} | \theta)$$

$$p(x | z_{\text{src}}, z_{\text{lens}}, \{z_{\text{sub}, i}\})$$

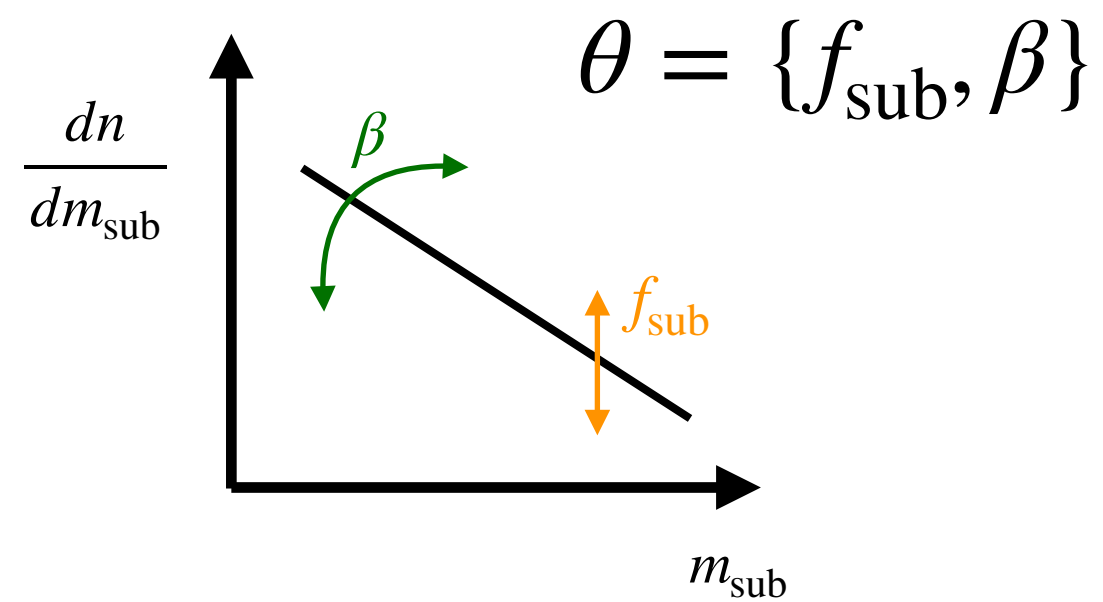
Prediction (Simulation)



# Modeling substructure in strong lenses

## Parameters of interest

Subhalo population parameters



## Latent variables

Source/host properties

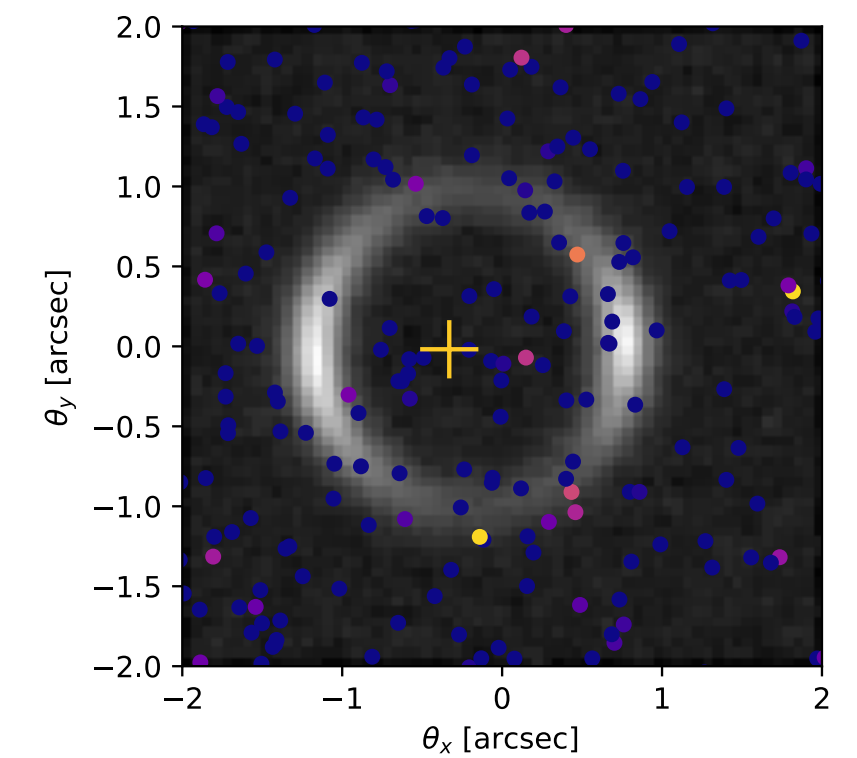
$z_{\text{src}}, z_{\text{lens}}$

Subhalo properties

$n_{\text{sub}}, \{z_{\text{sub}, i}\}$

## Observables

Lensing image  $x$



The key quantity for inference is the marginal likelihood

$$p(x | \theta) = \int dz_{\text{source}} \int dz_{\text{lens}} \sum_{n_{\text{sub}}} \int d^{n_{\text{sub}}} z_{\text{sub}} p(z_{\text{src}}) p(z_{\text{lens}}) p(n_{\text{sub}} | \theta) \prod_i^{n_{\text{sub}}} p(z_{\text{sub}, i} | \theta)$$

$$p(x | z_{\text{src}}, z_{\text{lens}}, \{z_{\text{sub}, i}\})$$

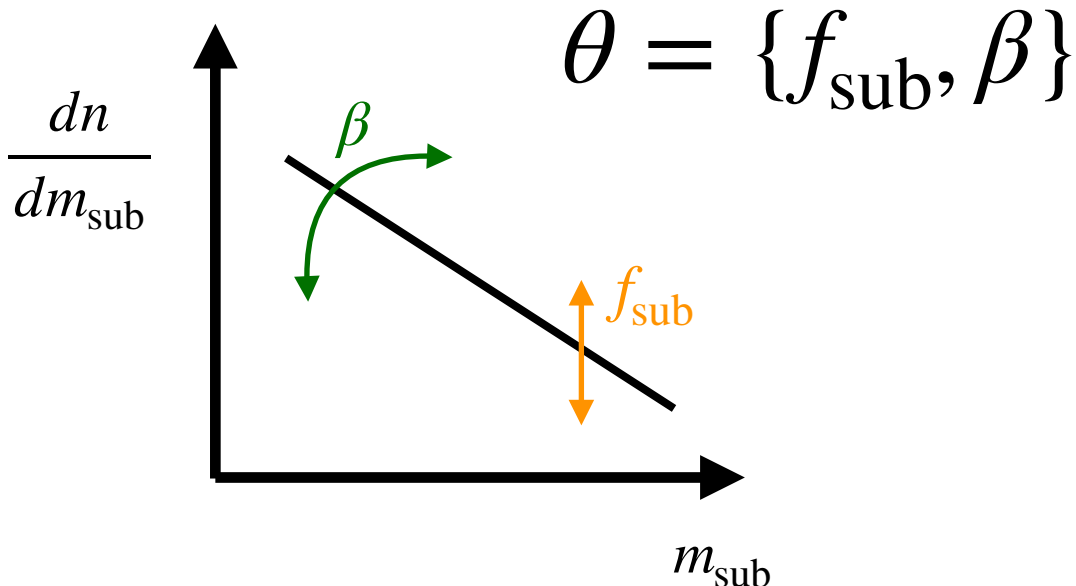
Inference



# Modeling substructure in strong lenses

## Parameters of interest

Subhalo population parameters



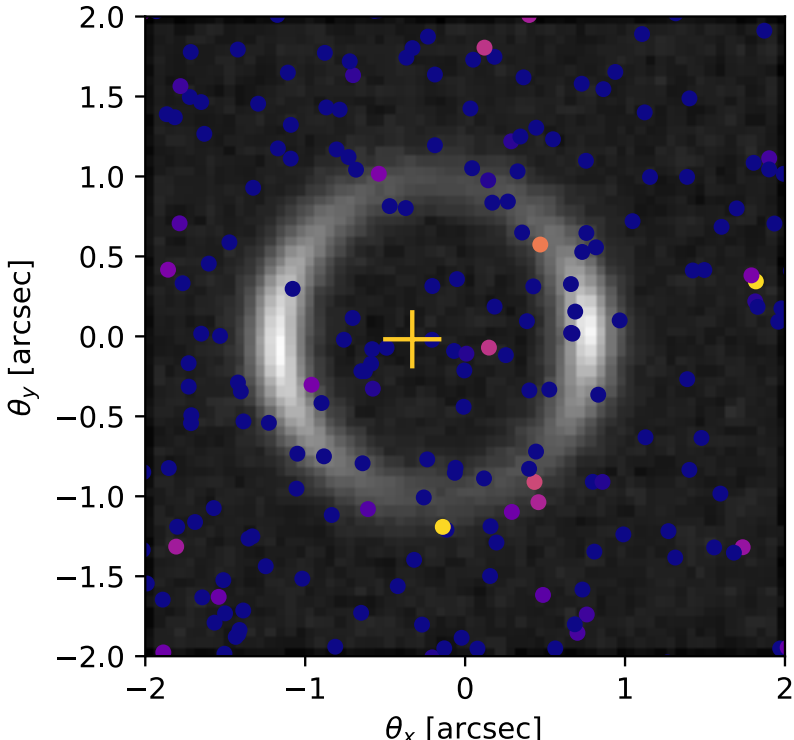
## Latent variables

Source/host properties      Subhalo properties

$z_{\text{src}}, z_{\text{lens}}$        $n_{\text{sub}}, \{z_{\text{sub}, i}\}$

## Observables

Lensing image  $x$



The key quantity for inference is the marginal likelihood

$$p(x | \theta) = \int dz_{\text{source}} \int dz_{\text{lens}} \sum_{n_{\text{sub}}} \int d^{n_{\text{sub}}} z_{\text{sub}} p(z_{\text{src}}) p(z_{\text{lens}}) p(n_{\text{sub}} | \theta) \prod_i^{n_{\text{sub}}} p(z_{\text{sub}, i} | \theta) p(x | z_{\text{src}}, z_{\text{lens}}, \{z_{\text{sub}, i}\})$$

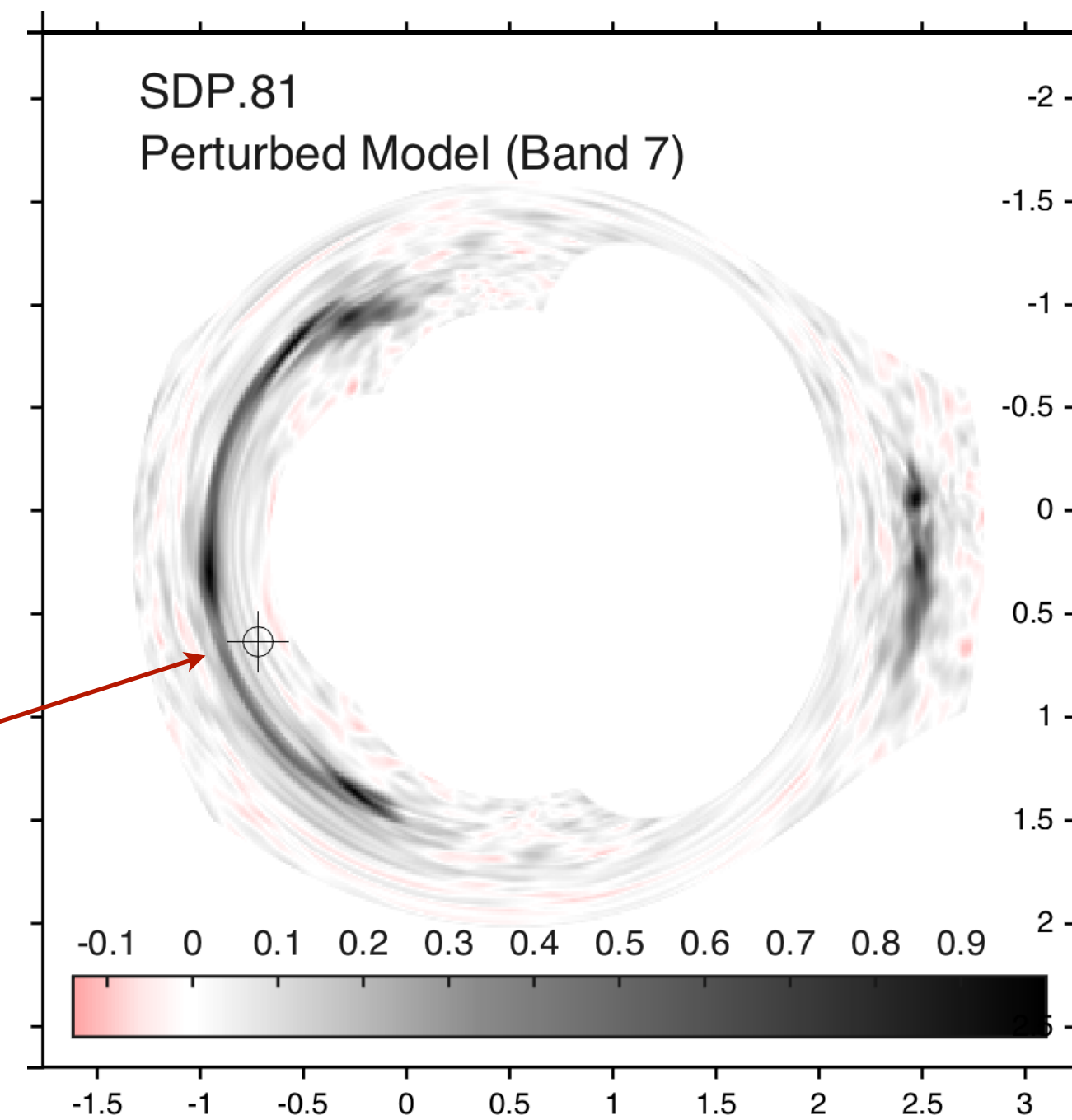
Integral over the huge latent space is intractable—*challenge for inference*

Inference



# Searches for individual subhalos

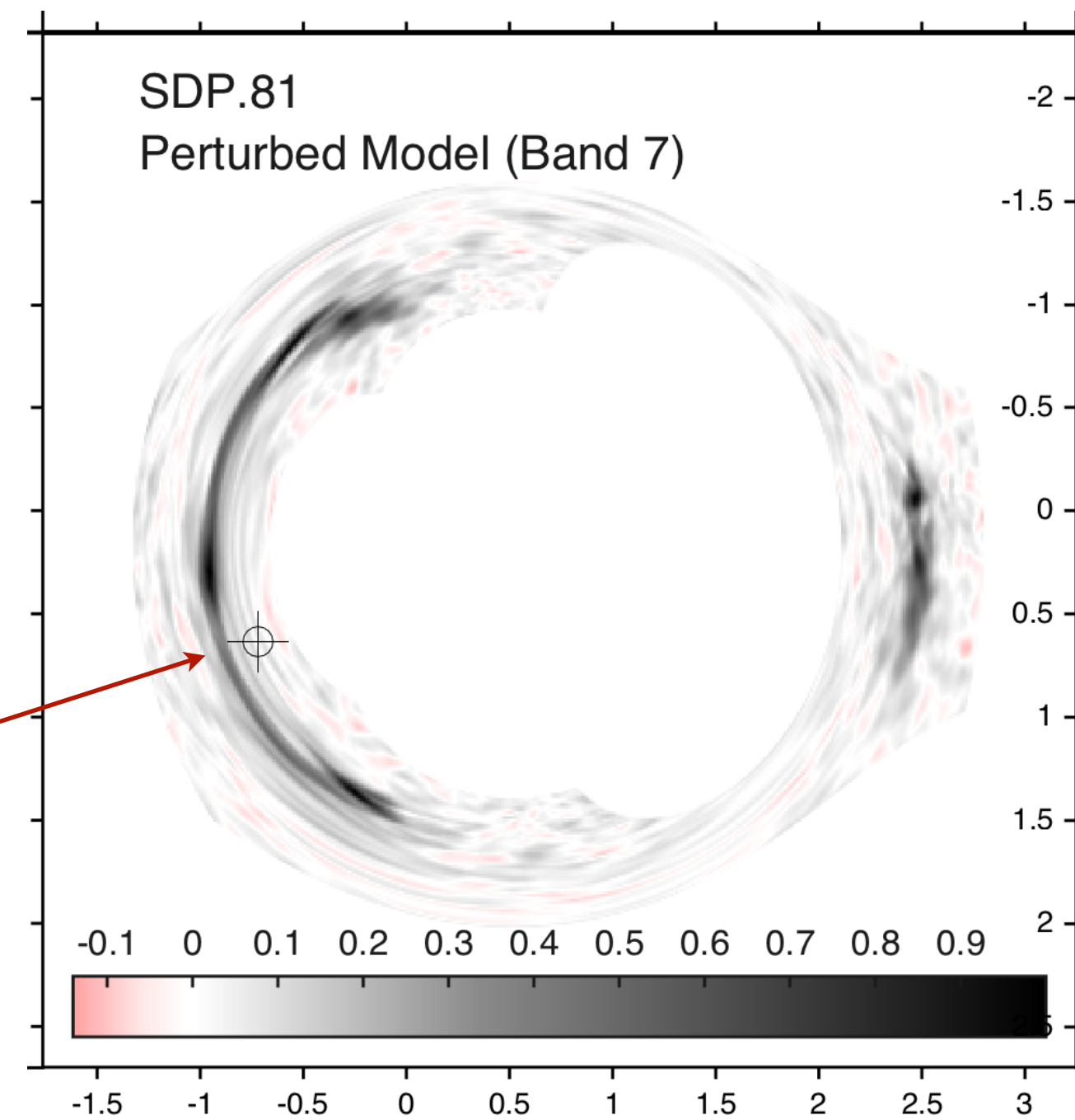
Constraints on **subhalo mass function** from detections of **individual subhalos**



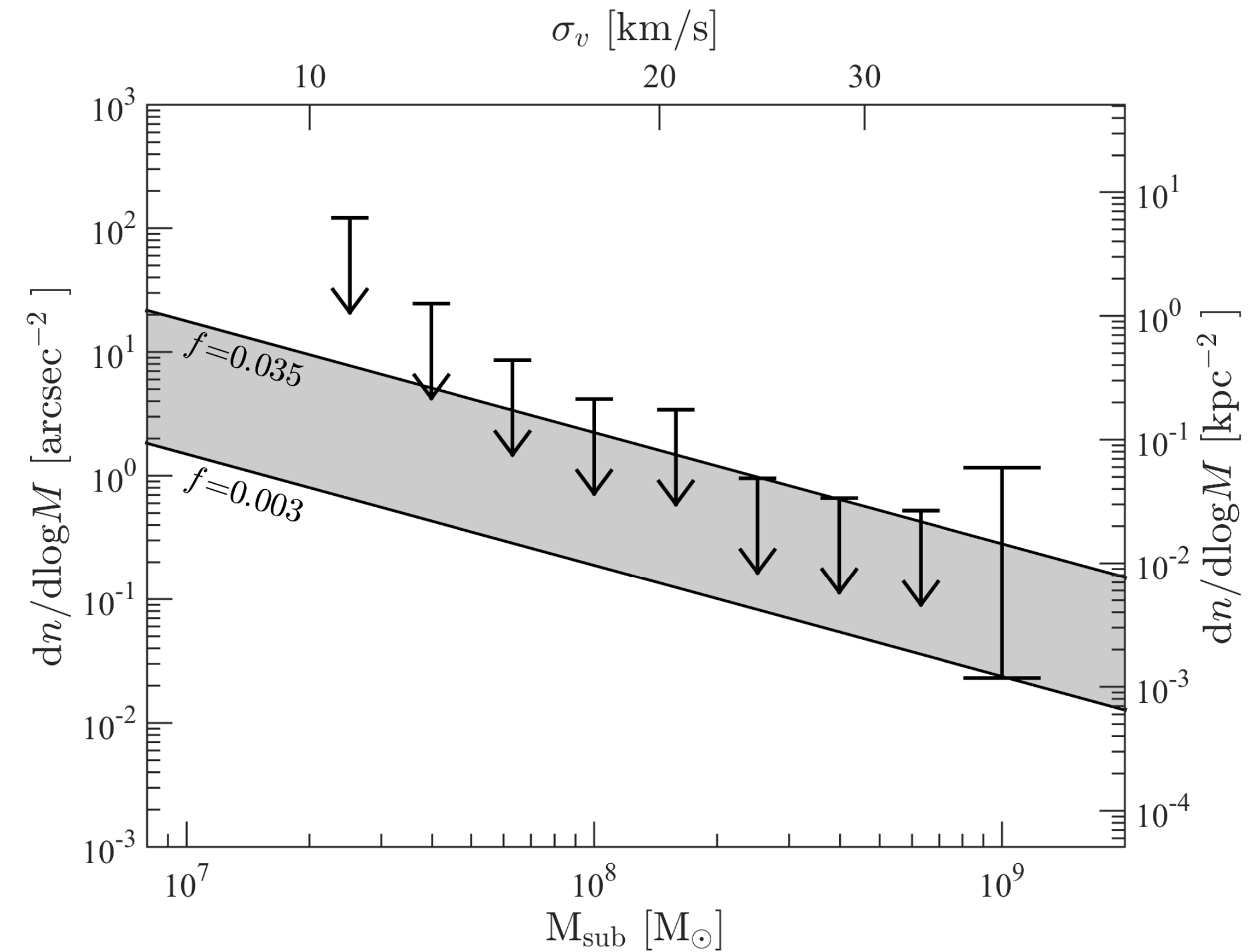
*Single  
detected  
subhalo*

# Searches for individual subhalos

Constraints on **subhalo mass function** from detections of **individual subhalos**



Single  
detected  
subhalo



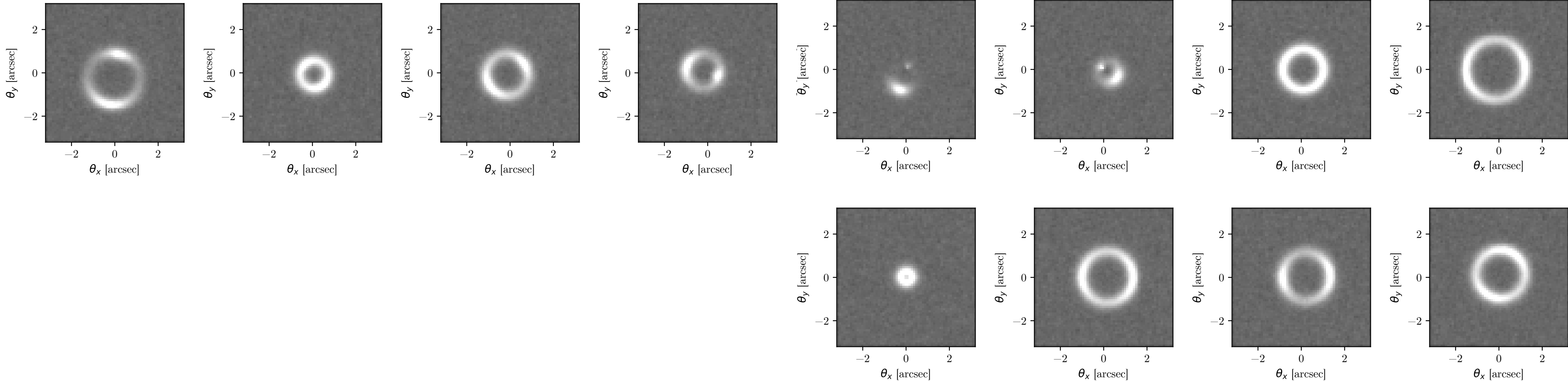
*Sensitive to individual, more massive subhalos*

# Goal: scalable inference of substructure population

$\mathcal{O}(10,000)$

Future observatories like the *Euclid* are expected to deliver large samples of galaxy-galaxy lenses

Collett [ApJ 2015]

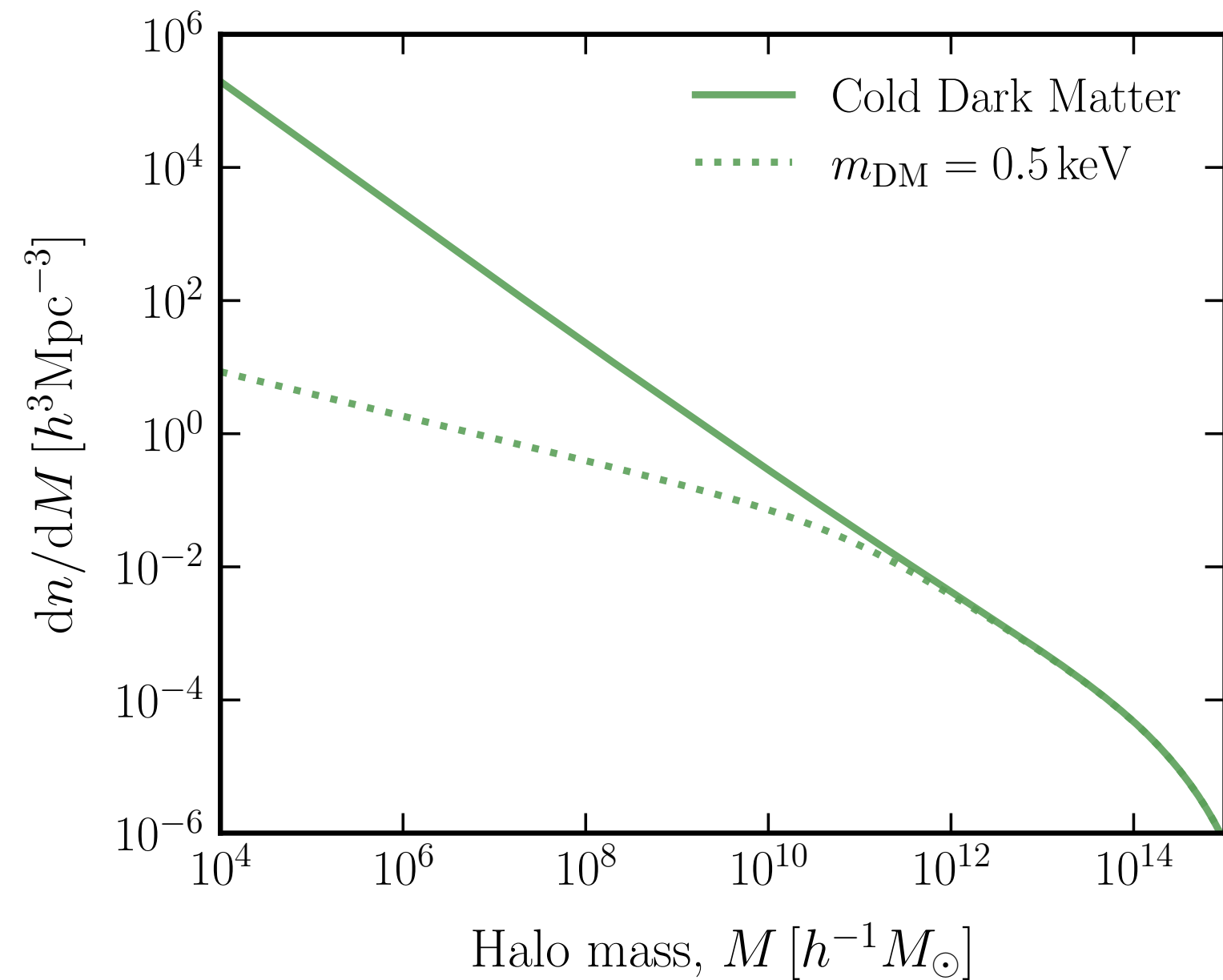
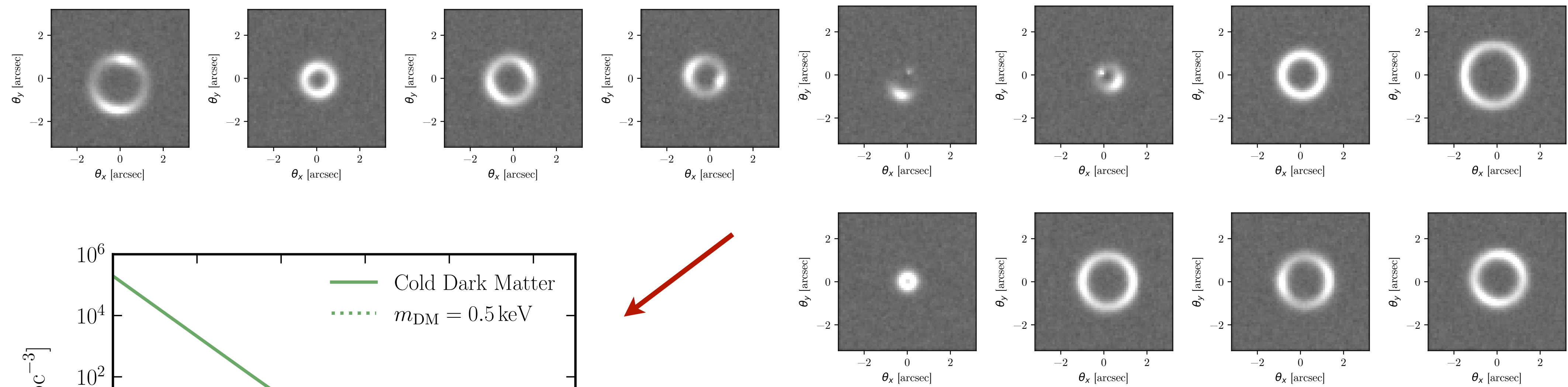


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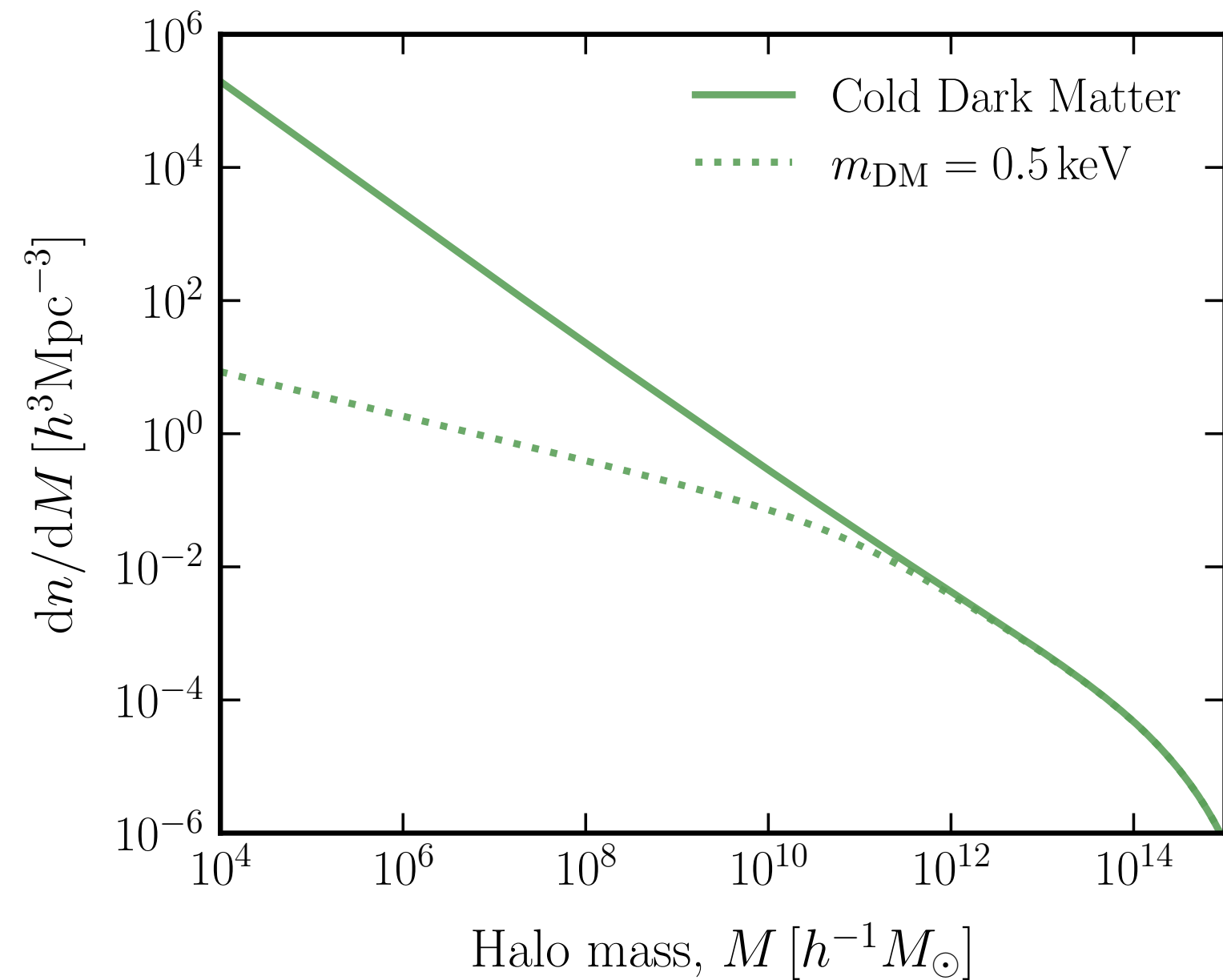
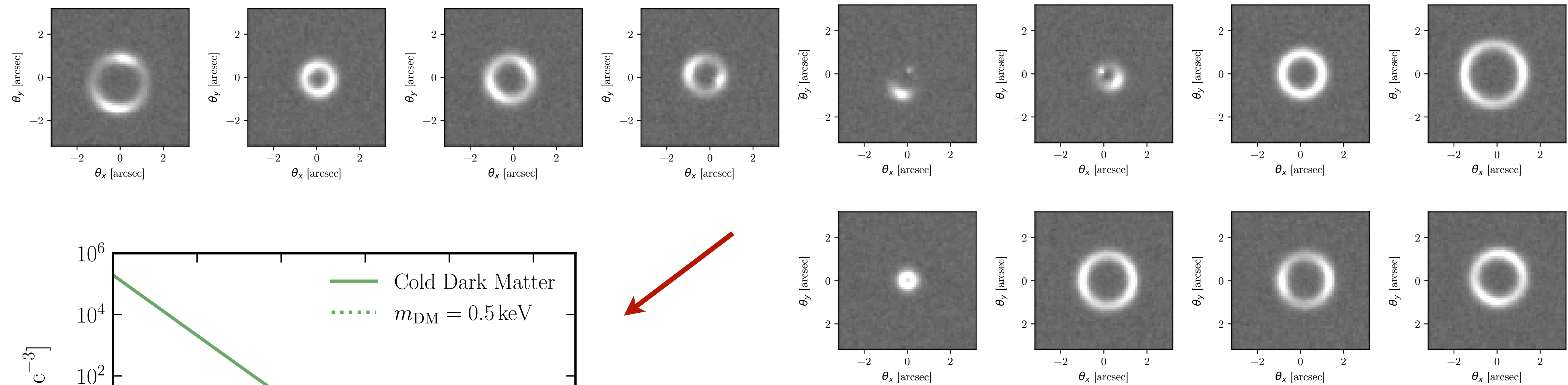


# Goal: scalable inference of substructure population

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Future observatories like the *Euclid* are expected to deliver large samples of galaxy-galaxy lenses

Collett [ApJ 2015]

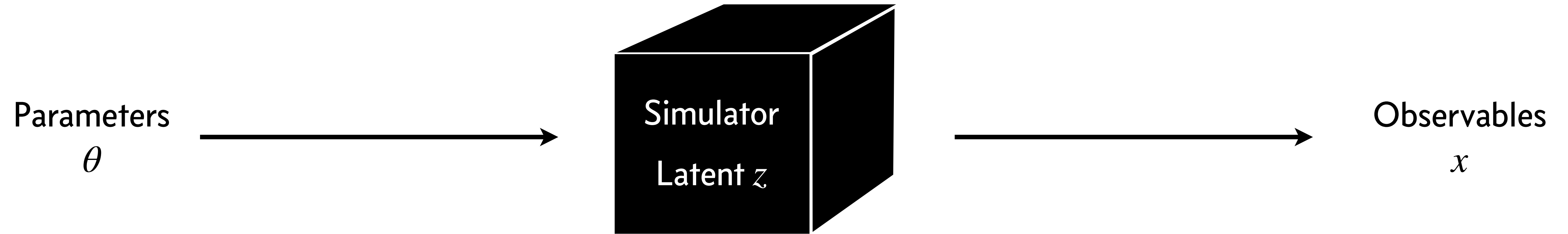


- Capture maximum information from high-dim data
- Scalable to a large sample of lenses
- Can deal with a large number of nuisance/latent parameters



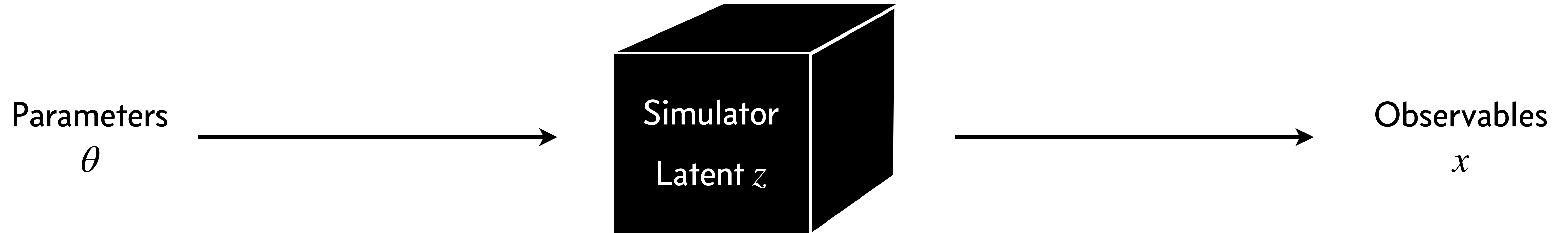
# Simulation-based inference (SBI)

Slides inspiration: Johann Brehmer



# Simulation-based inference (SBI)

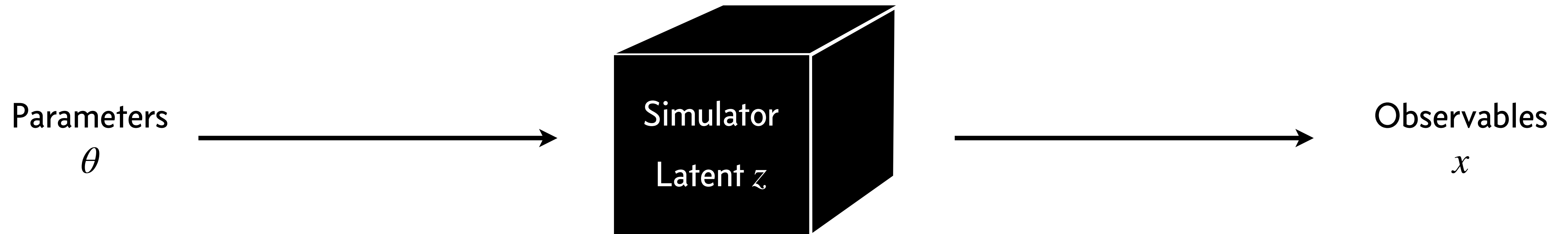
Slides inspiration: Johann Brehmer



Prediction:

- Well-motivated mechanistic, causal model
- Simulator can generate samples  $x \sim p(x | \theta)$

# Simulation-based inference (SBI)



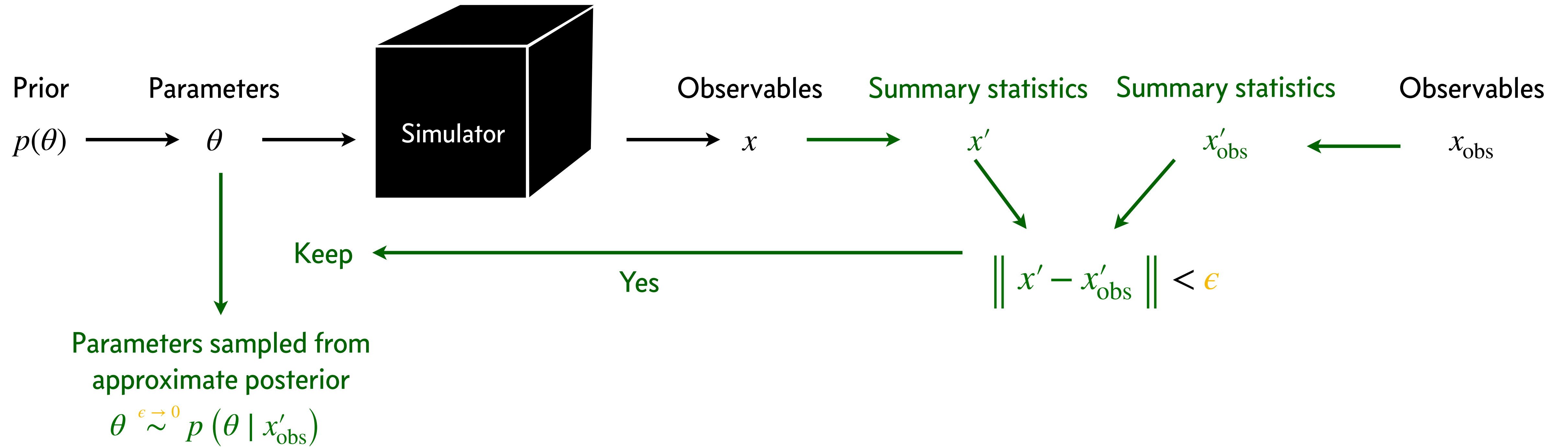
Prediction:

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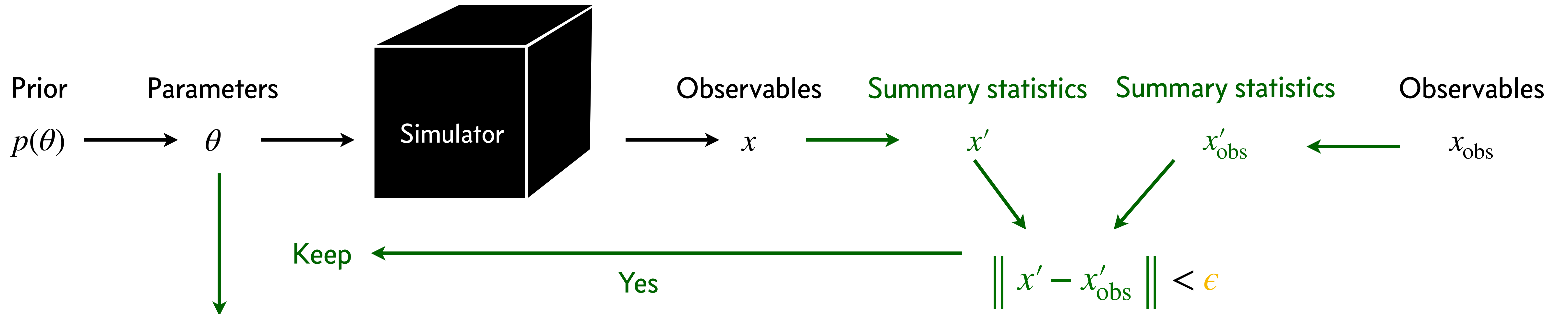
Inference:

- Likelihood  $p(x | \theta) = \int dz p(x, z | \theta)$  is intractable
- *Inference is challenging*

# “Traditional” SBI: *Approximate Bayesian Computation*

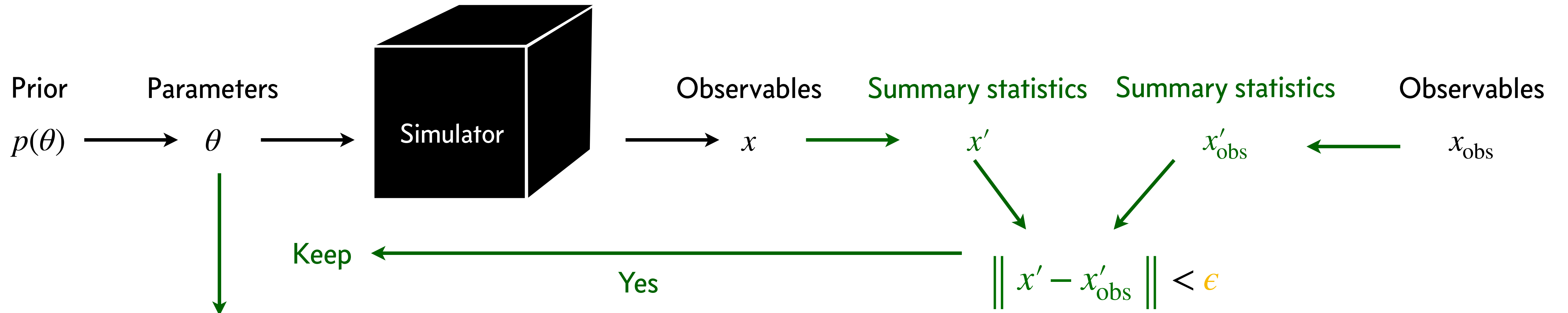


# “Traditional” SBI: *Approximate Bayesian Computation*



- How to choose  $x'$ ? *Curse of dimensionality*
- Loss of information
- How to compare with data? *Likelihood may not be available*
- Need to re-run pipeline for new data or new prior

# “Traditional” SBI: *Approximate Bayesian Computation*



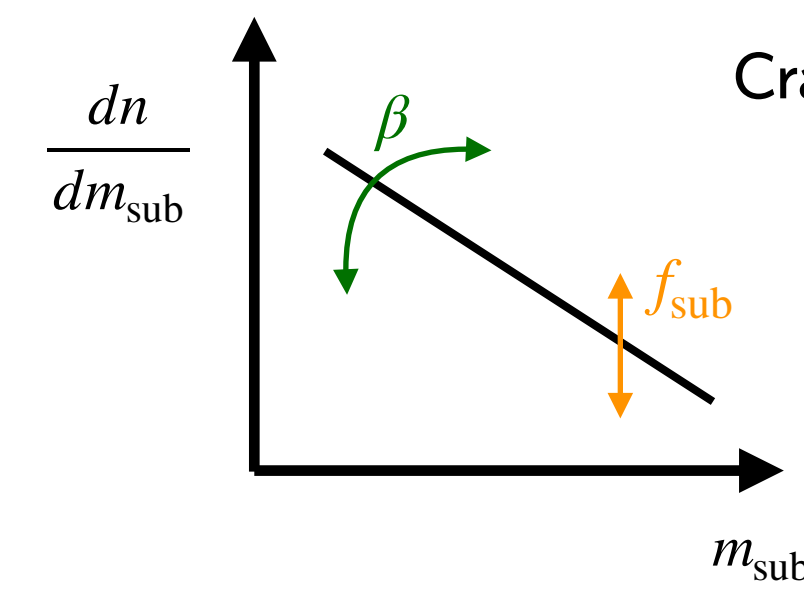
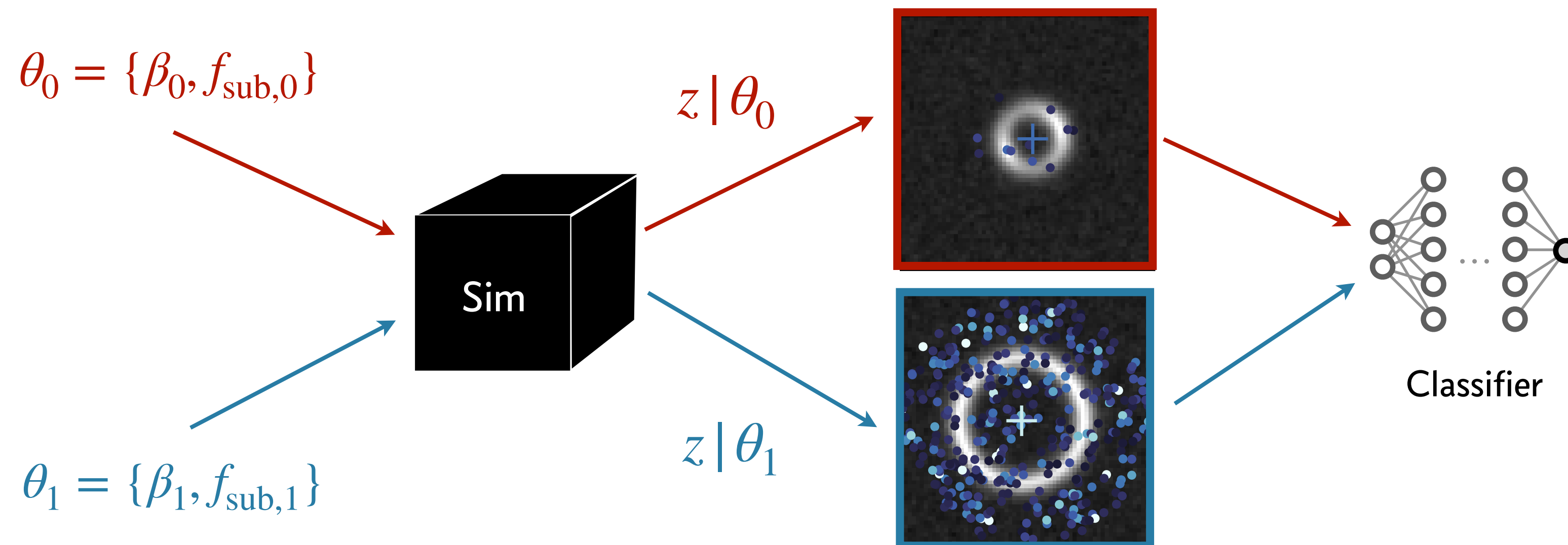
Parameters sampled from approximate posterior

$$\theta \stackrel{\epsilon \rightarrow 0}{\sim} p(\theta | x'_{\text{obs}})$$

- How to choose  $x'$ ? *Curse of dimensionality*
  - Loss of information
  - How to compare with data? *Likelihood may not be available*
  - Need to re-run pipeline for new data or new prior
- Lots of recent progress using ML***  
 see Cranmer, Brehmer, Louppe [PNAS 2020] for a review

# The likelihood-ratio trick

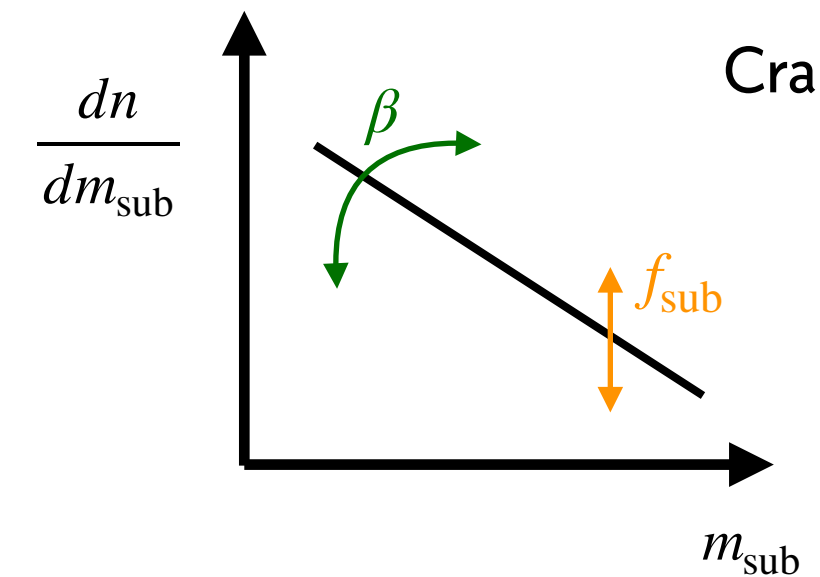
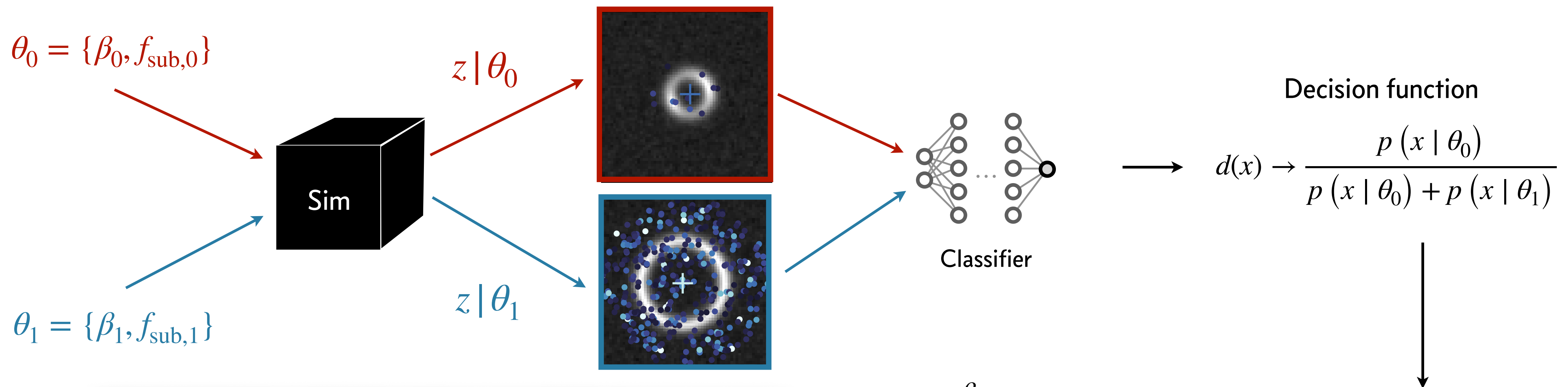
We can train a classifier between two sets of simulated samples



Cranmer, Pavez, Louppe [arXiv 2015]  
Brehmer et al [PRL, PRD 2018]  
Stoye et al [arXiv 2018]  
Hermans et al [ICML 2020]  
+ others

# The likelihood-ratio trick

We can train a classifier between two sets of simulated samples



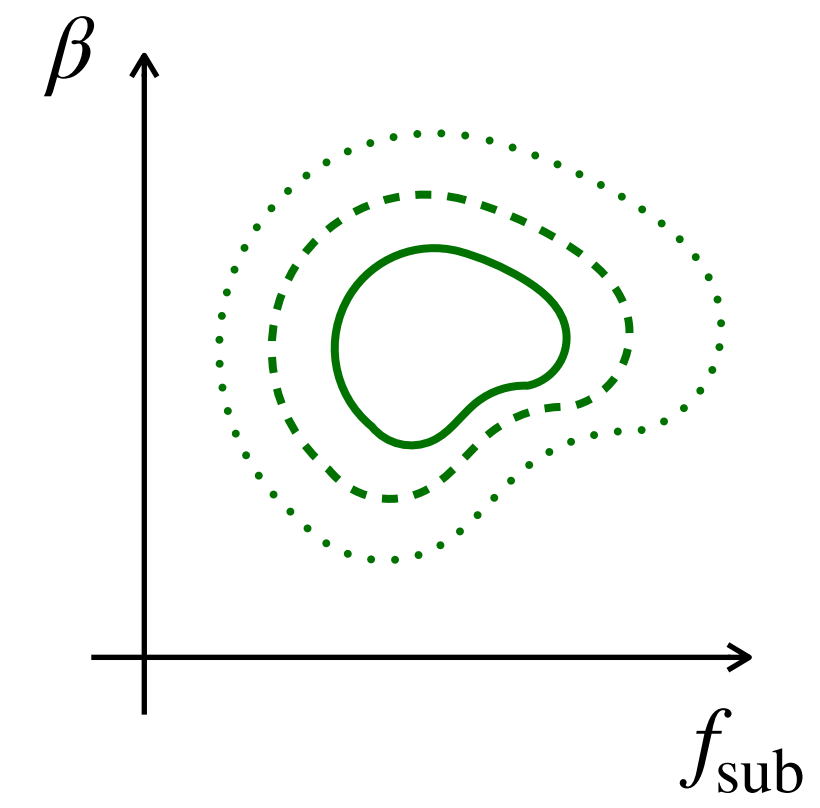
Cranmer, Pavez, Louppe [arXiv 2015]  
 Brehmer et al [PRL, PRD 2018]  
 Stoye et al [arXiv 2018]  
 Hermans et al [ICML 2020]  
 + others

*IX. On the Problem of the most Efficient Tests of Statistical Hypotheses.*

By J. NEYMAN, *Nencki Institute, Soc. Sci. Lit. Varsoviensis, and Lecturer at the Central College of Agriculture, Warsaw,* and E. S. PEARSON, *Department of Applied Statistics, University College, London.*

(Communicated by K. PEARSON, F.R.S.)

(Received August 31, 1932.—Read November 10, 1932.)



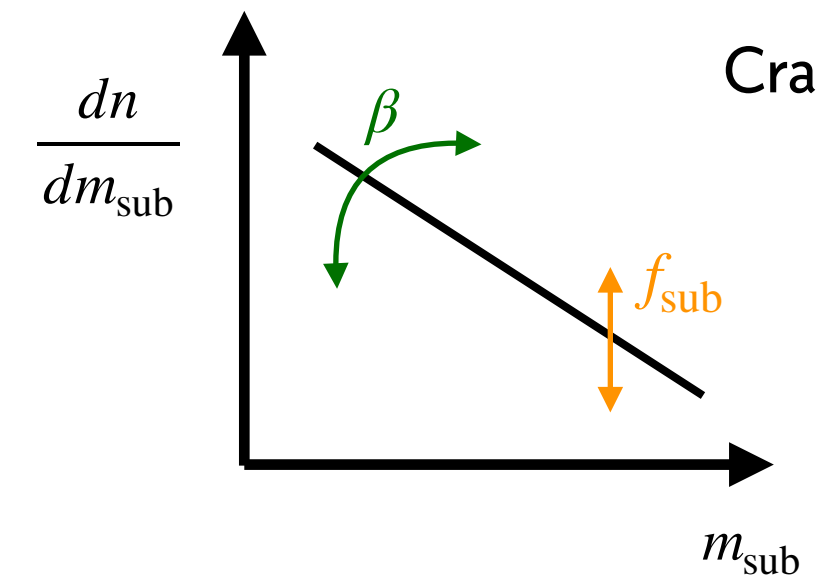
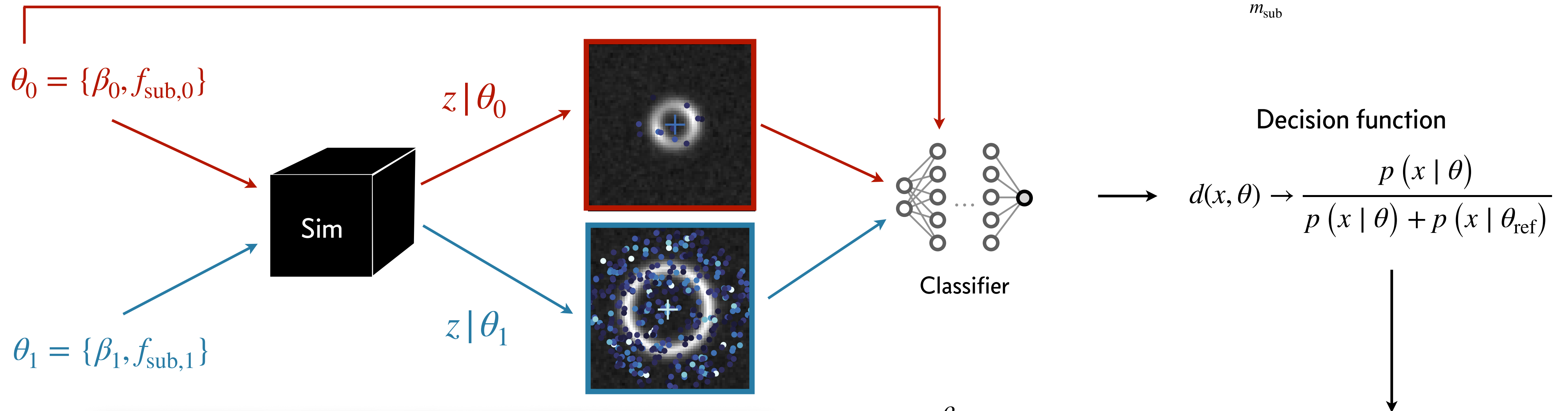
Estimator for likelihood ratio

$$\hat{r}(x) = \frac{d(x)}{1 - d(x)} \rightarrow \frac{p(x | \theta_0)}{p(x | \theta_1)}$$



# The likelihood-ratio trick

We can train a classifier between two sets of simulated samples



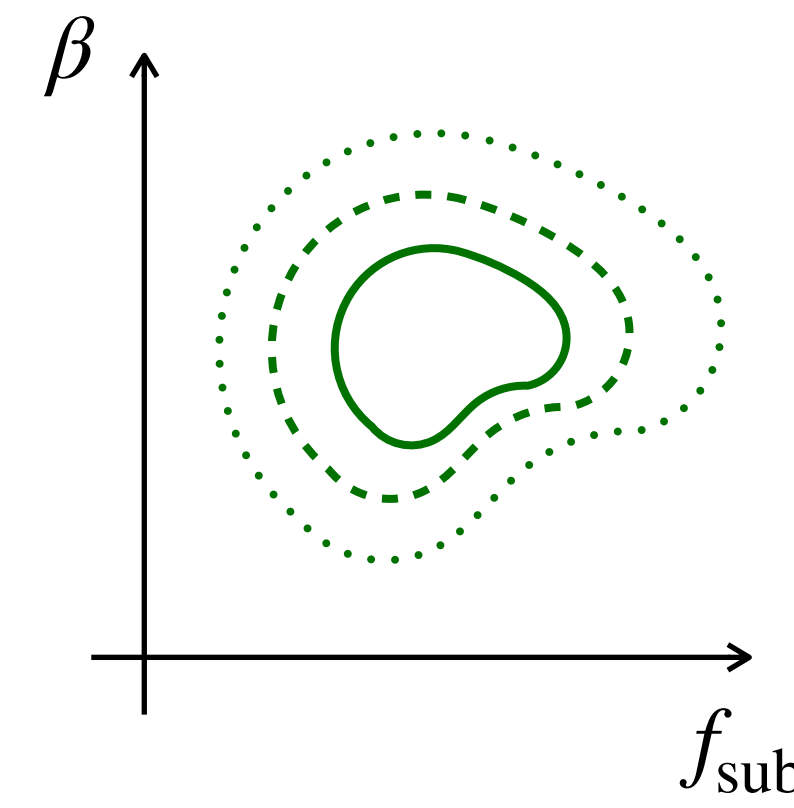
Cranmer, Pavez, Louppe [arXiv 2015]  
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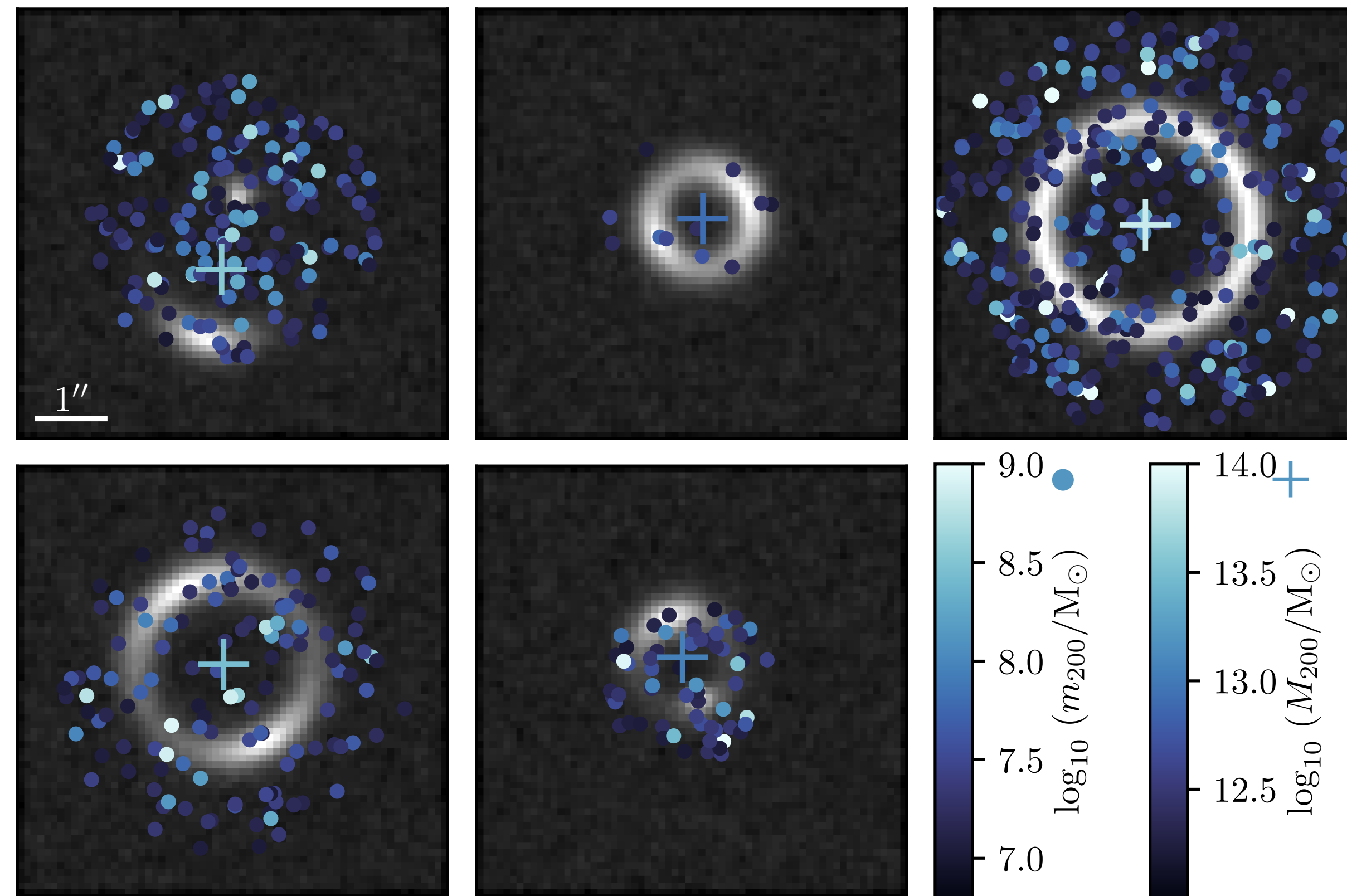
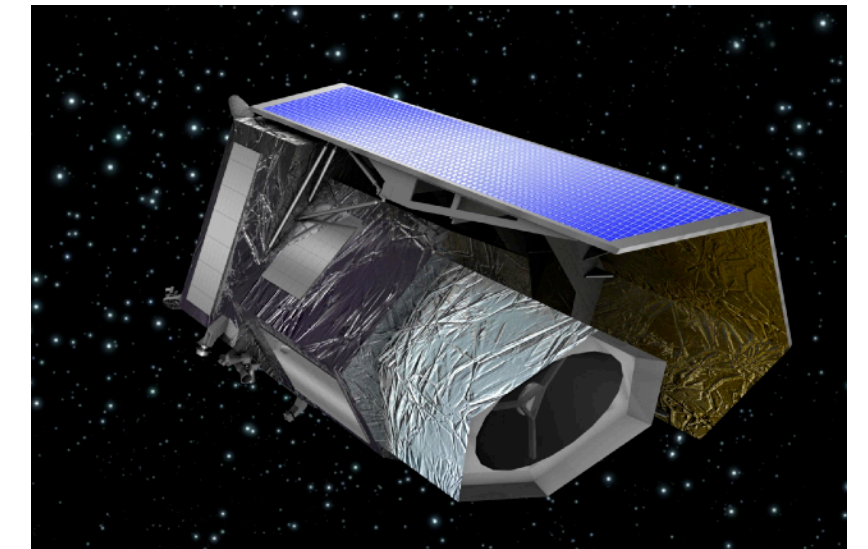
Estimator for likelihood ratio

$$\hat{r}(x | \theta) = \frac{d(x, \theta)}{1 - d(x, \theta)} \rightarrow \frac{p(x | \theta)}{p(x | \theta_{\text{ref}})}$$

# Proof of principle

Brehmer, SM, Hermans, Louppe, Cranmer [ApJ 2019]

Simulated ensemble of galaxy-galaxy lenses observable by *Euclid*

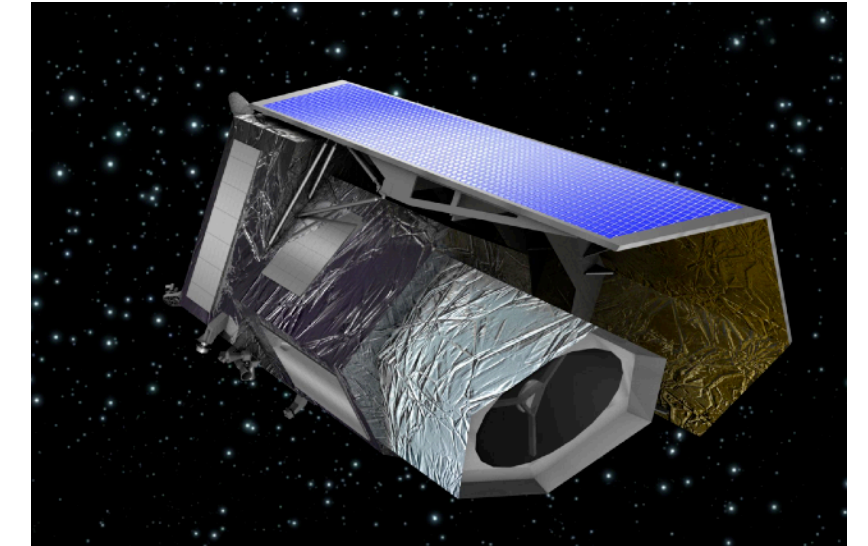


$$f_{\text{sub}} = 5\%, \beta = -0.9$$

# Proof of principle

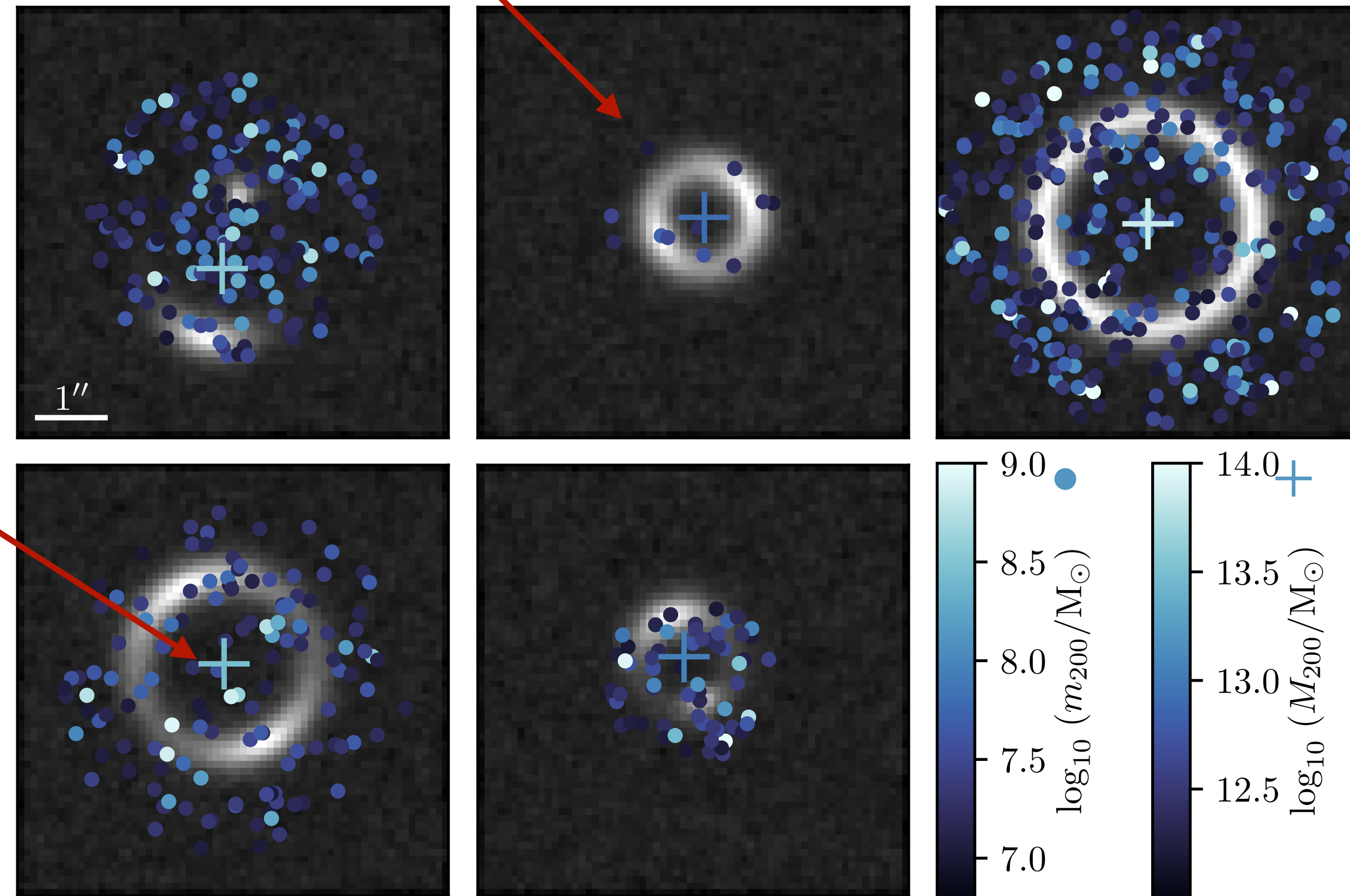
Brehmer, SM, Hermans, Louppe, Cranmer [ApJ 2019]

Simulated ensemble of galaxy-galaxy lenses observable by *Euclid*



Lensing host galaxies at  $z \sim 0.5 - 1$

Galaxy sources at  $z \sim 1.5$

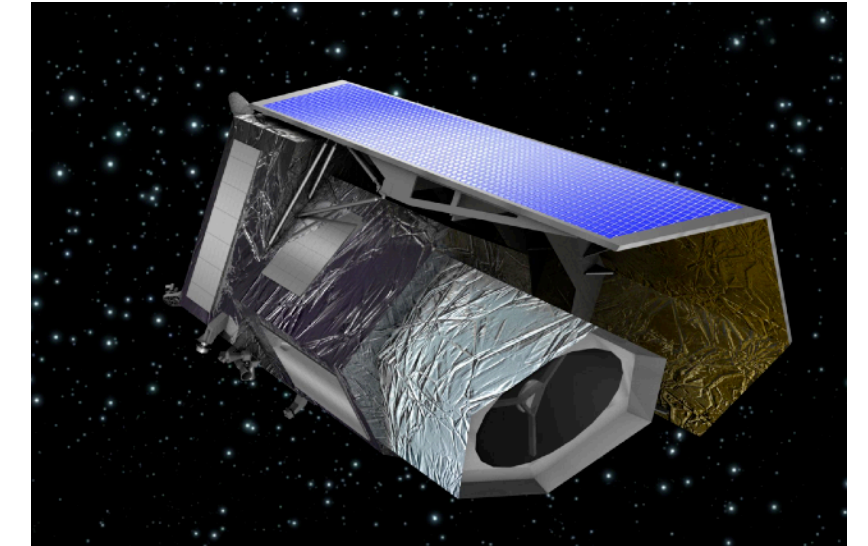


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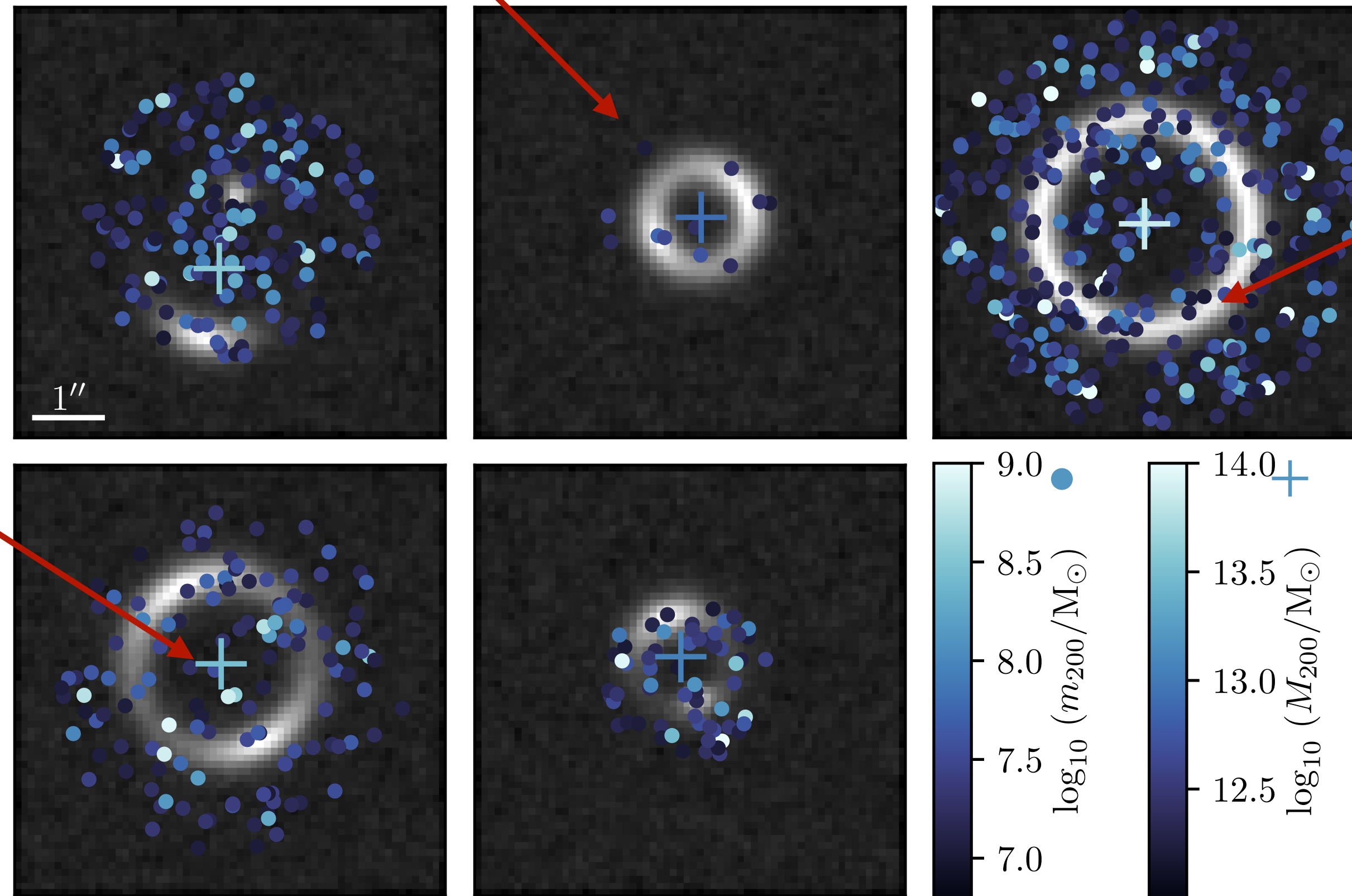
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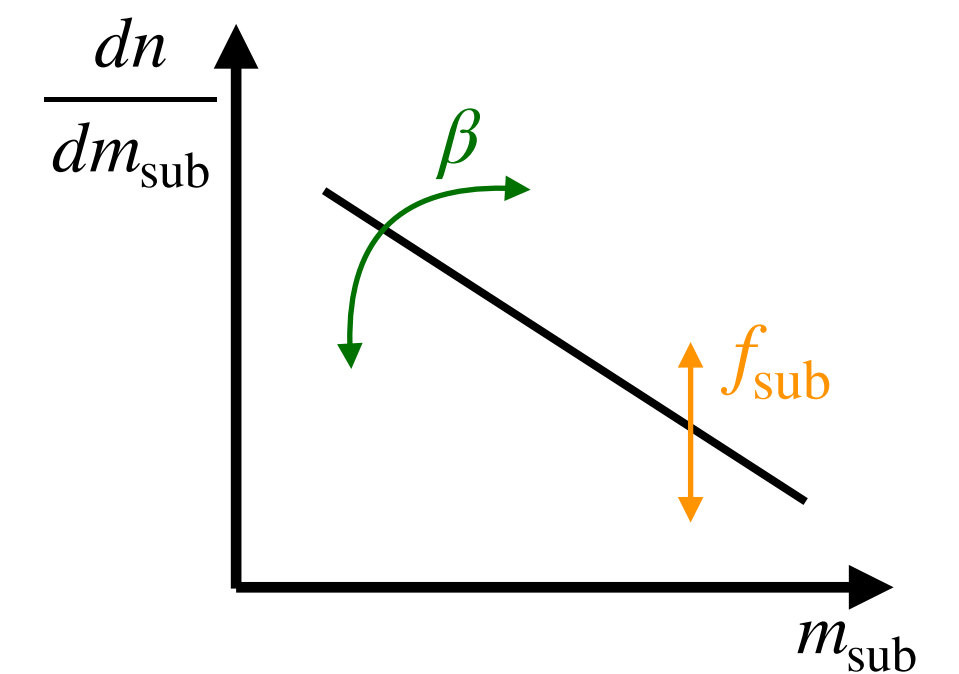


Lensing host galaxies at  $z \sim 0.5 - 1$

Galaxy sources at  $z \sim 1.5$



Subhalo mass function with two parameters

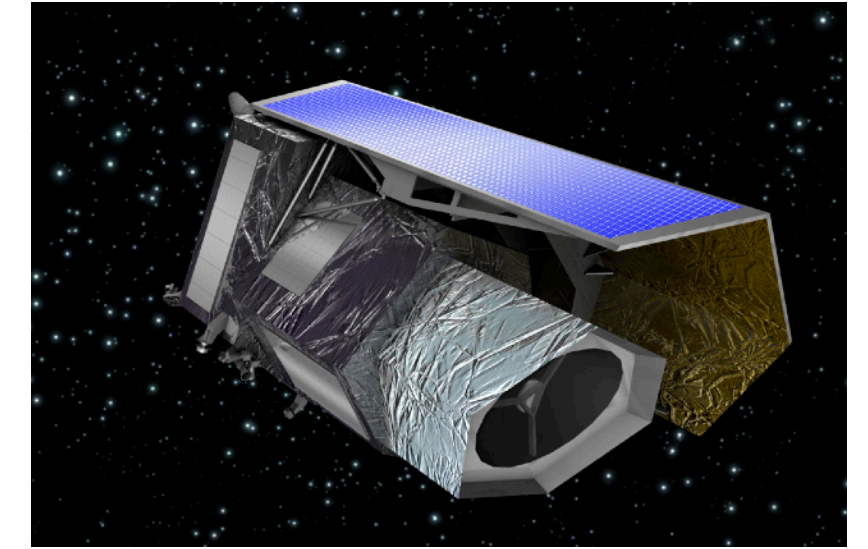


$$f_{\text{sub}} = 5\%, \beta = -0.9$$

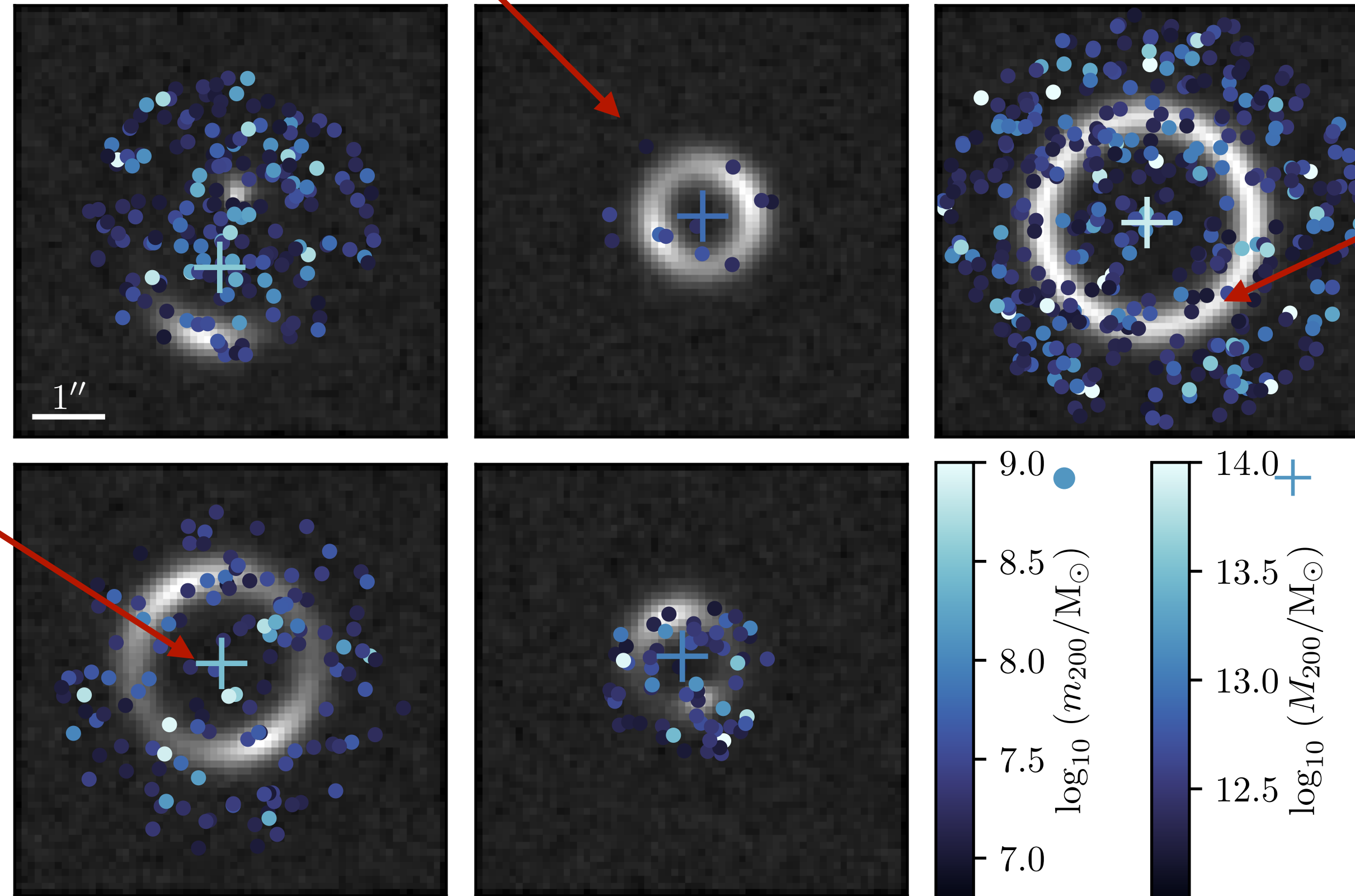
# Proof of principle

Brehmer, SM, Hermans, Louppe, Cranmer [ApJ 2019]

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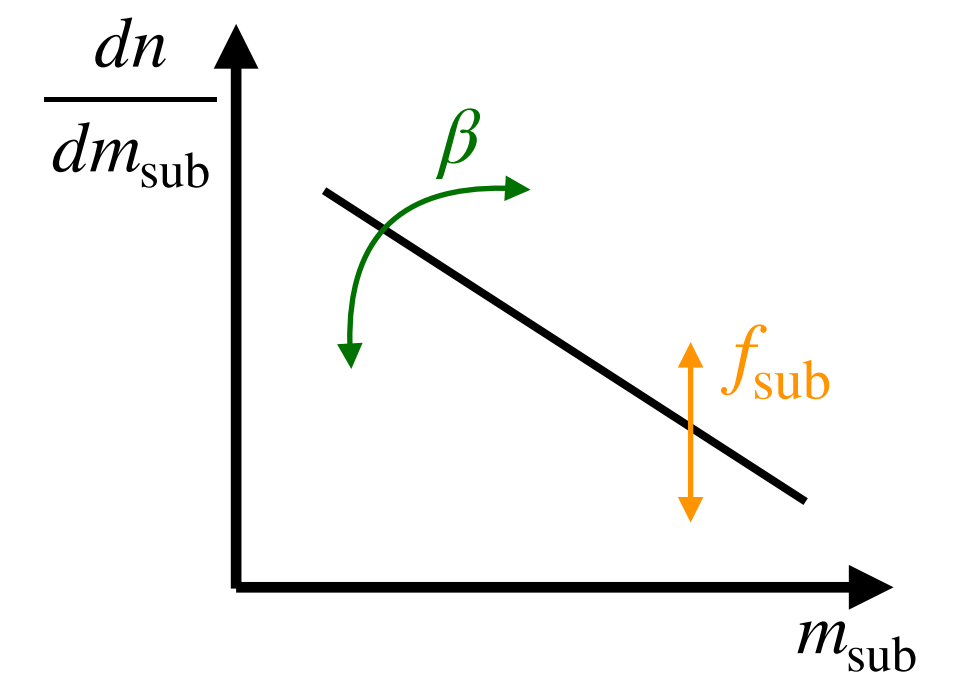
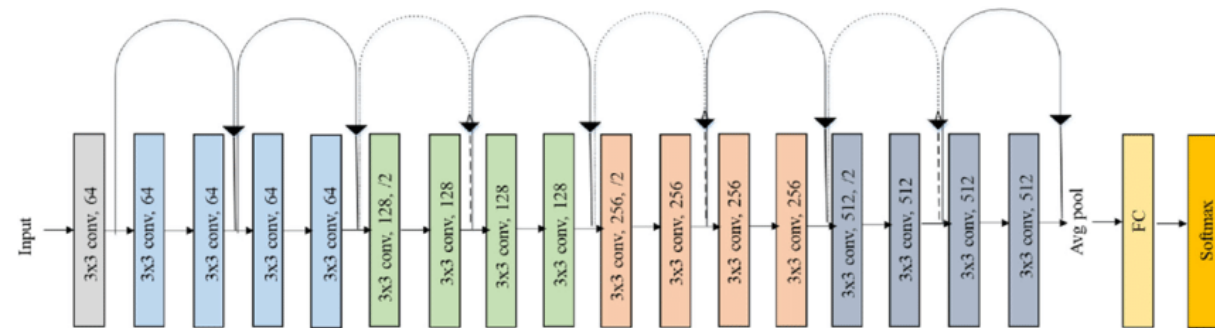
Lensing host galaxies at  $z \sim 0.5 - 1$



Subhalo mass function with two parameters

Galaxy sources at  $z \sim 1.5$

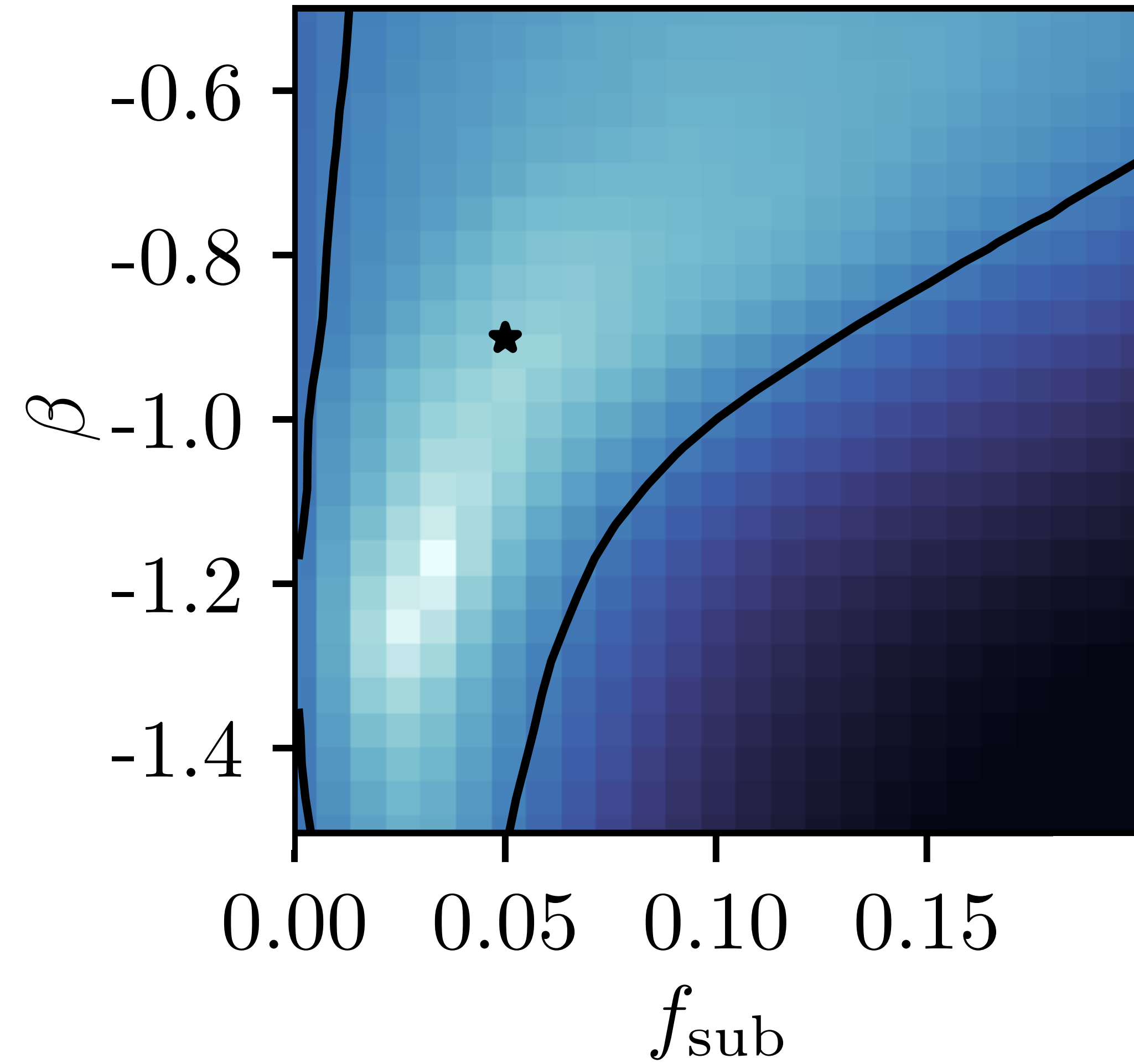
ResNet-18 architecture



$$f_{\text{sub}} = 5\%, \beta = -0.9$$

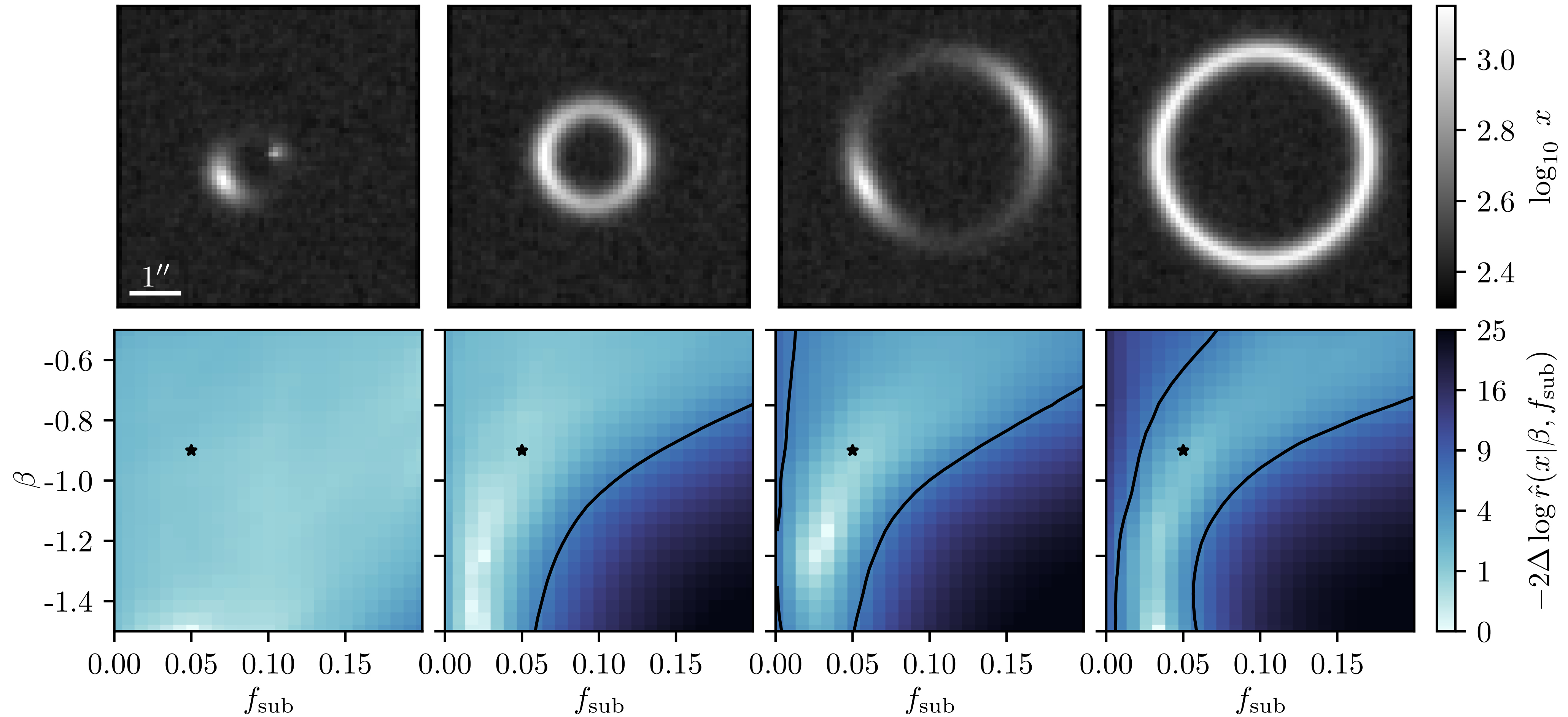
# Inferred likelihood ratios

$$f_{\text{sub}} = 5\%, \beta = -0.9$$



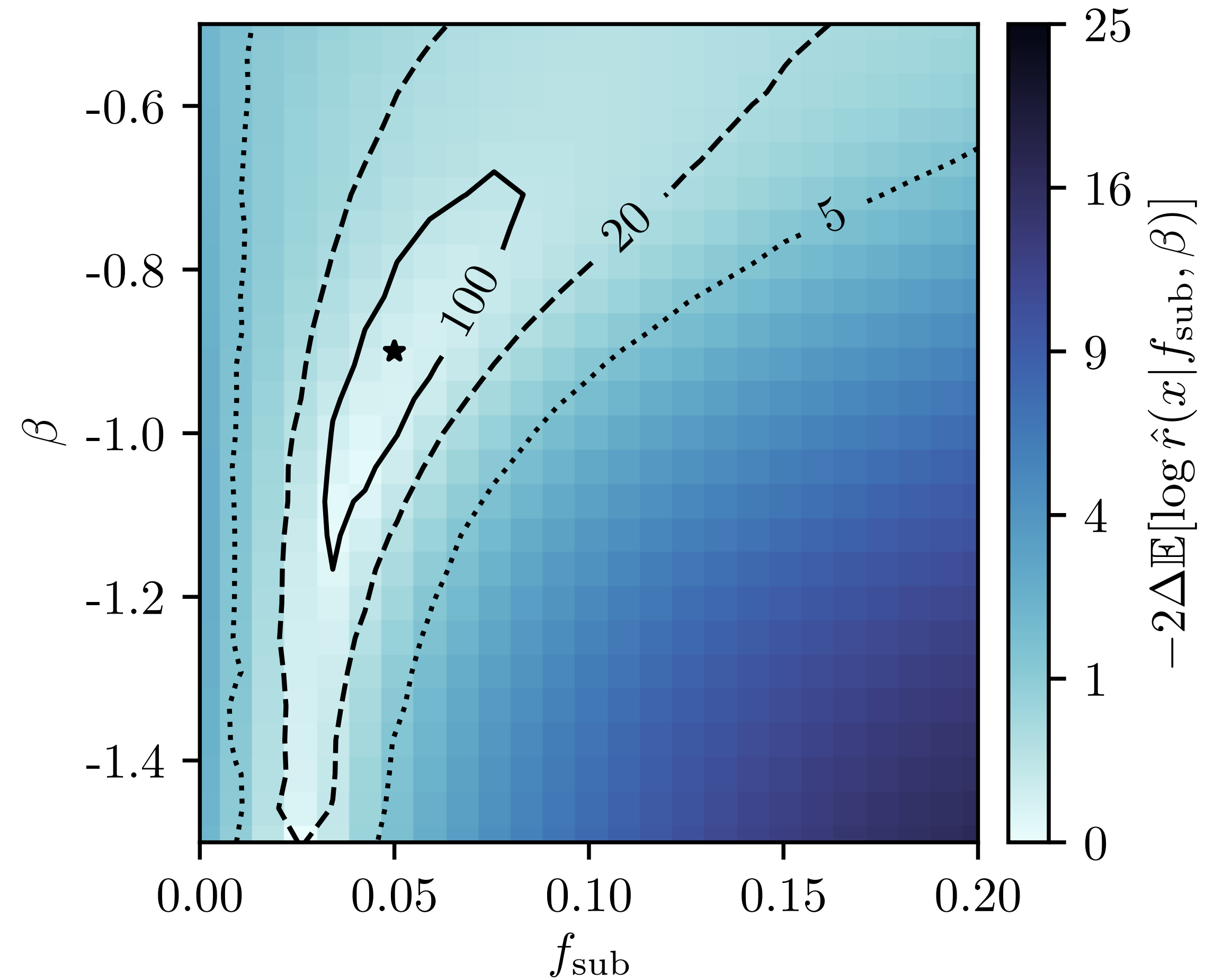
# Inferred likelihood ratios: *individual images*

$$f_{\text{sub}} = 5\%, \beta = -0.9$$



# Inferred likelihood ratios: *stacking images*

$$f_{\text{sub}} = 5\%, \beta = -0.9$$



Combination of lenses can place powerful constraints on subhalo mass function



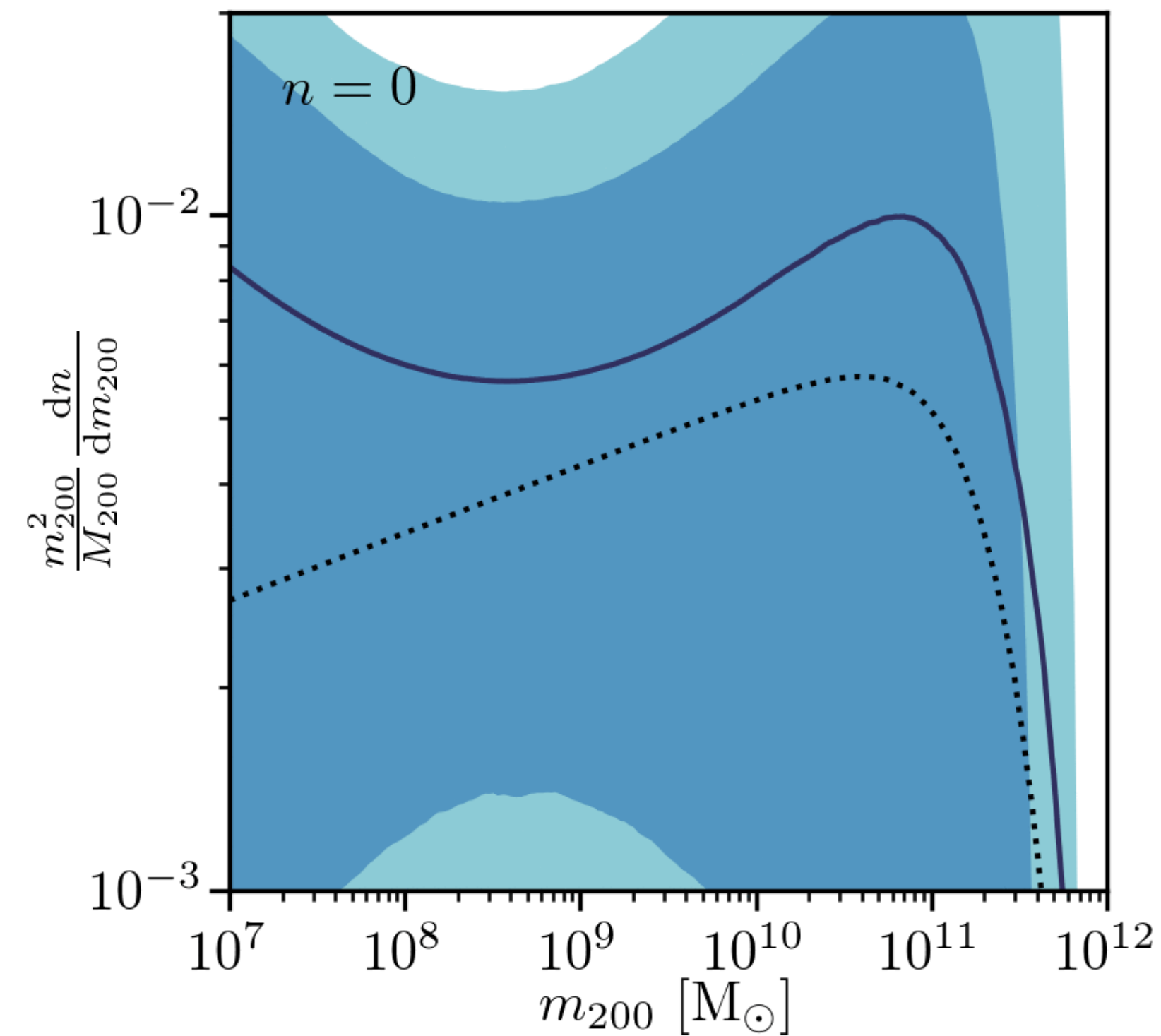
# Bayesian inference

$$f_{\text{sub}} = 5\%, \beta = -0.9$$

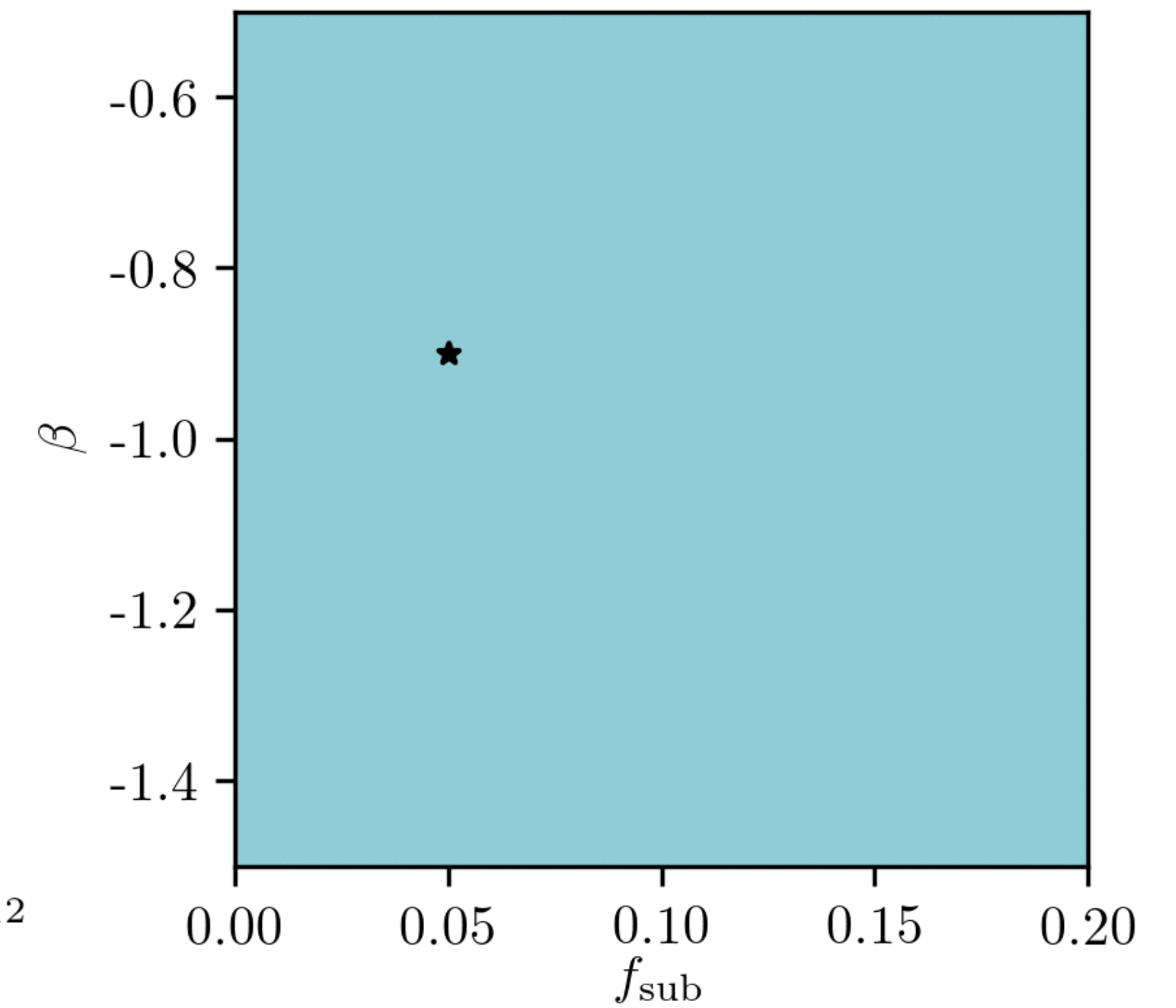
Uniform priors for  $f_{\text{sub}} \sim [0, 0.2]$ ,  $\beta \sim [-1.5, -0.5]$

Lens sample

Mass function posterior



Parameter posteriors



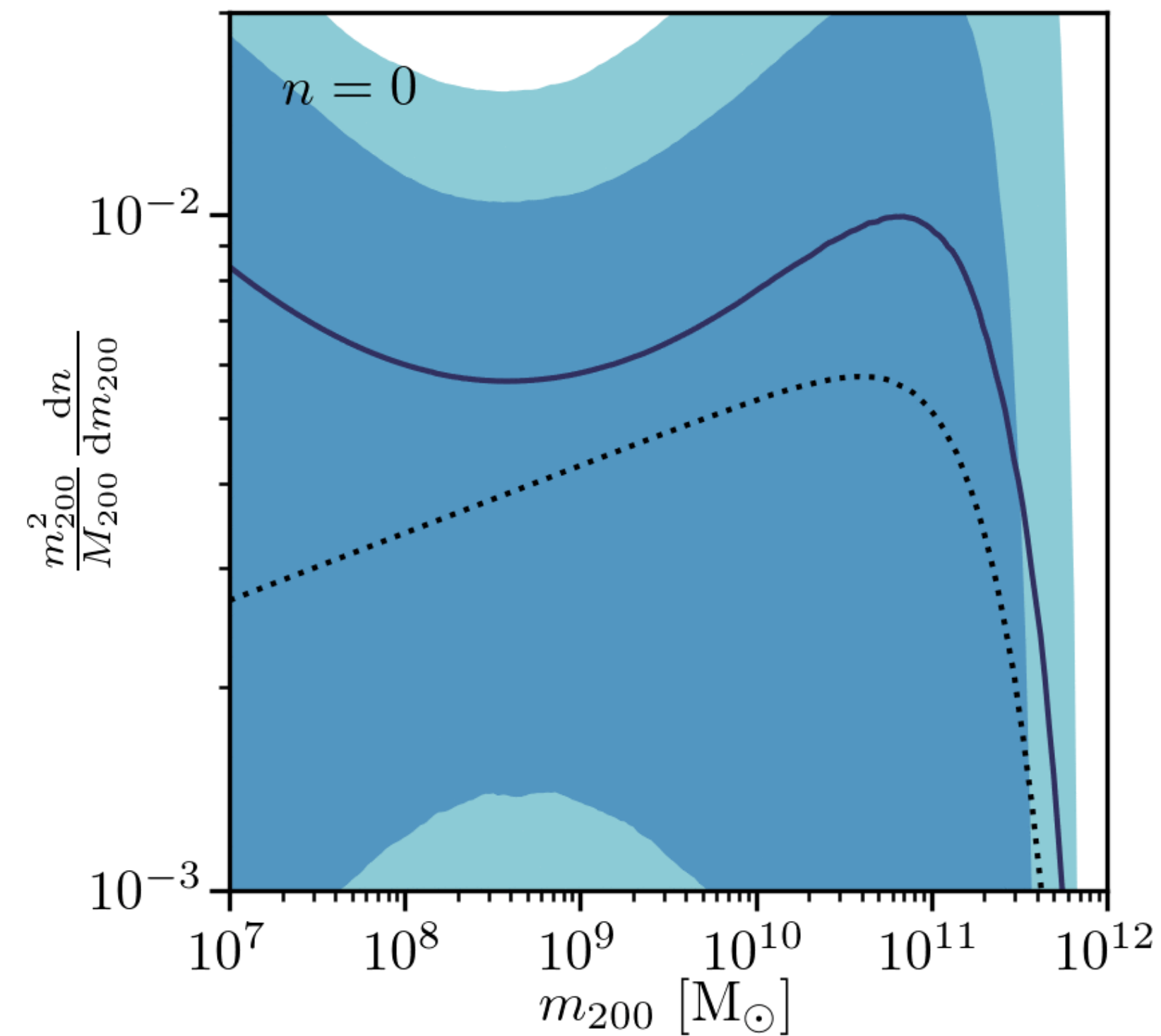
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$$f_{\text{sub}} = 5\%, \beta = -0.9$$

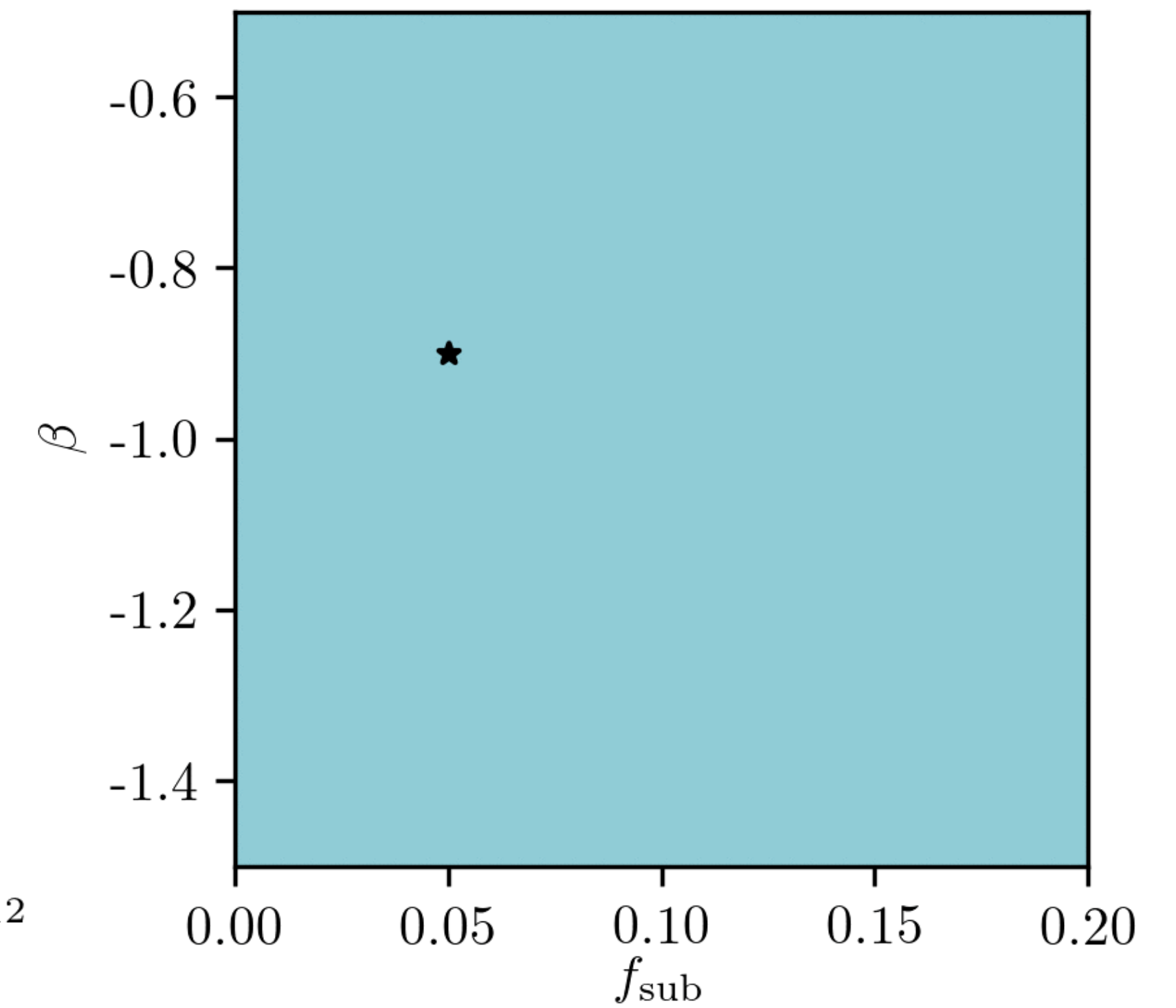
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Lens sample

Mass function posterior



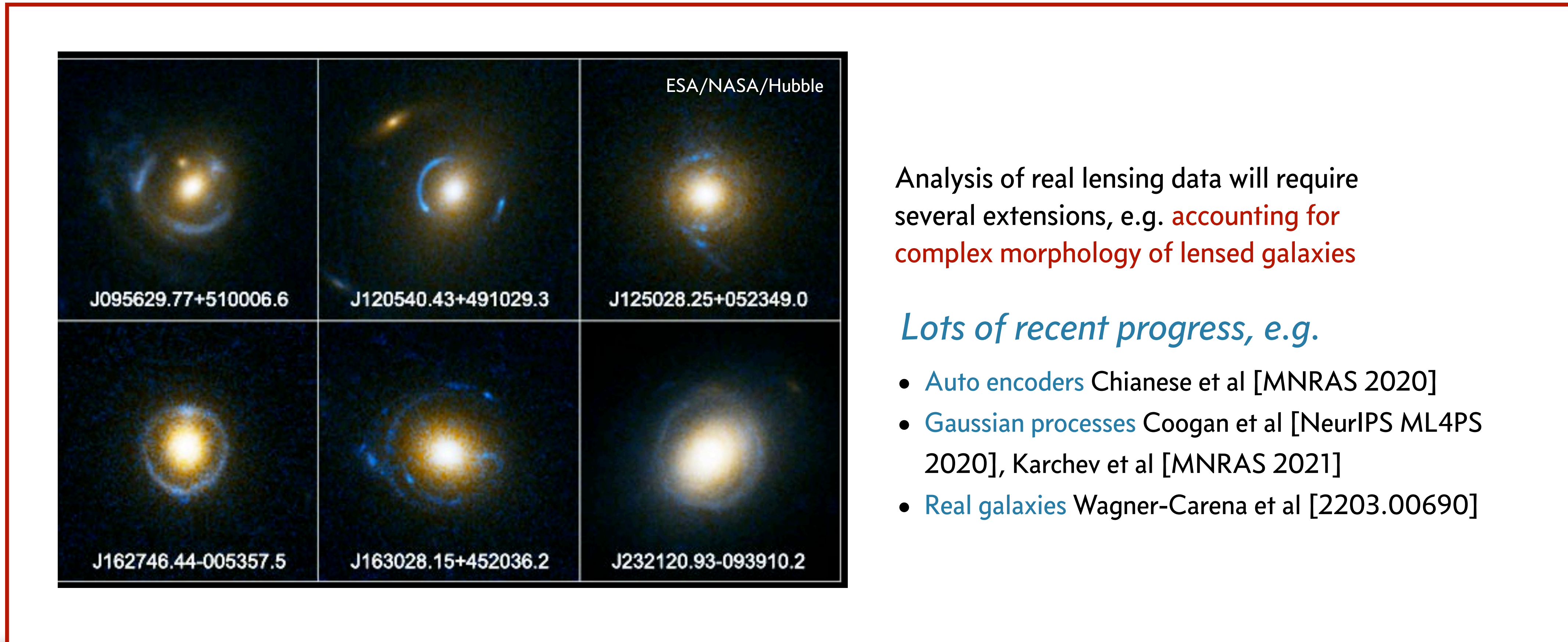
Parameter posteriors



# Bayesian inference

$$f_{\text{sub}} = 5\%, \beta = -0.9$$

Uniform priors for  $f_{\text{sub}} \sim [0, 0.2]$ ,  $\beta \sim [-1.5, -0.5]$

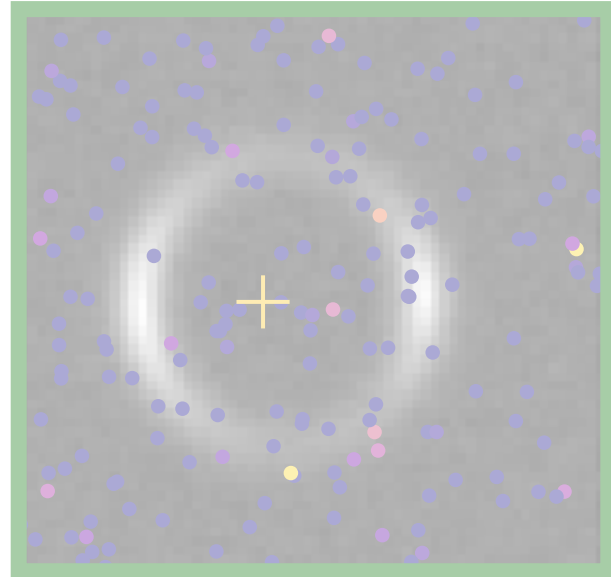


Analysis of real lensing data will require several extensions, e.g. **accounting for complex morphology of lensed galaxies**

*Lots of recent progress, e.g.*

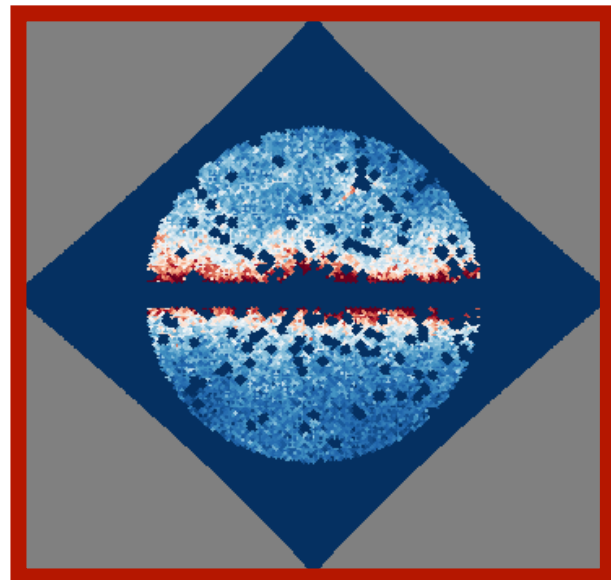
- **Auto encoders** Chianese et al [MNRAS 2020]
- **Gaussian processes** Coogan et al [NeurIPS ML4PS 2020], Karchev et al [MNRAS 2021]
- **Real galaxies** Wagner-Carena et al [2203.00690]

# Outline



Detecting extragalactic dark matter in strong lenses

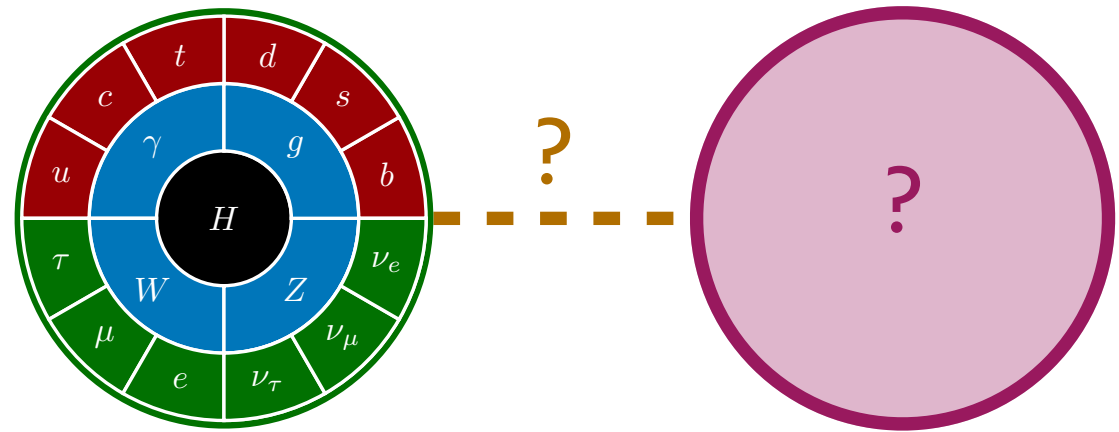
*Combining information from thousands of systems*



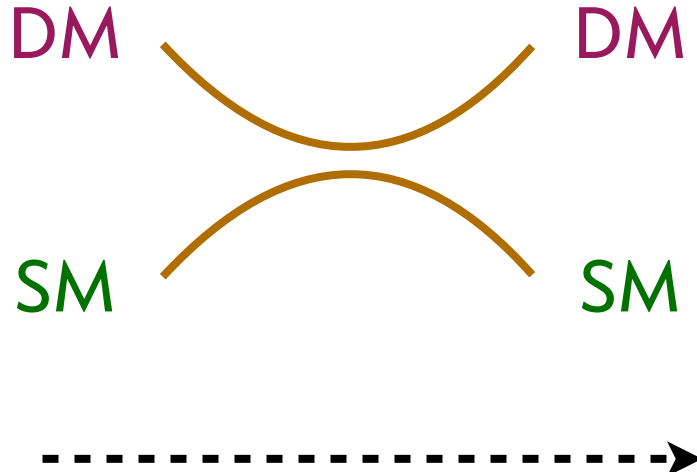
Characterizing  $\gamma$ -ray point sources in the Galactic Center

*Exploiting more information to reduce model misspecification*

# Searches for dark matter



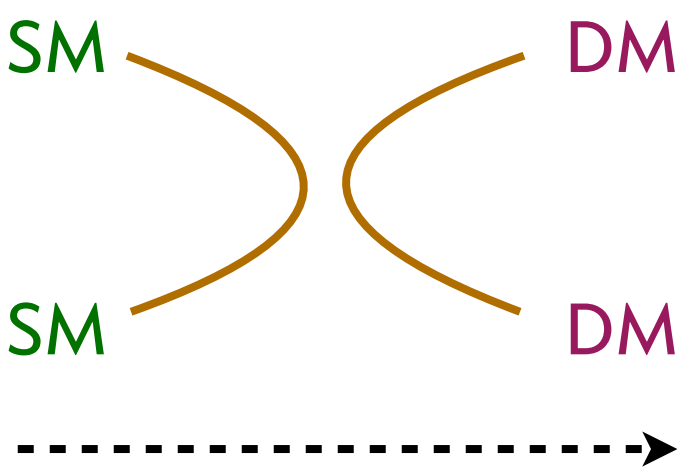
## Scattering of DM against SM



Direct detection



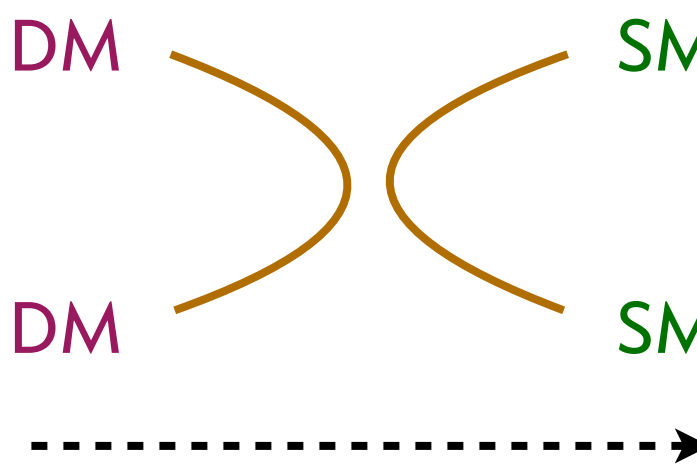
## Production of DM from SM



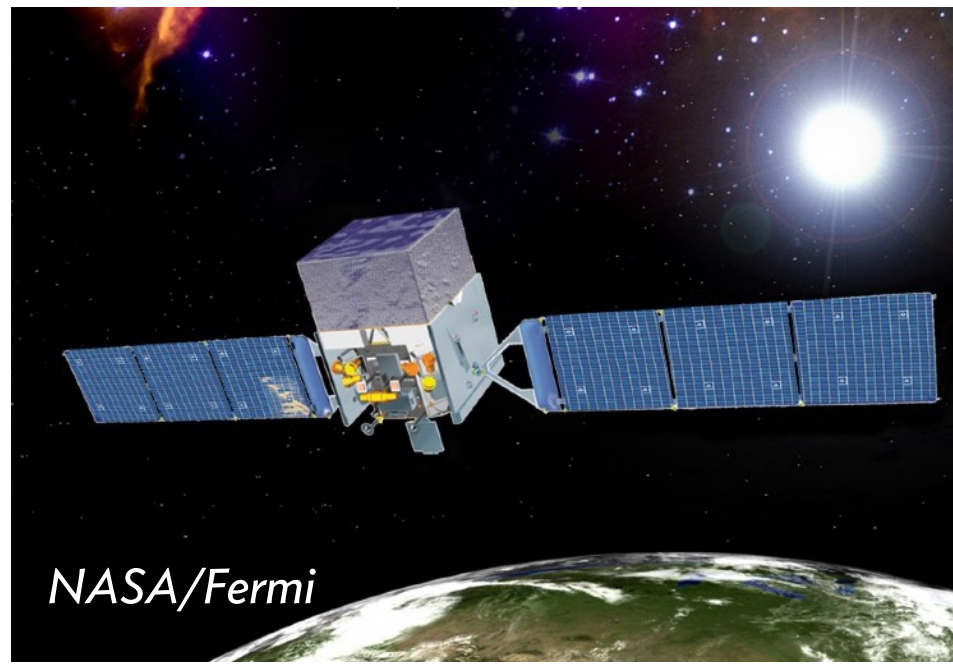
Particle colliders



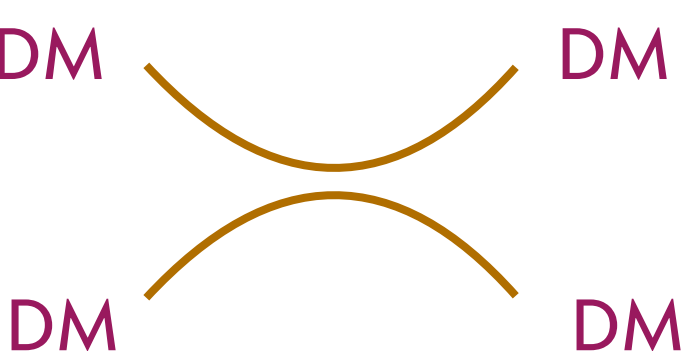
## Production of SM from DM



Indirect detection



## Gravitational effects of DM interaction

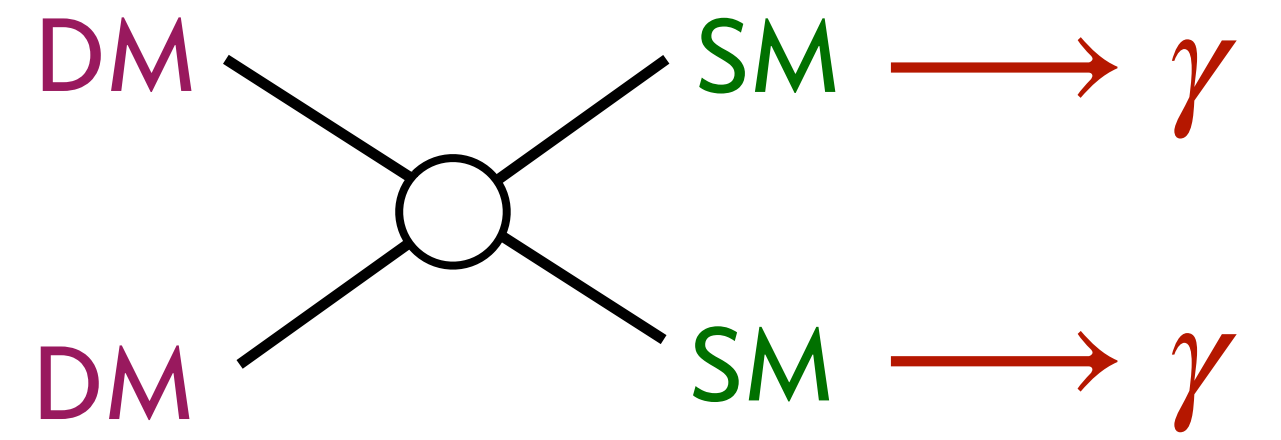


Astrophysical probes

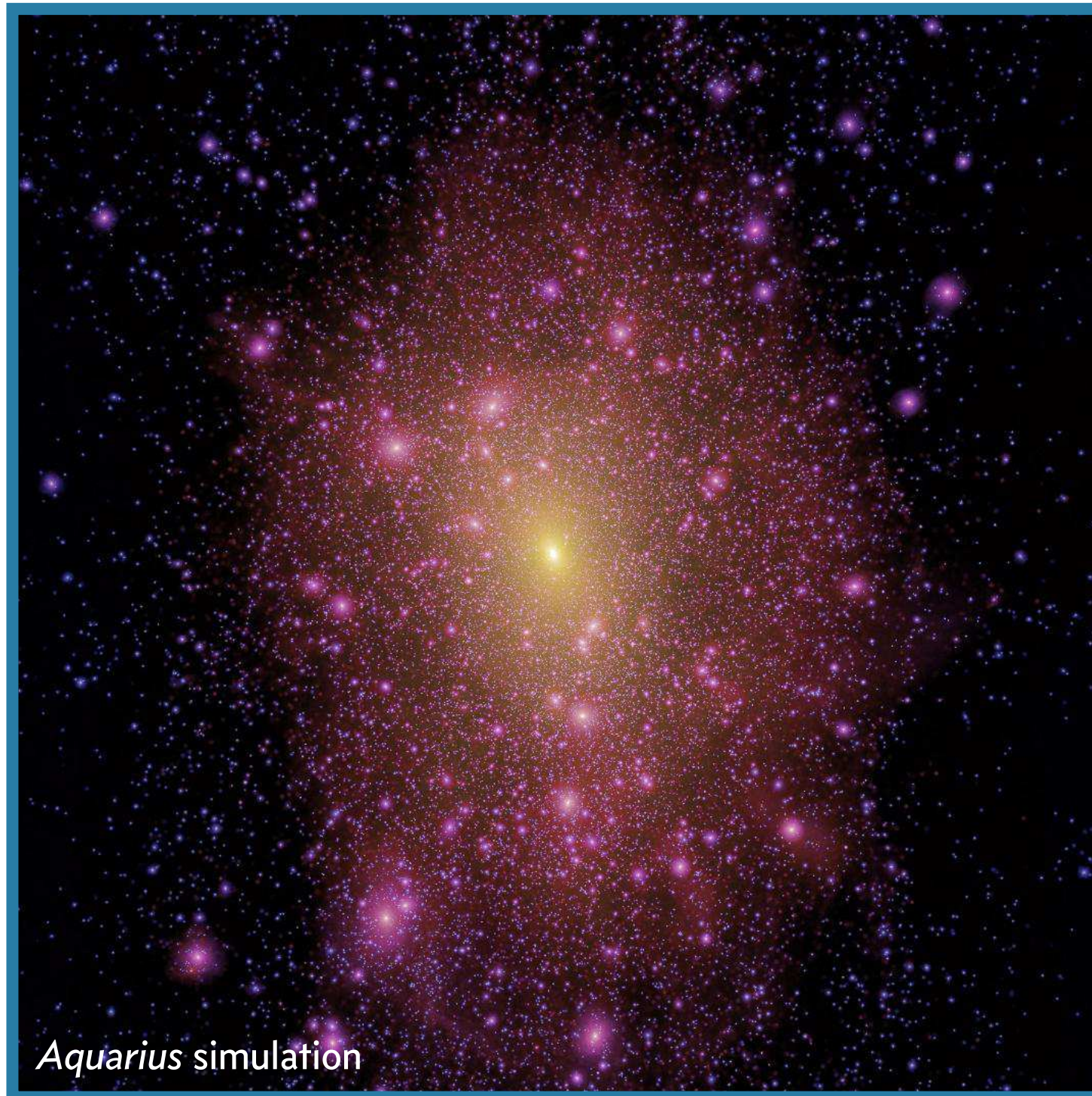


# Dark matter annihilation in the Galactic Center

Annihilating WIMP DM would produce **excess  $\gamma$ -rays from the Galactic Center**

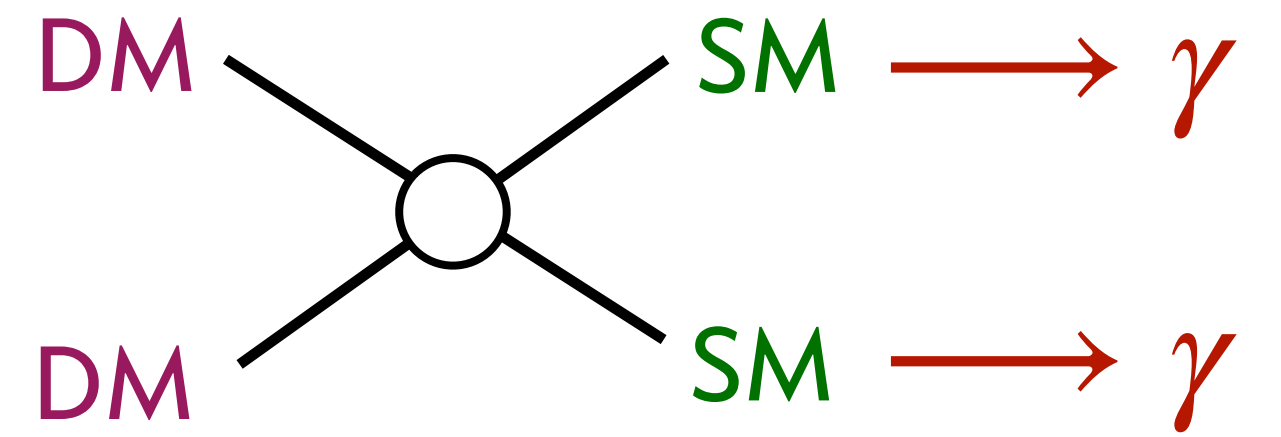


DM distribution



# Dark matter annihilation in the Galactic Center

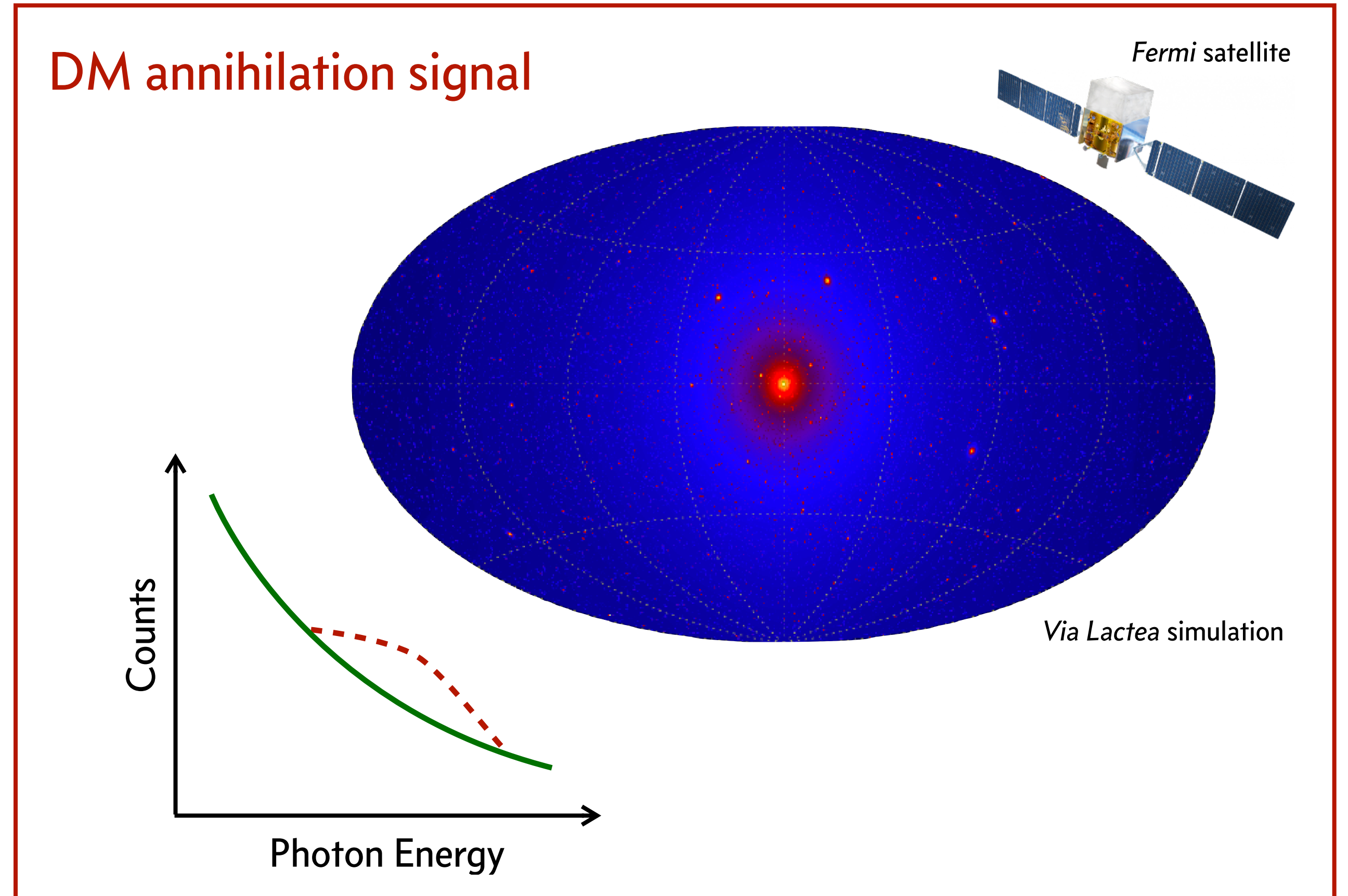
Annihilating WIMP DM would produce **excess  $\gamma$ -rays from the Galactic Center**



DM distribution



DM annihilation signal

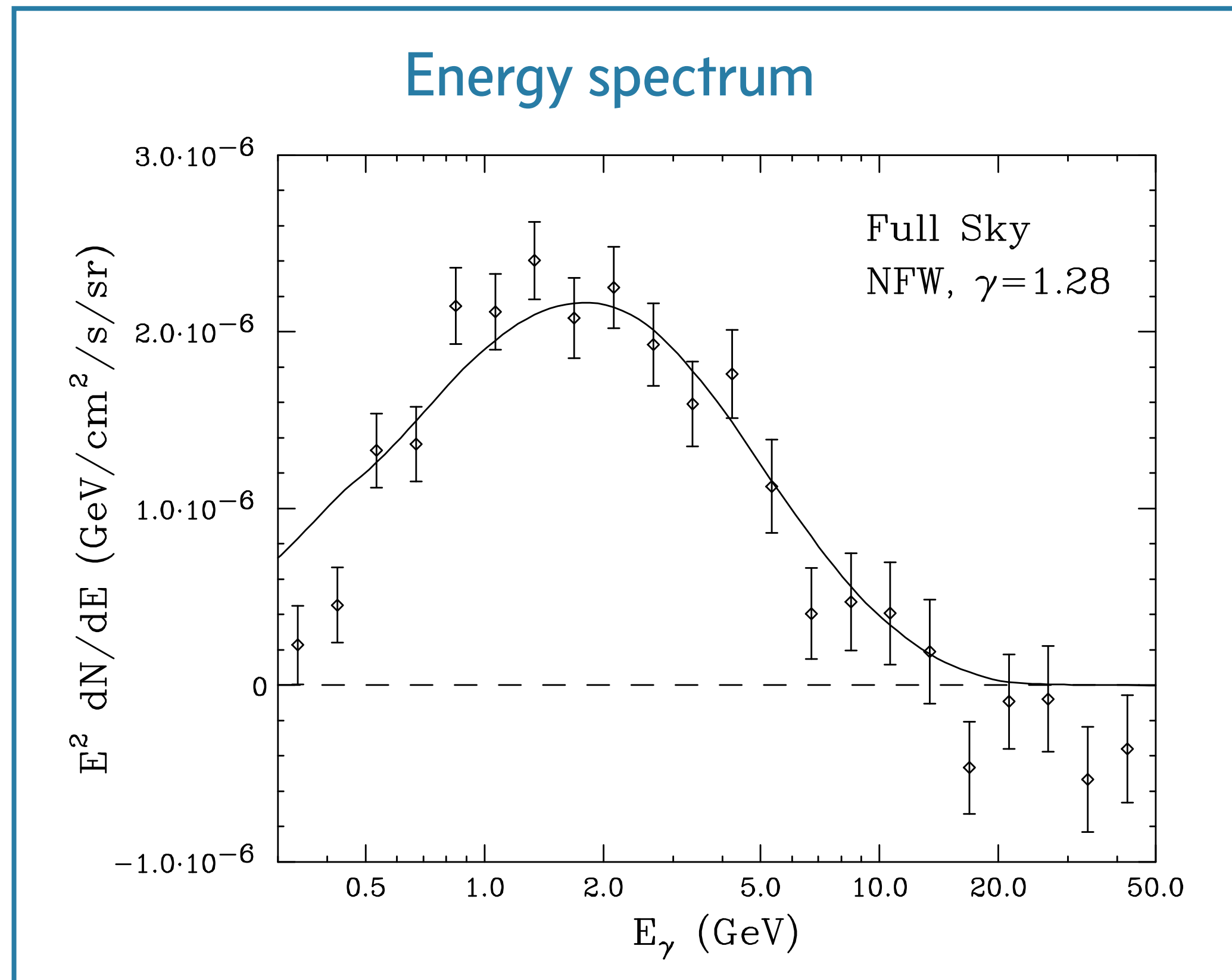


# The *Fermi* Galactic Center Excess

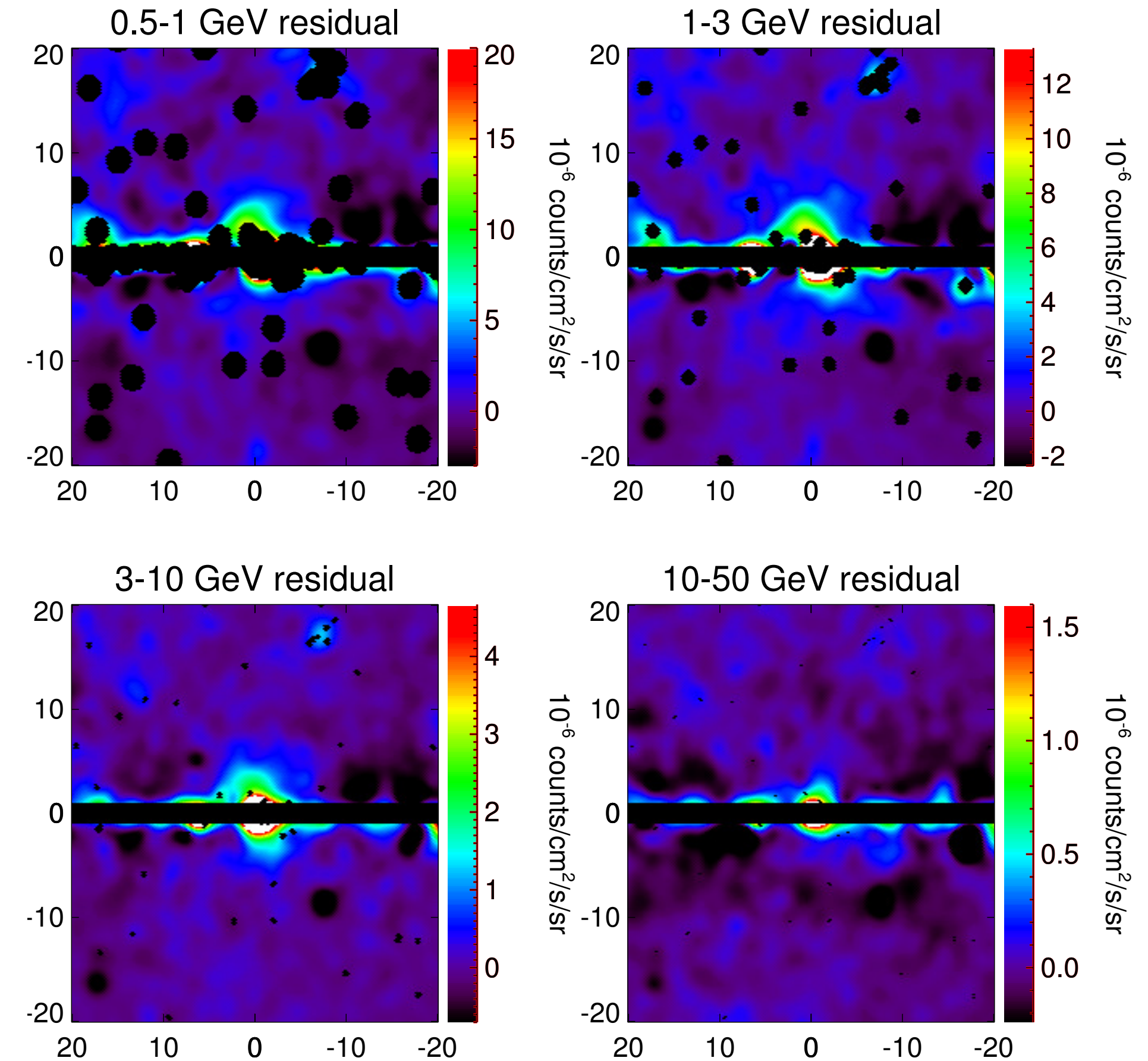
Daylan et al [PDU 2016]

## Some facts:

- $\sim$  Spherically symmetric  $\gamma$ -ray excess in the Inner Galaxy
- Extends out  $\sim 10^\circ$  from the center of Galaxy
- Constitutes  $\sim 10\%$  total flux

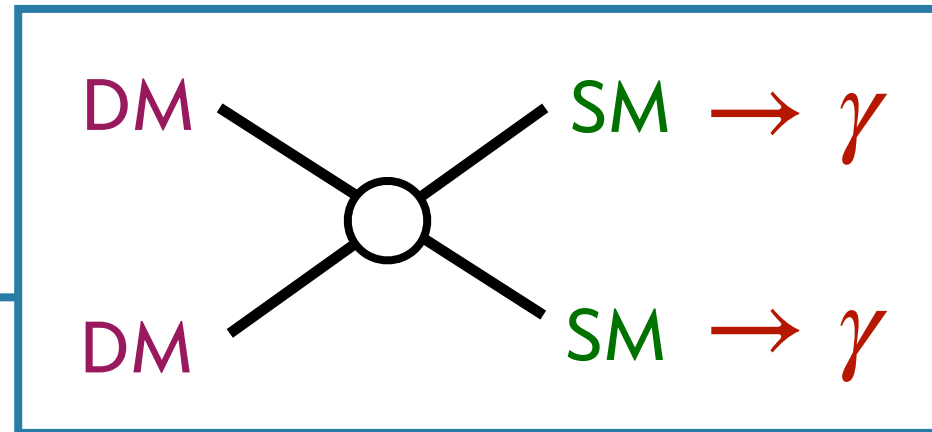


## Spatial morphology



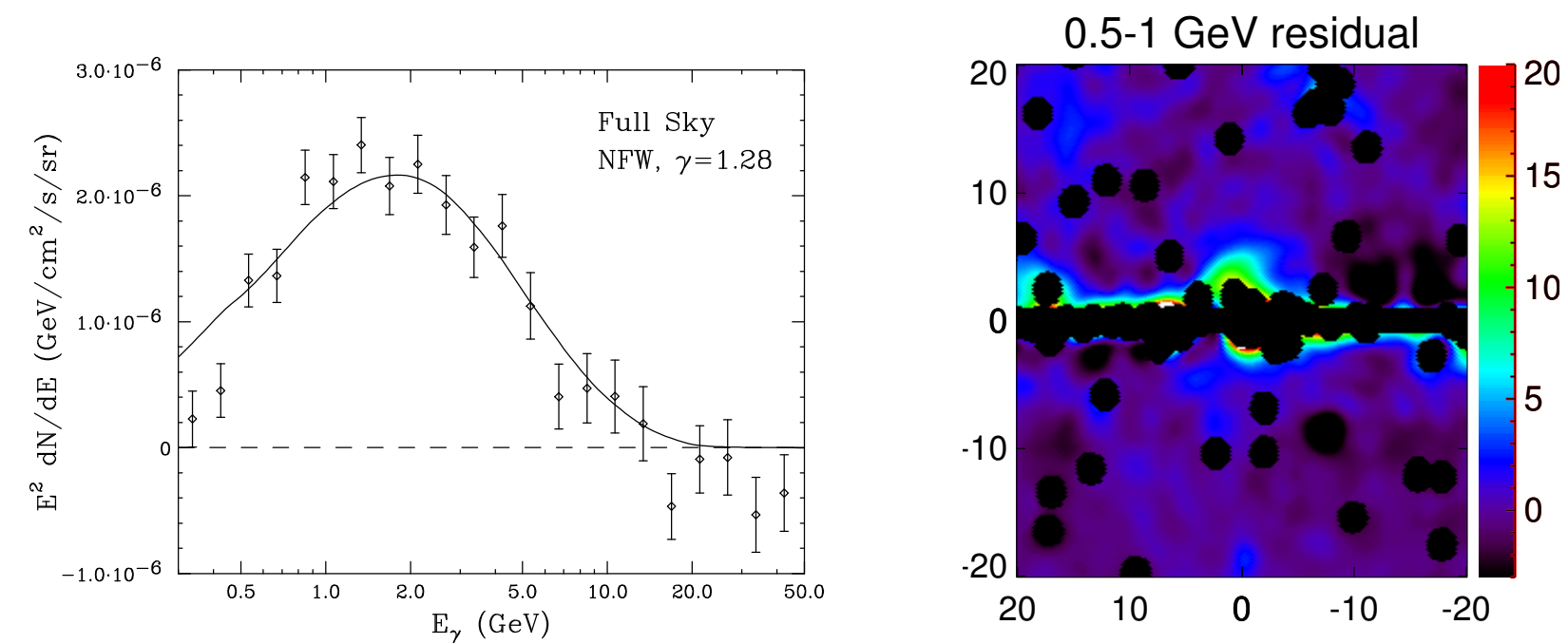


# Possible explanations



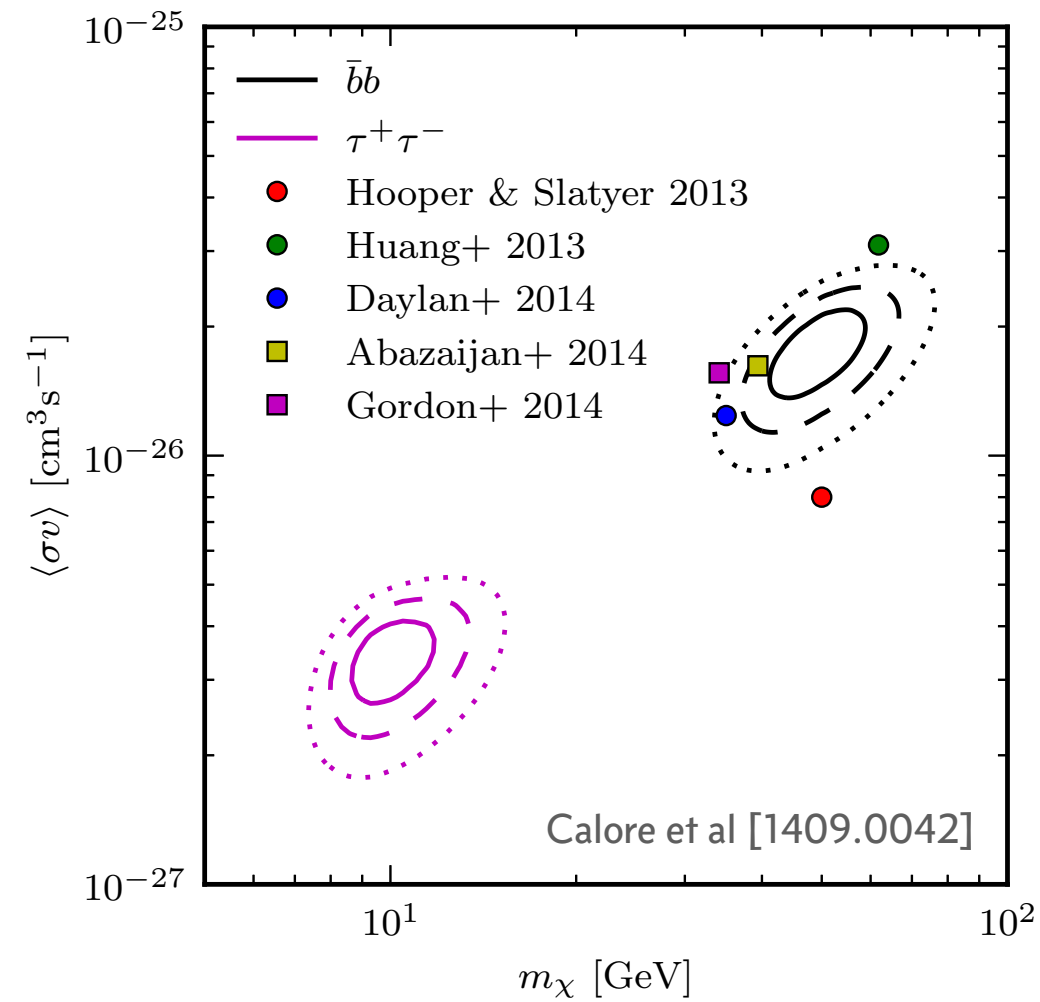
## Dark Matter

*Spectrum and spatial morphology consistent with DM expectation*



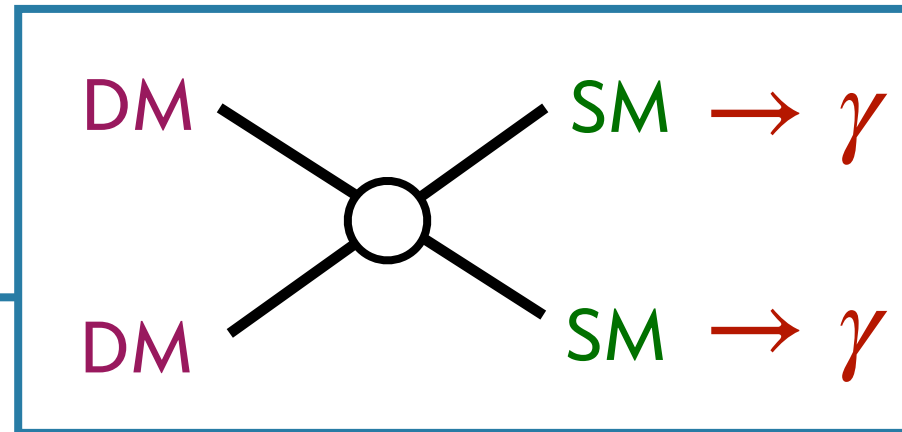
Daylan et al [1402.6703]

*Consistent with thermal cross section expectation*



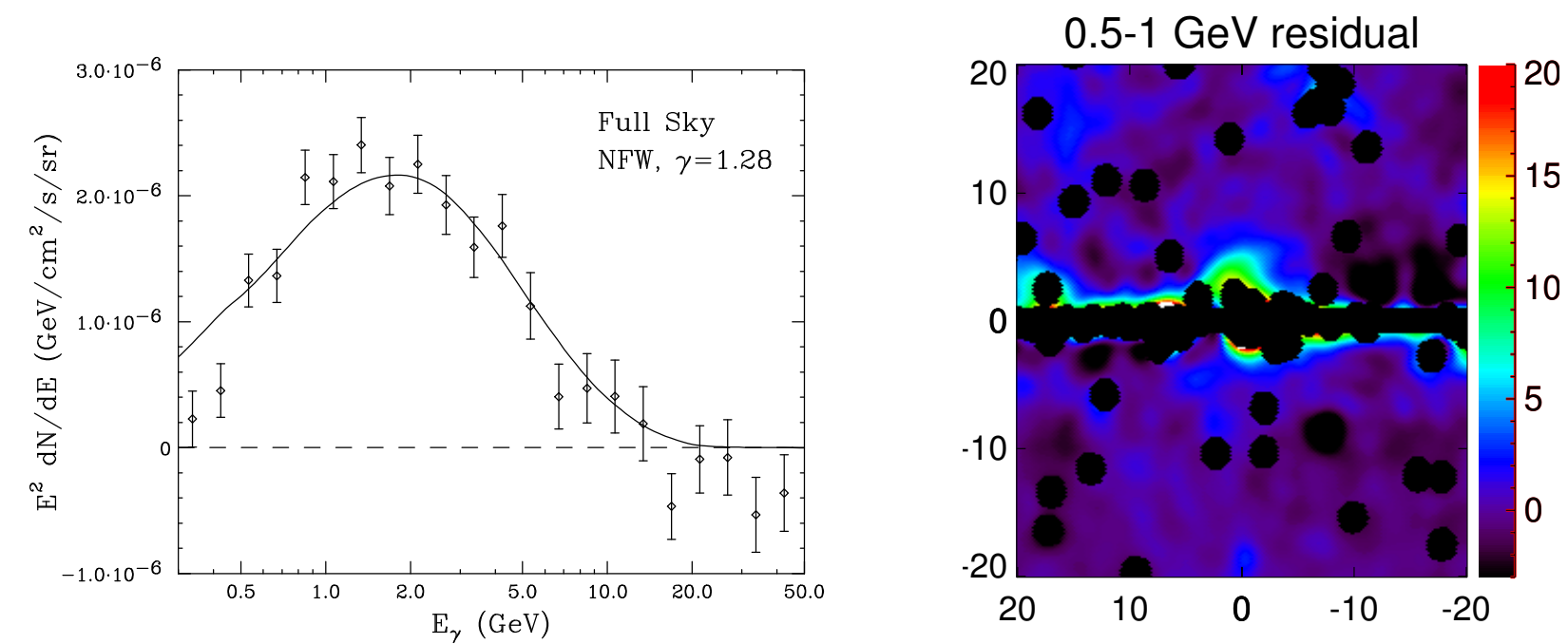
Calore et al [1409.0042]

# Possible explanations



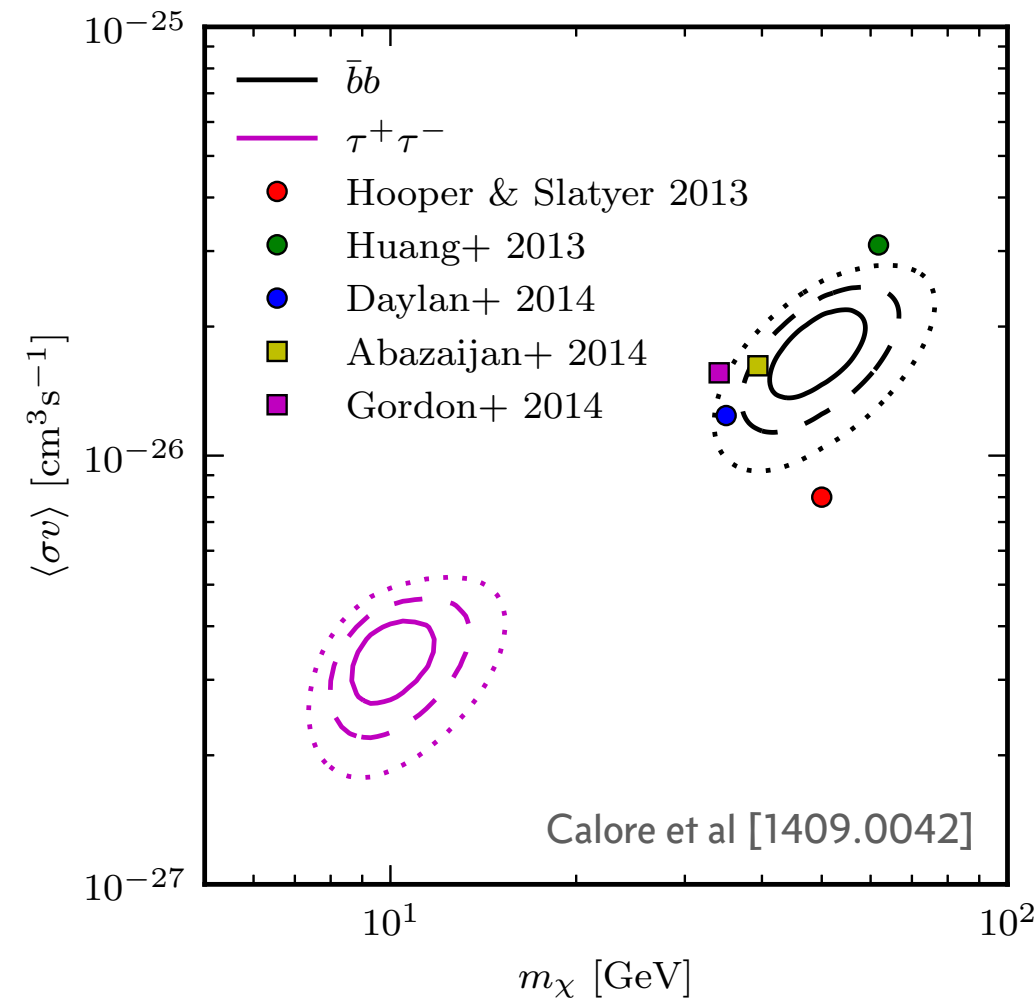
## Dark Matter

*Spectrum and spatial morphology consistent with DM expectation*



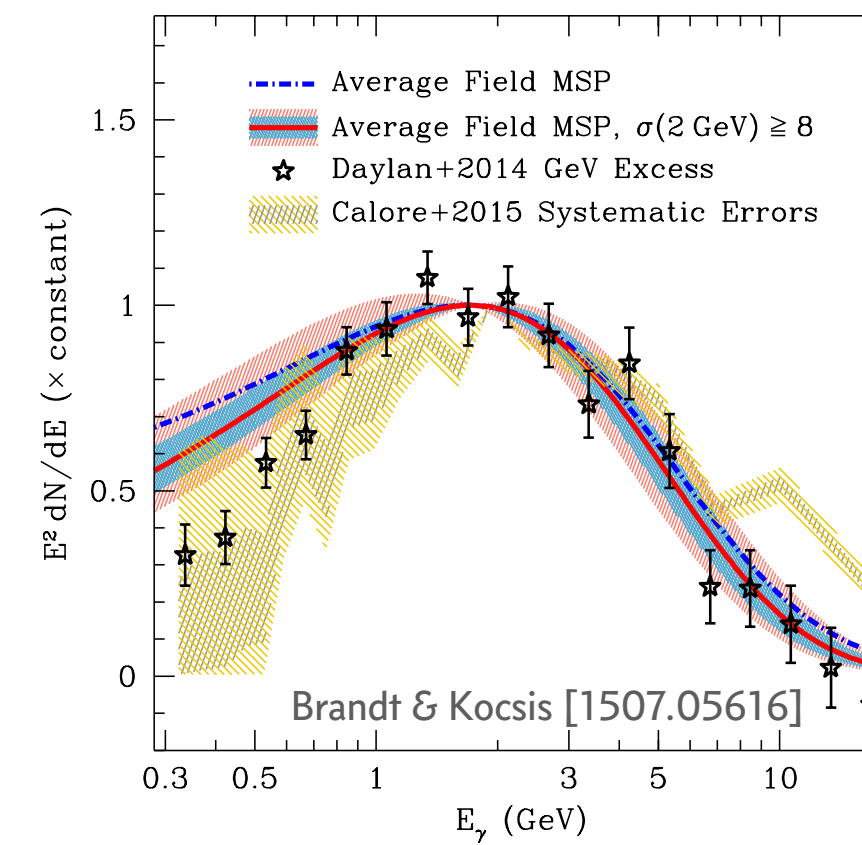
Daylan et al [1402.6703]

*Consistent with thermal cross section expectation*

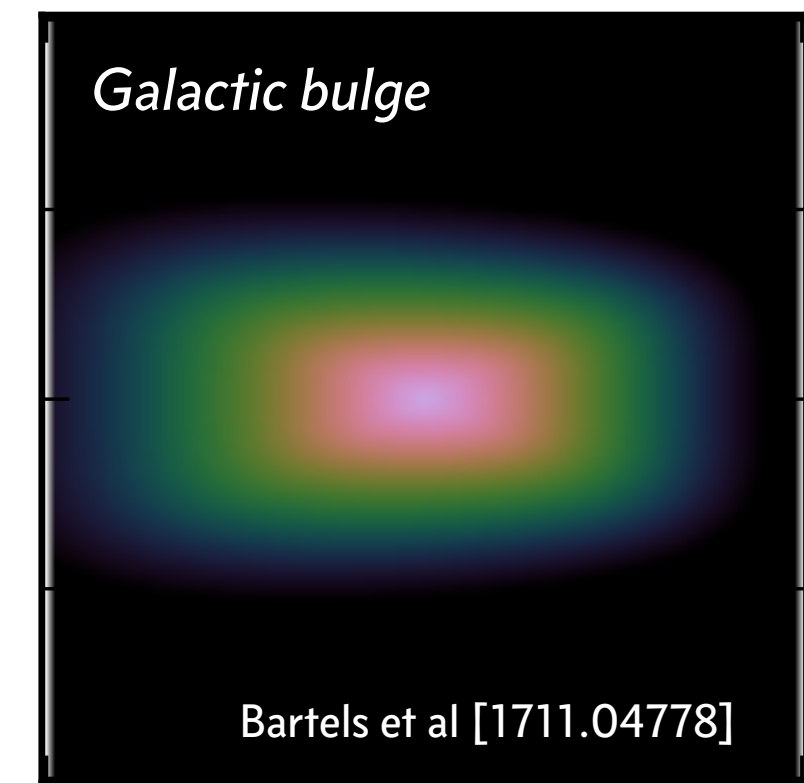


## Astrophysics

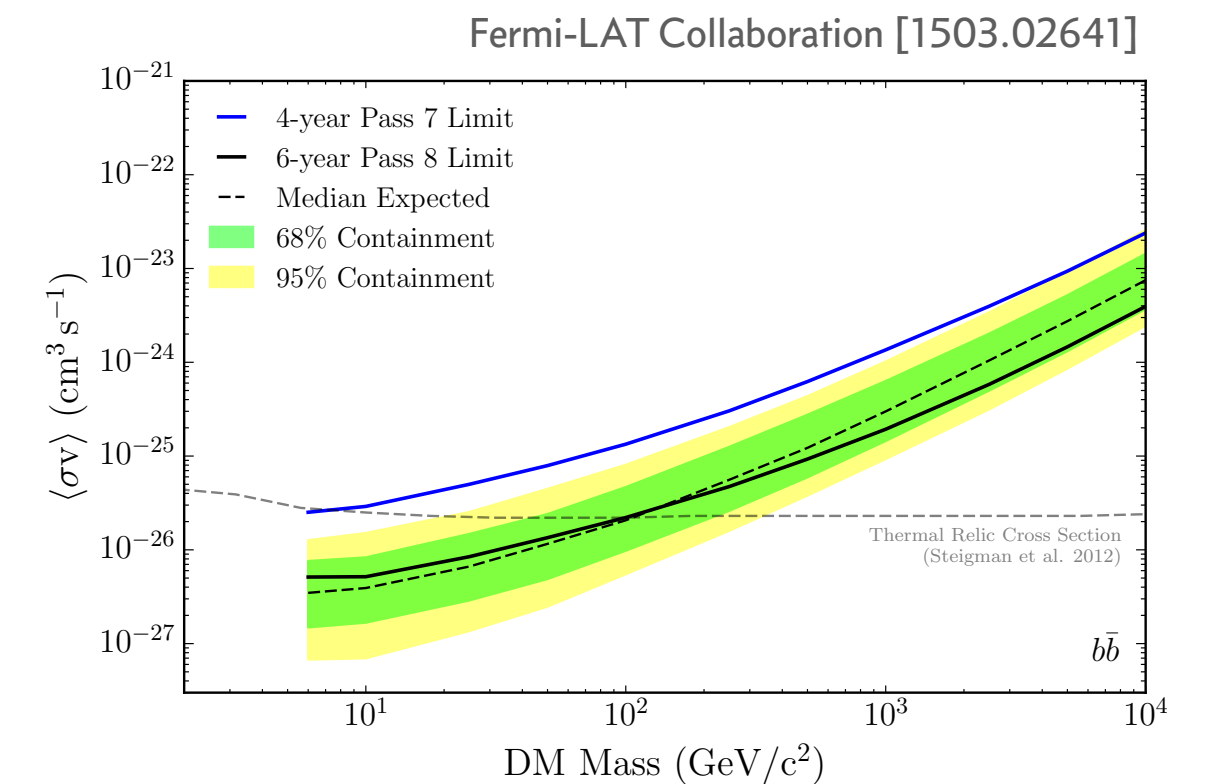
*Spectrum roughly consistent with MSP expectation*



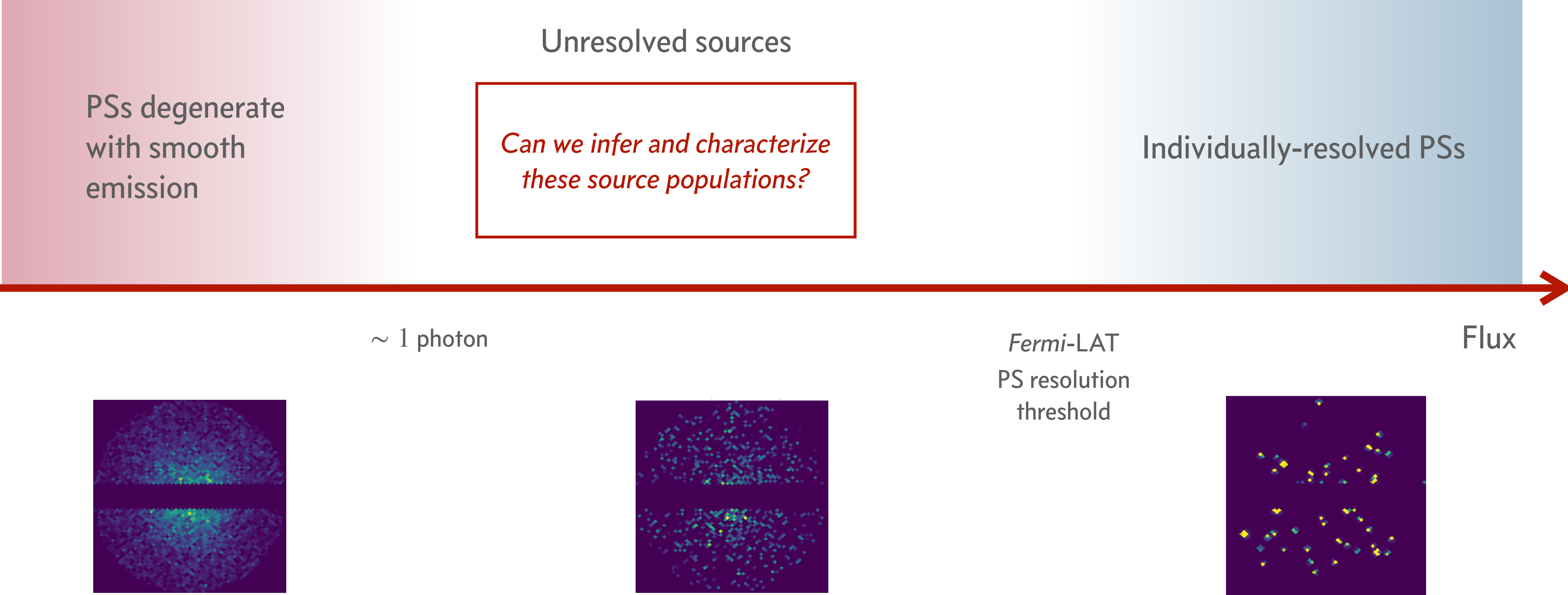
*Spatial morphology consistent with stellar distribution?*



*DM annihilation signal not seen in other targets*



# Distinguishing DM from PSs

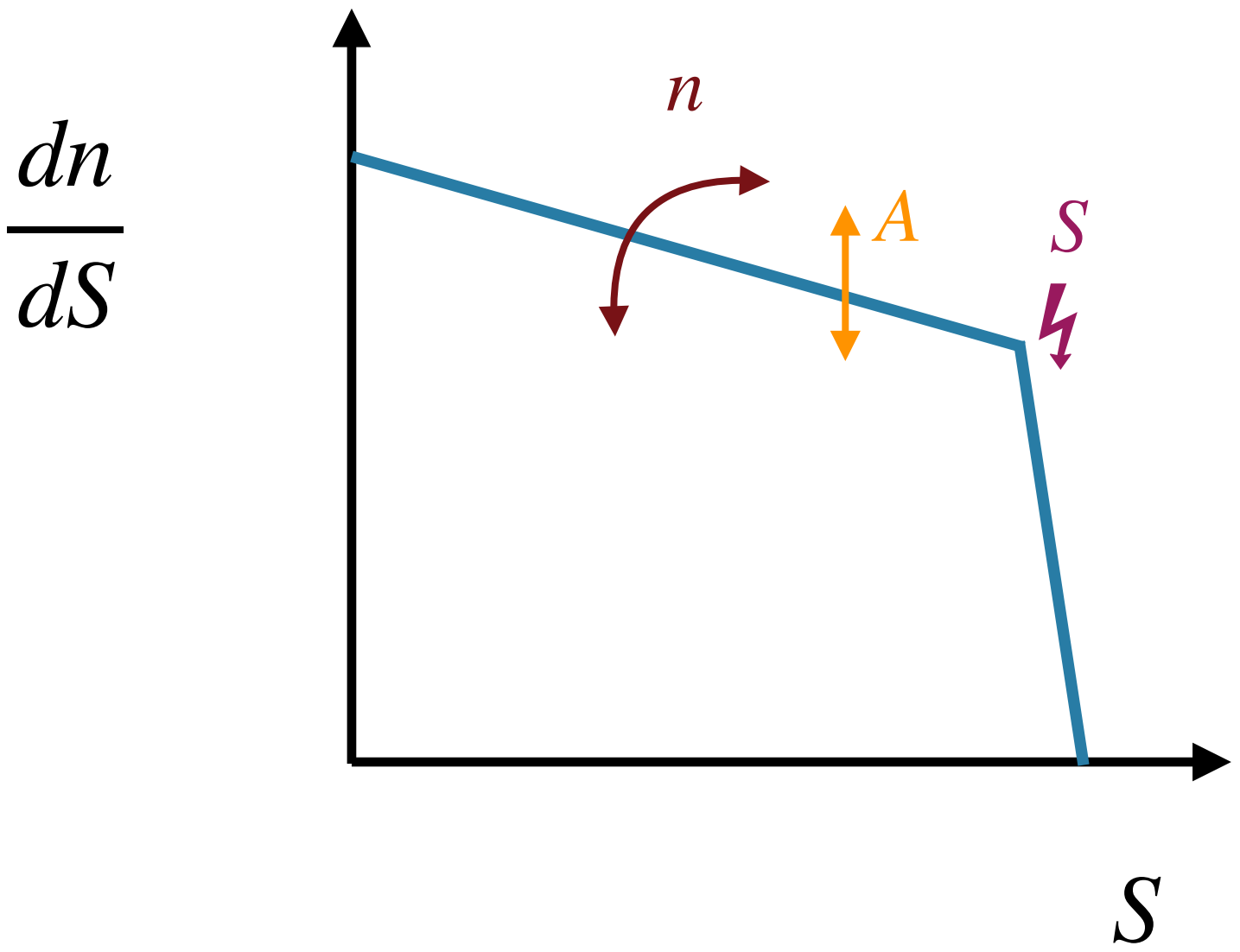


# Modeling PS populations in $\gamma$ -ray data

## Parameters of interest

*PS population properties*

$$\theta = \{A, n, S\}$$



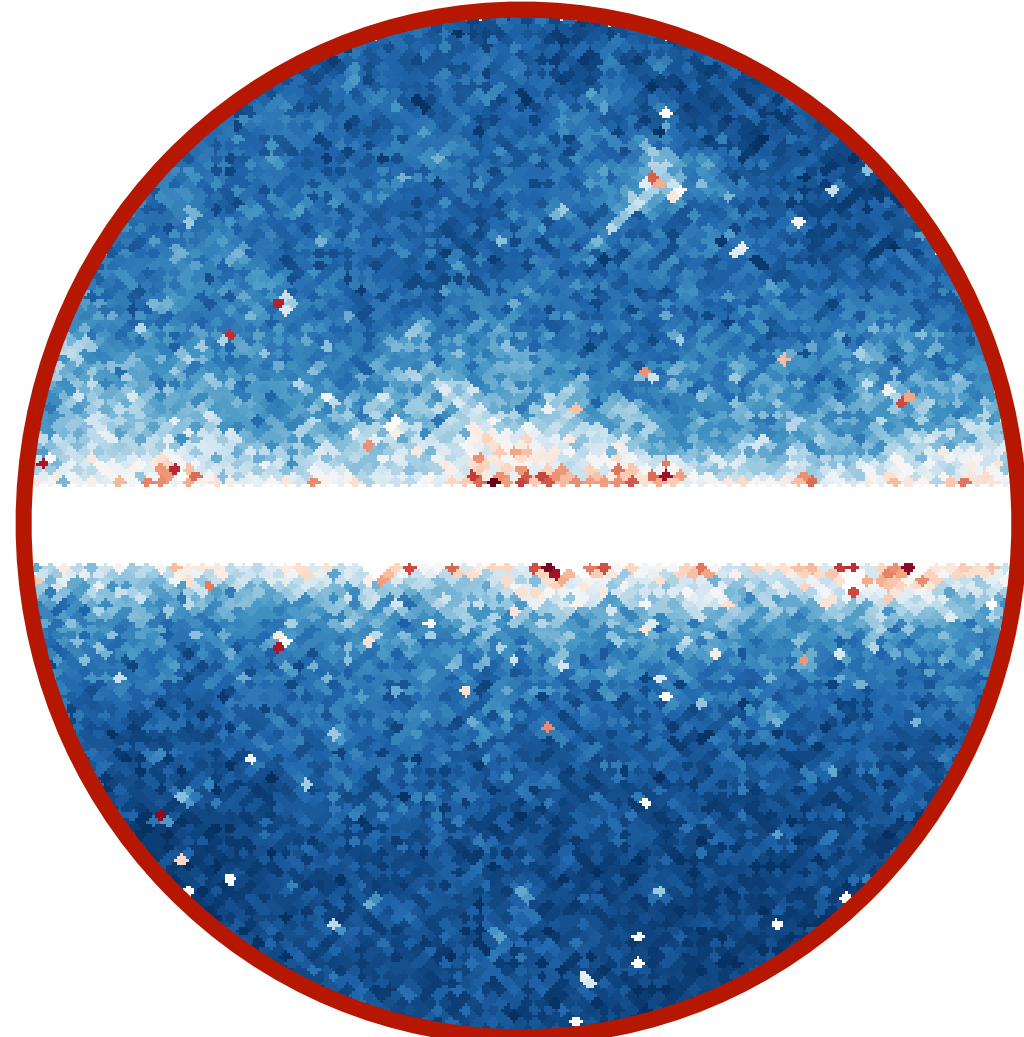
## Latent variables

*PS properties*

$$\{z_{PS,i}\}$$

## Observables

*Gamma-ray image  $x$*

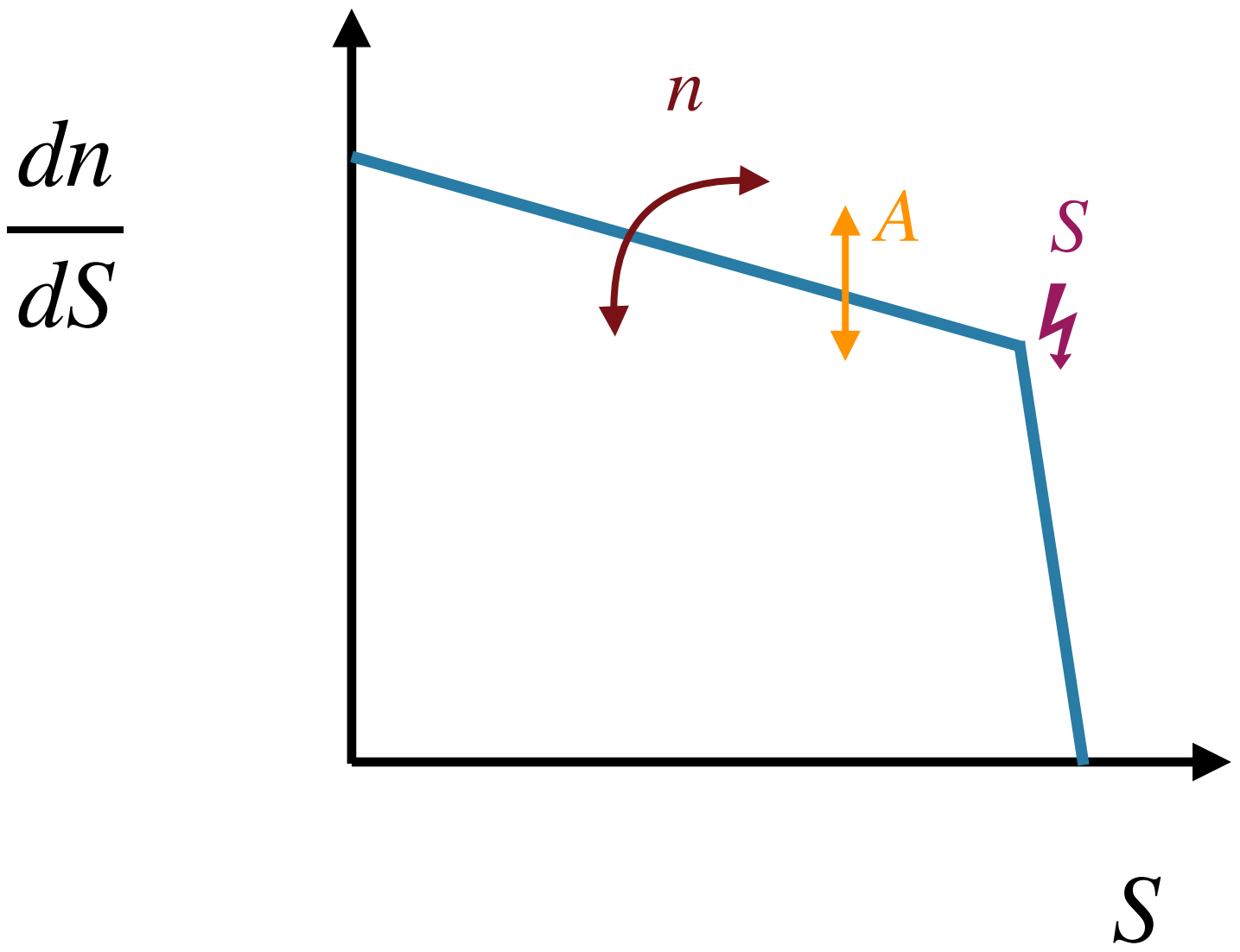


# Modeling PS populations in $\gamma$ -ray data

Parameters of interest

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Latent variables

*PS properties*

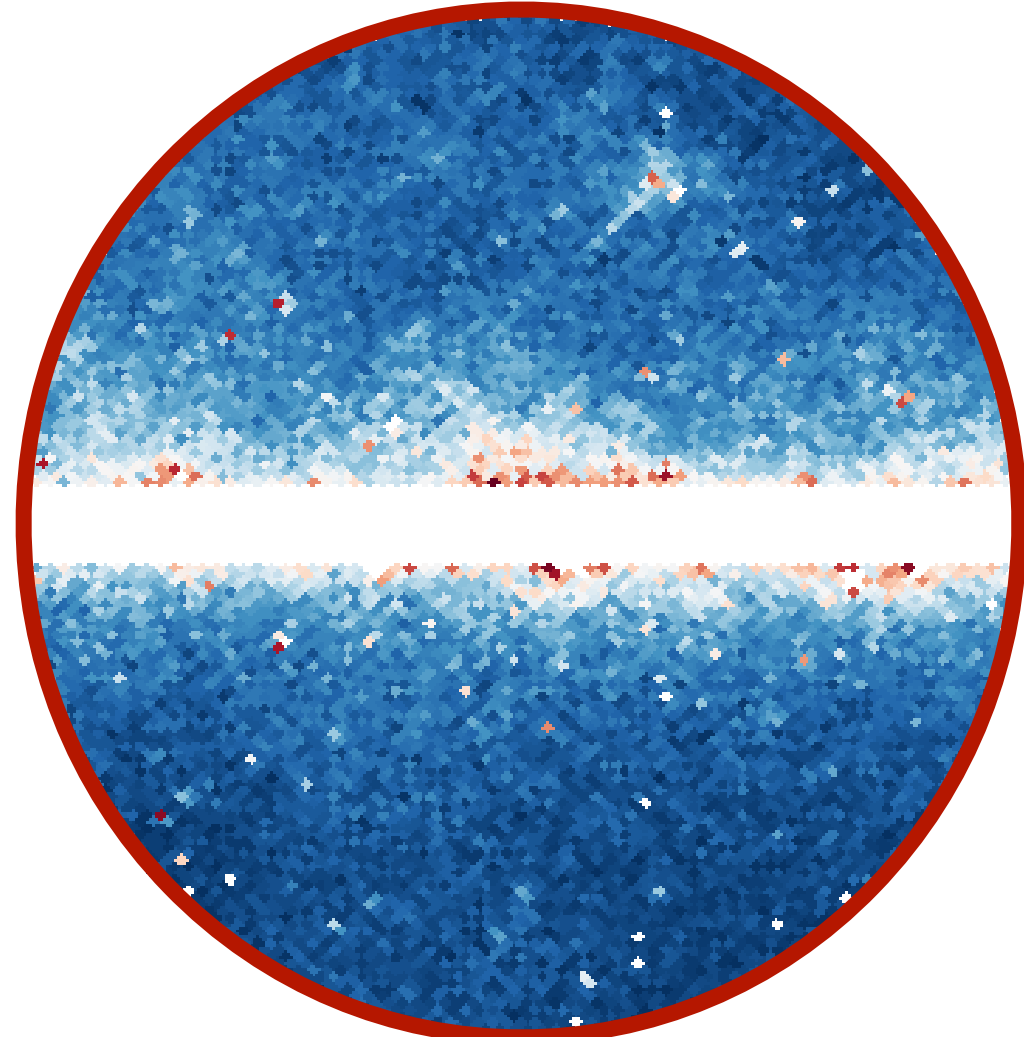
$$\{z_{PS,i}\}$$

Prediction (Simulation)

$$p(x, z | \theta)$$

Observables

*Gamma-ray image  $x$*

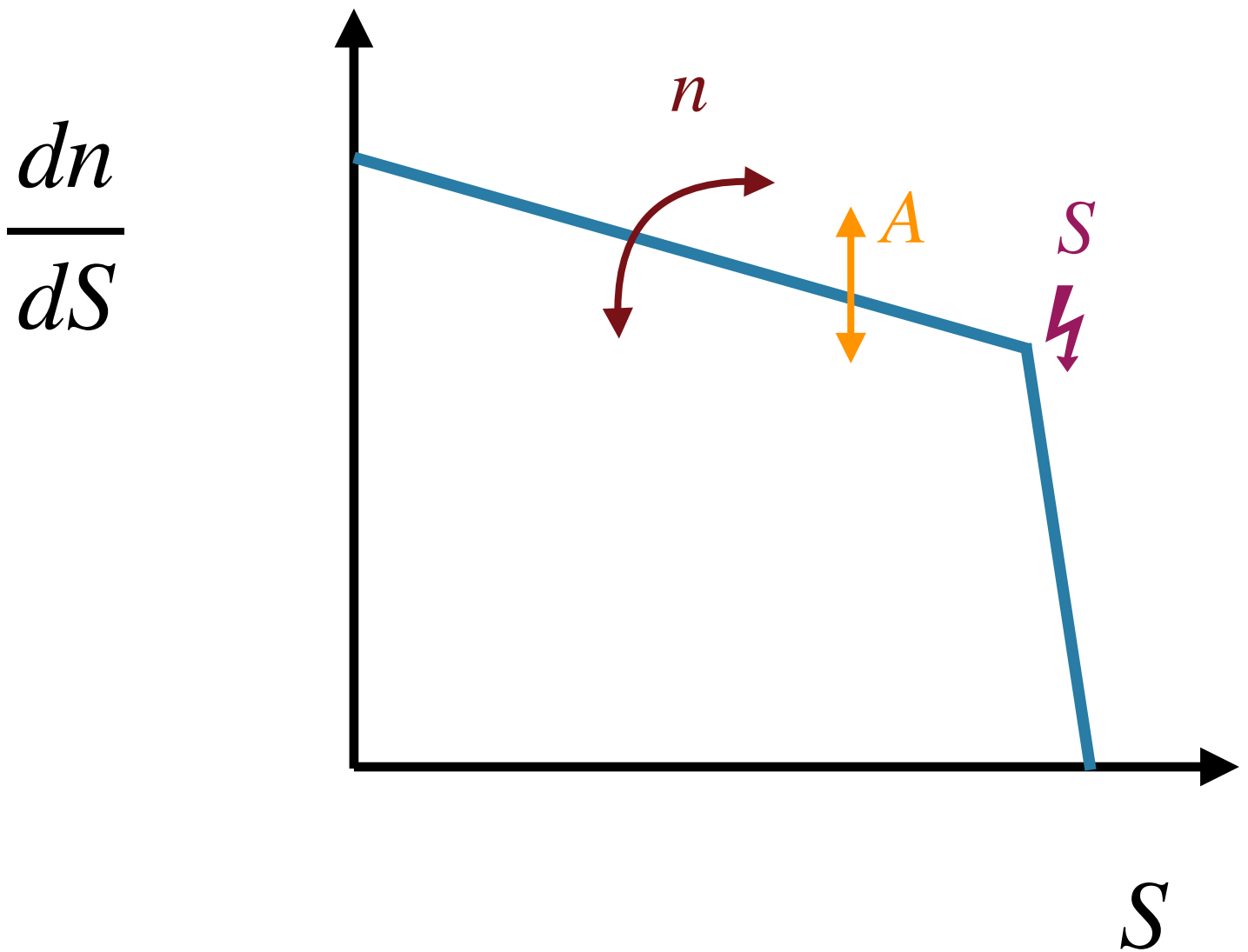


# Modeling PS populations in $\gamma$ -ray data

## Parameters of interest

*PS population properties*

$$\theta = \{A, n, S\}$$



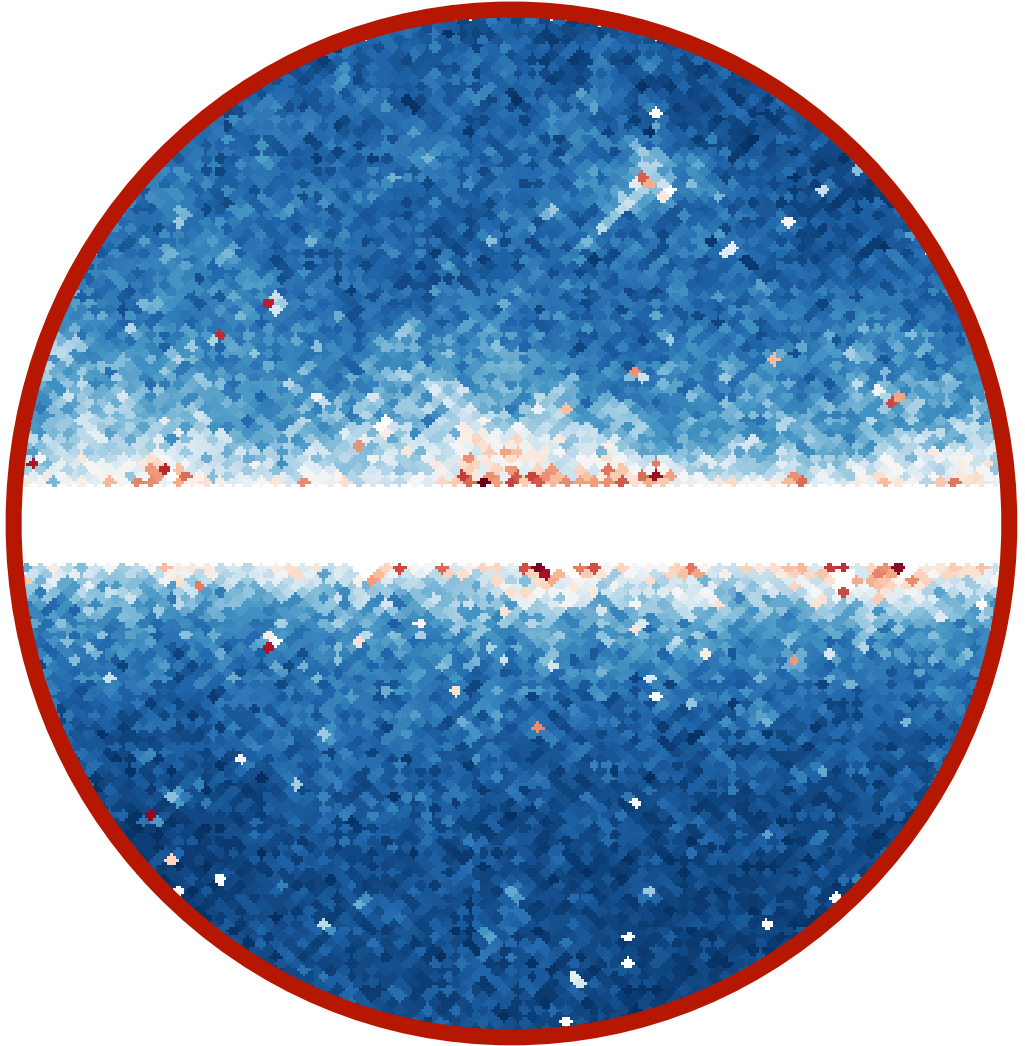
## Latent variables

*PS properties*

$$\{z_{PS,i}\}$$

## Observables

*Gamma-ray image  $x$*



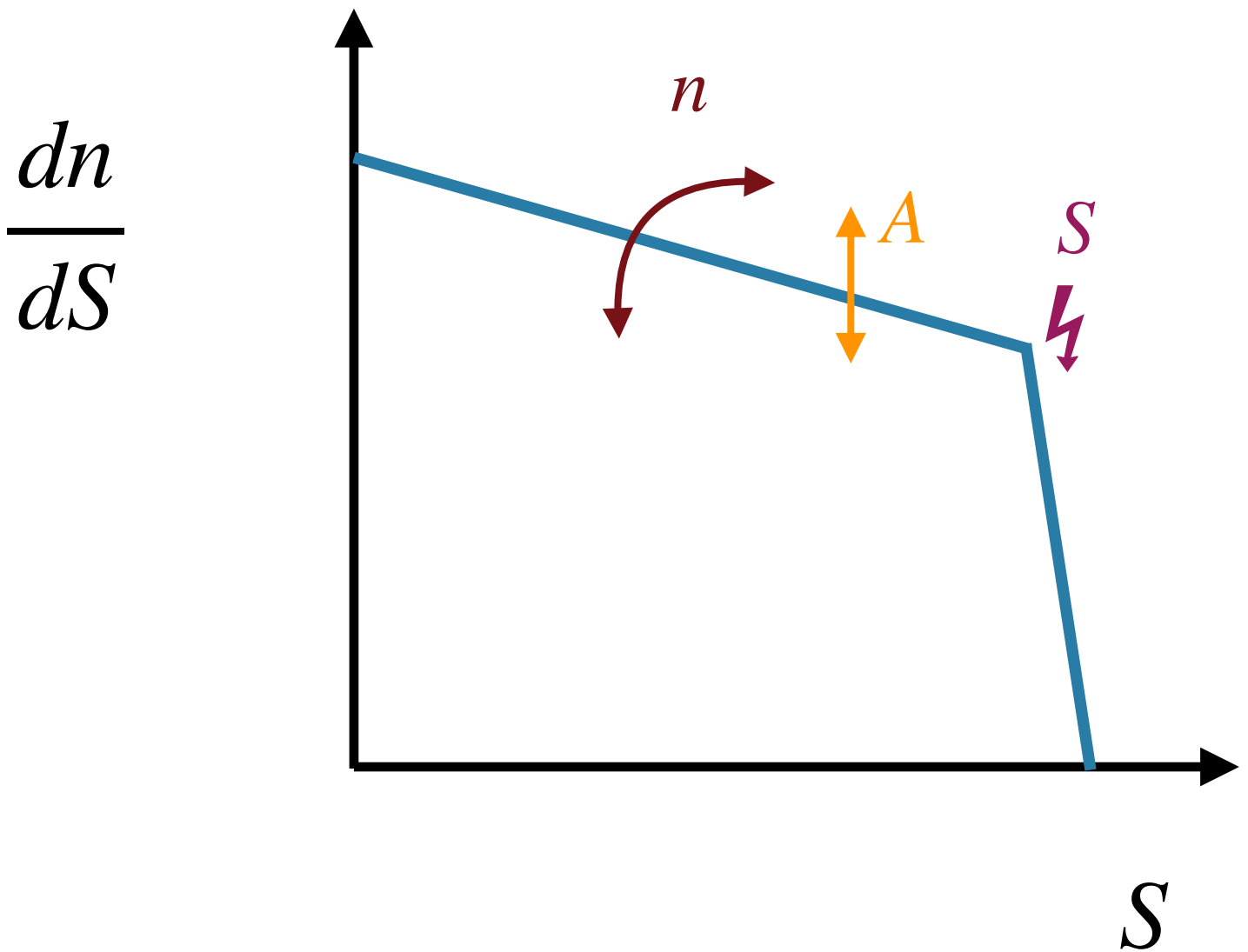
$$p(x | \theta) = \int dz p(x, z | \theta)$$

# Modeling PS populations in $\gamma$ -ray data

## Parameters of interest

*PS population properties*

$$\theta = \{A, n, S\}$$



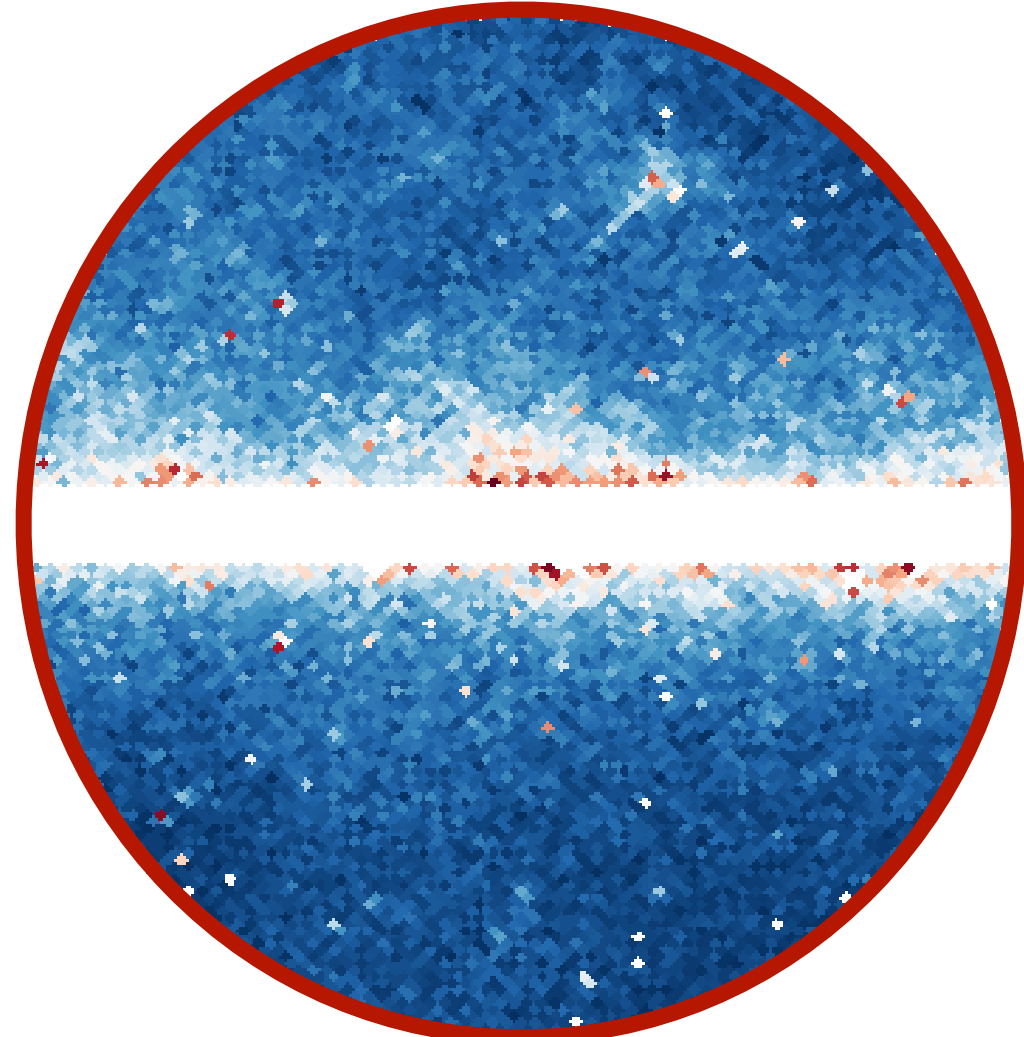
## Latent variables

*PS properties*

$$\{z_{PS,i}\}$$

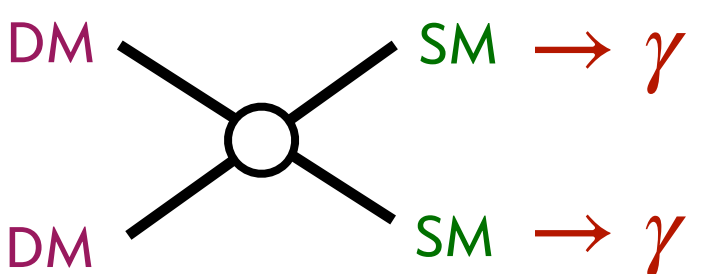
## Observables

*Gamma-ray image  $x$*

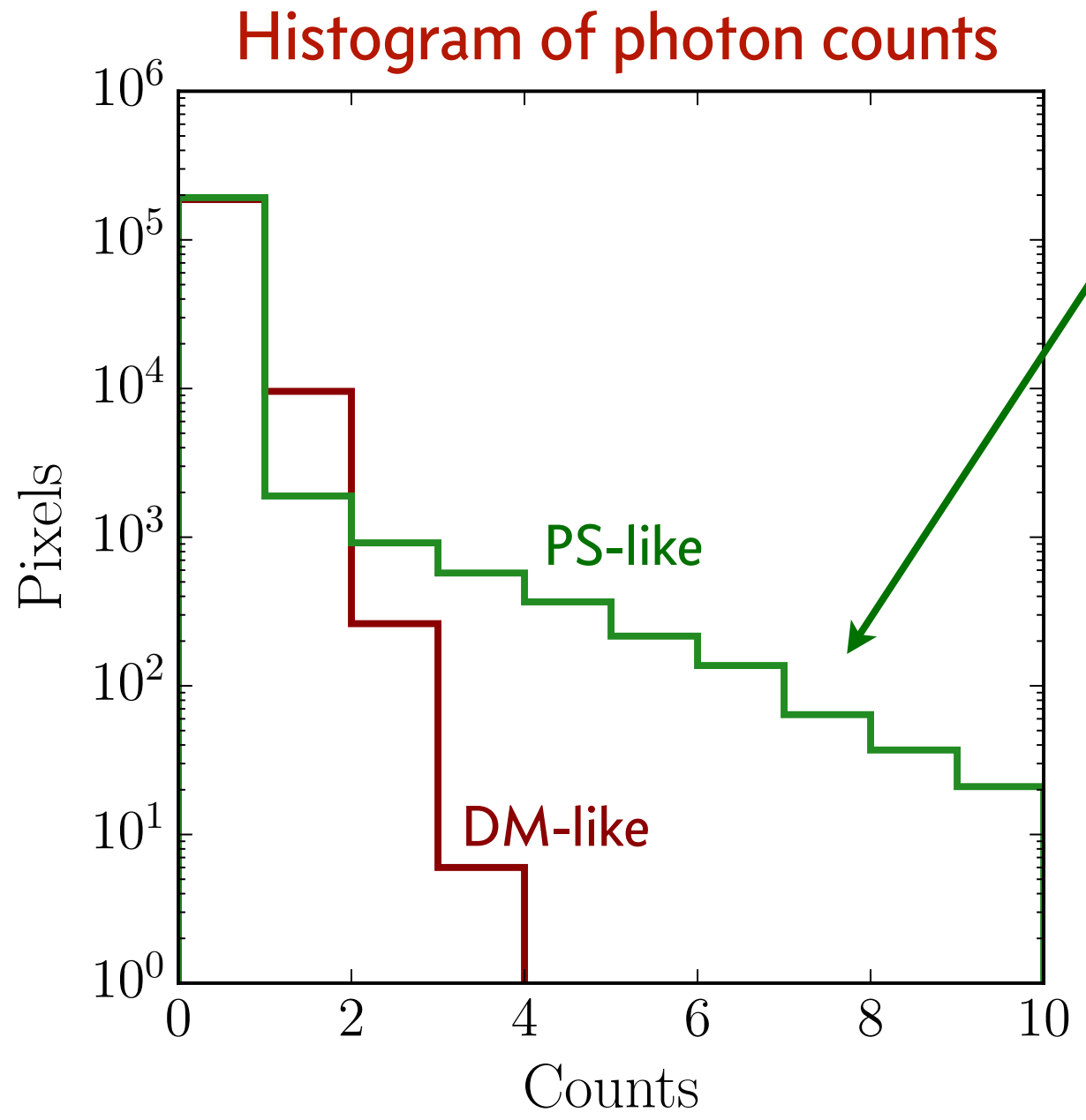
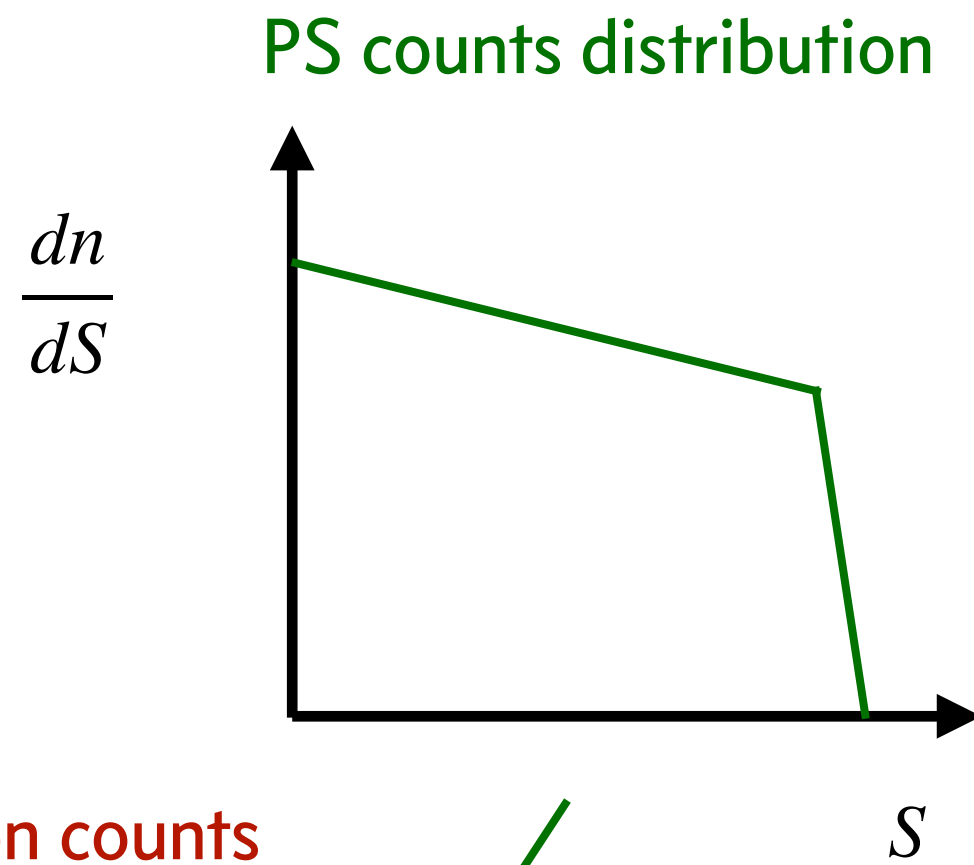
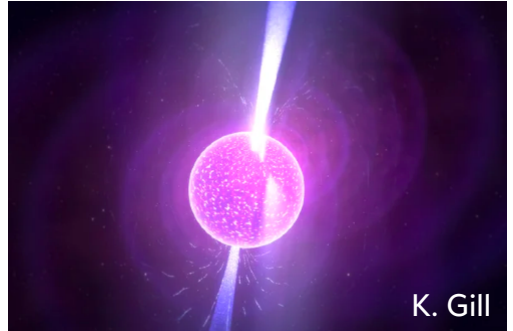
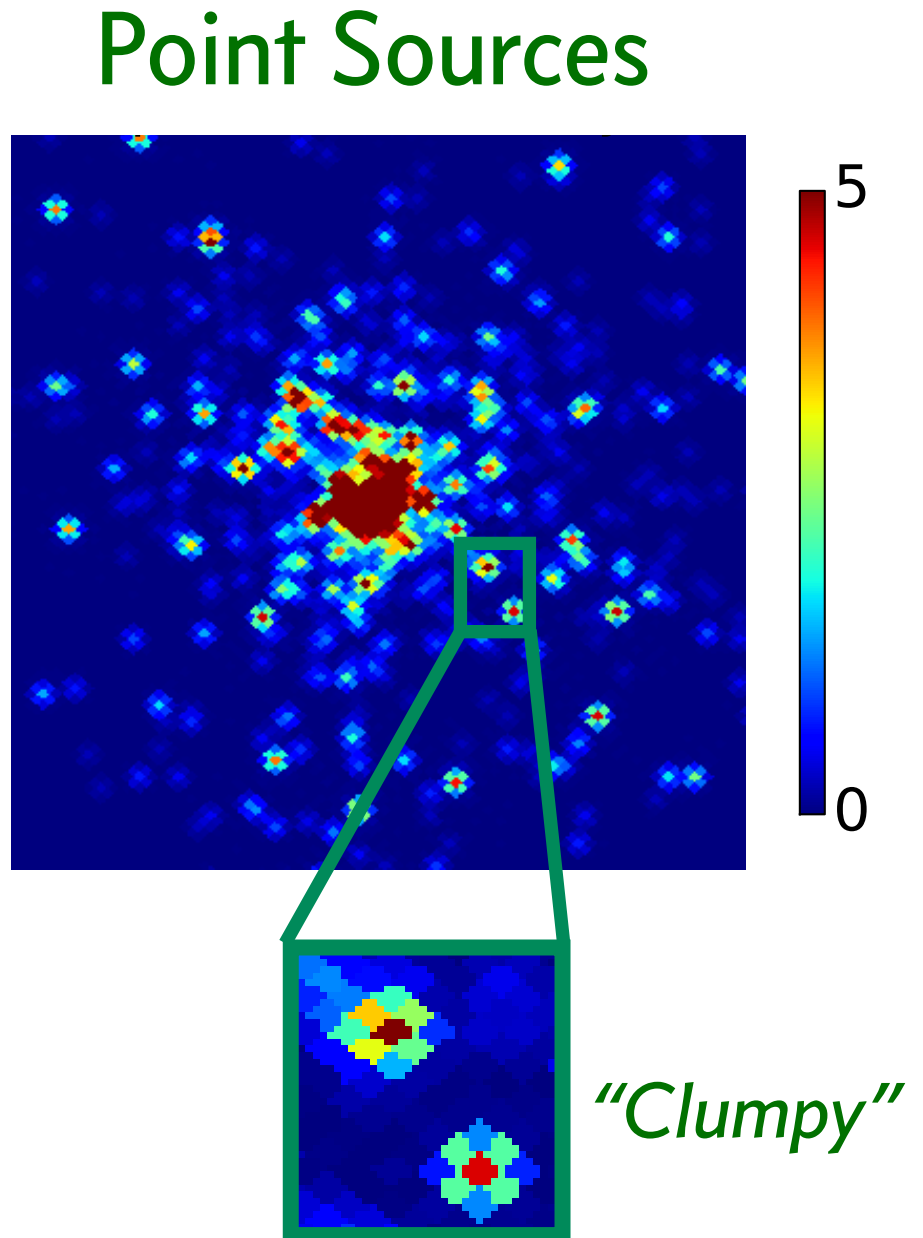
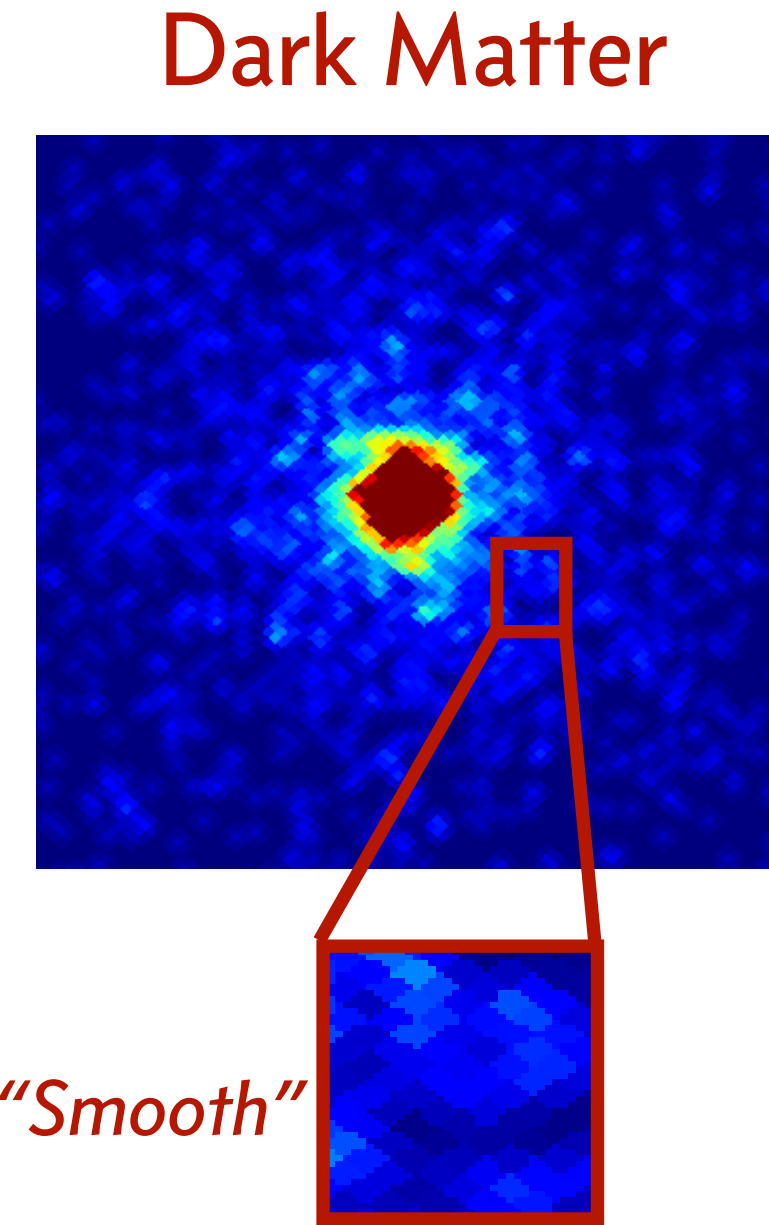


$$p(x | \theta) = \int dz p(x, z | \theta)$$

# Distinguishing DM from PS with the 1-point PDF

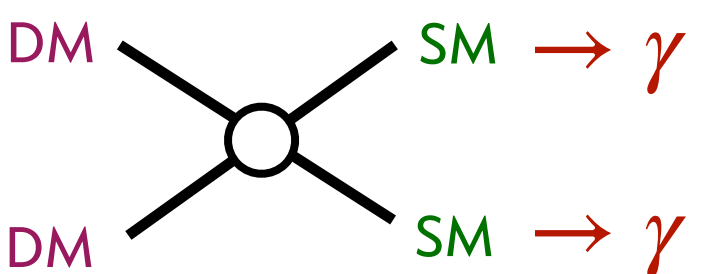


Lee et al [JCAP 2015]



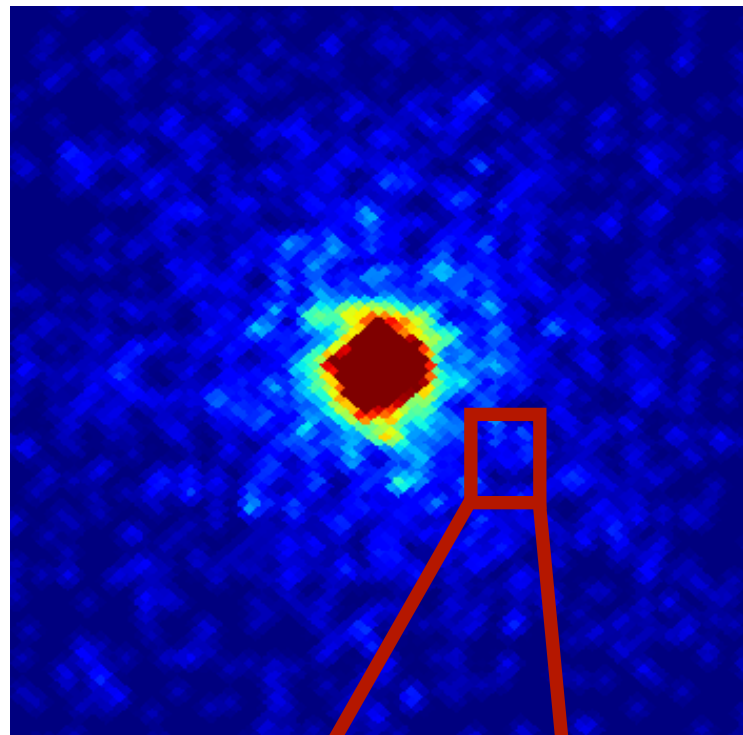


# Distinguishing DM from PS with the 1-point PDF

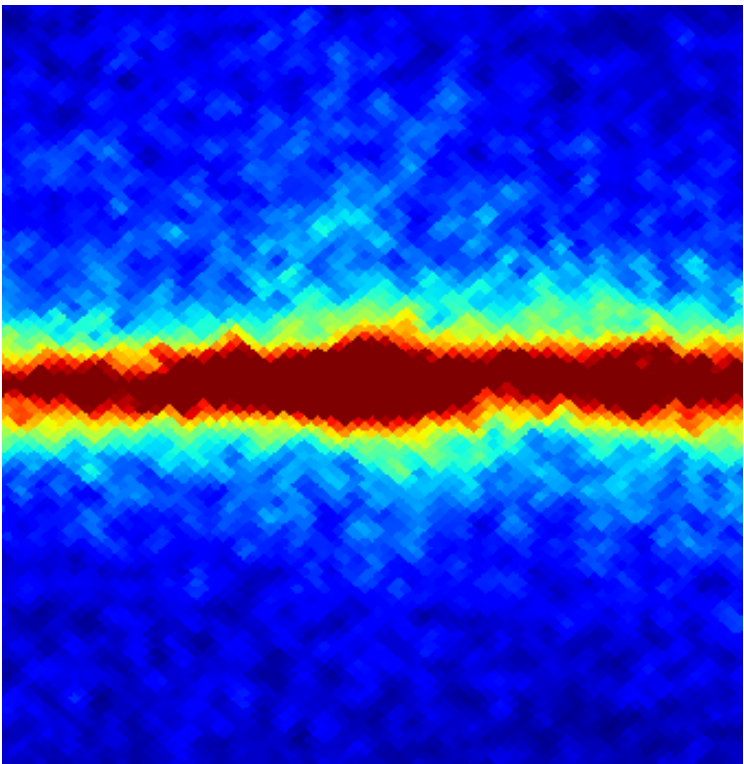


Lee et al [JCAP 2015]

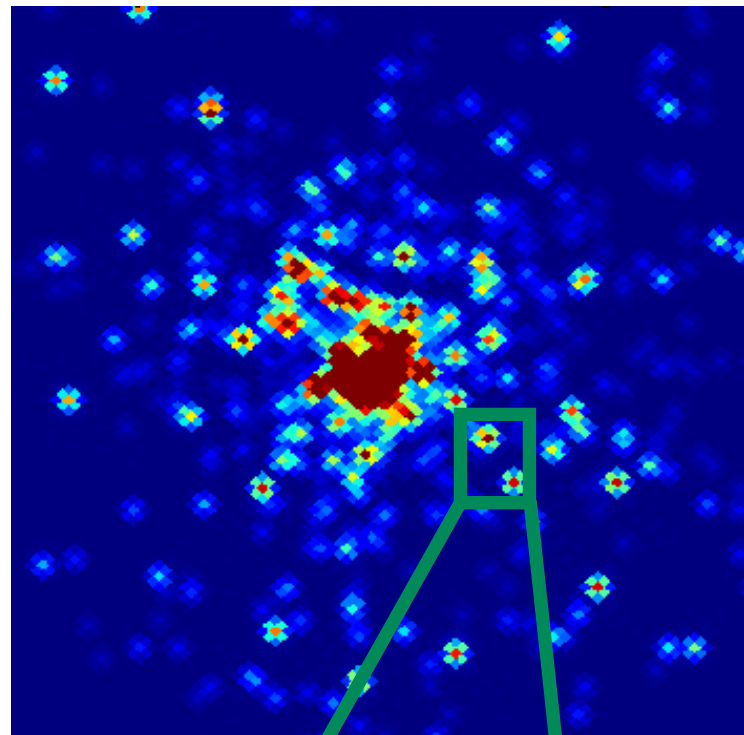
Dark Matter



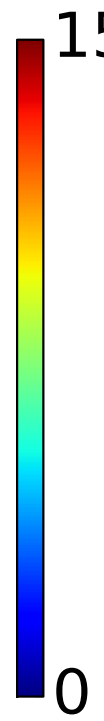
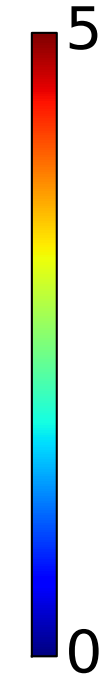
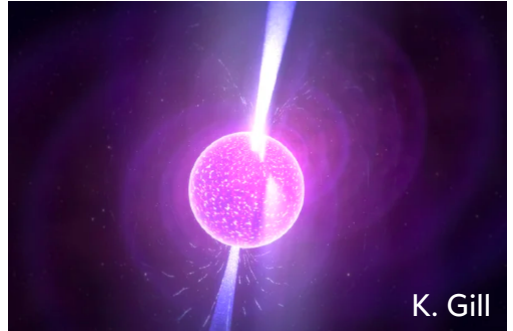
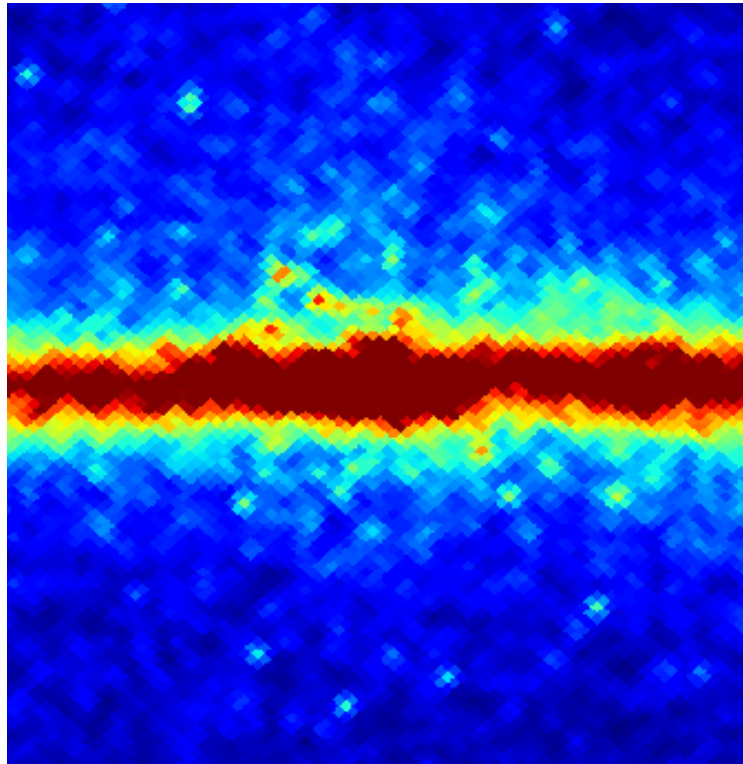
"Smooth"



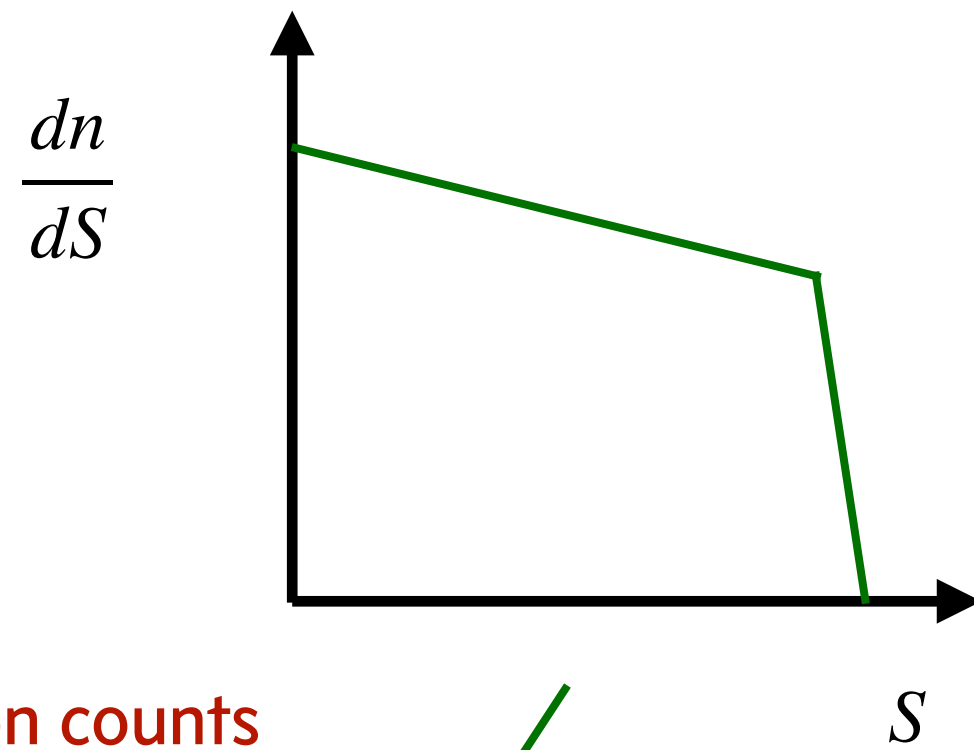
Point Sources



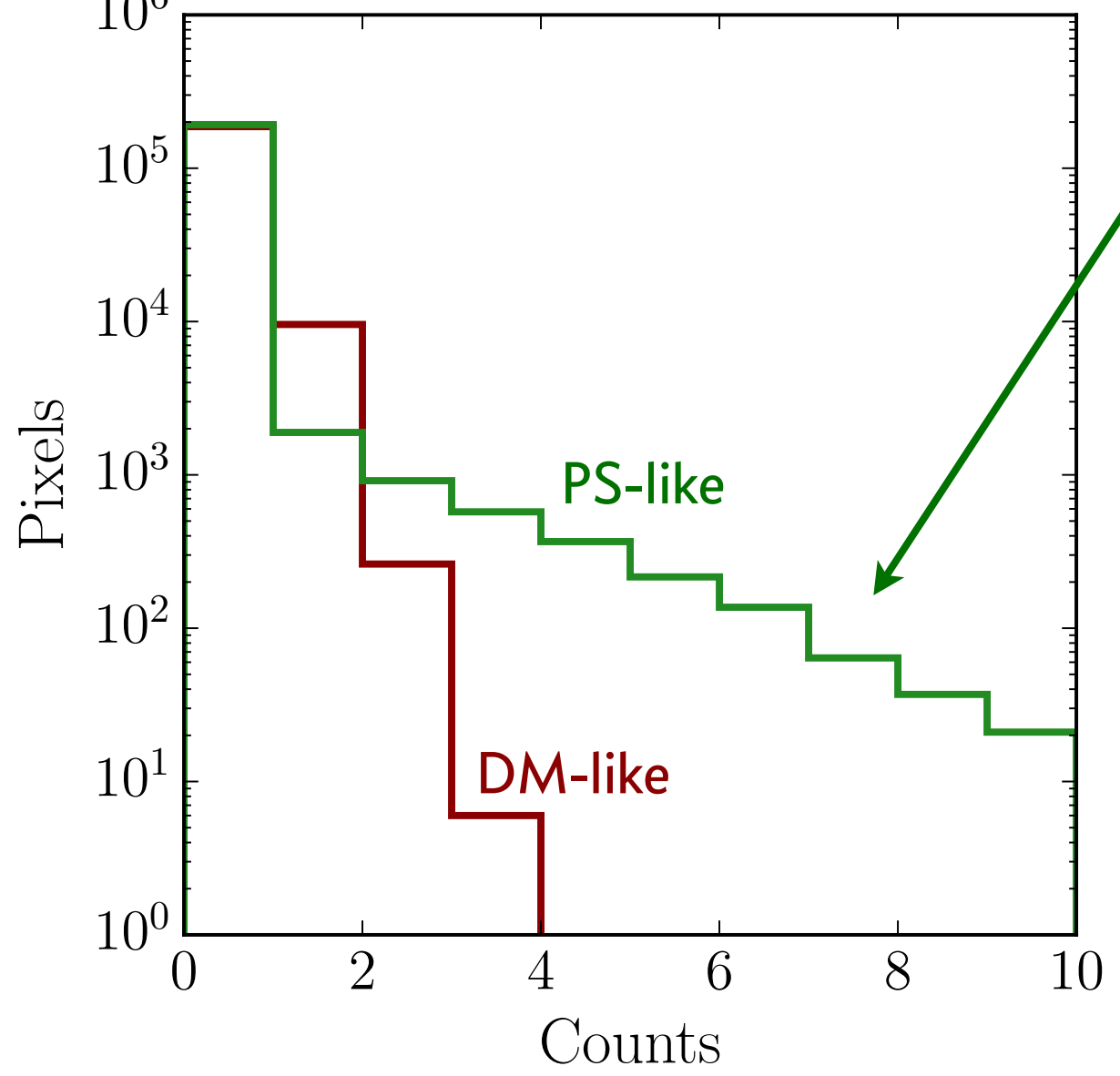
"Clumpy"



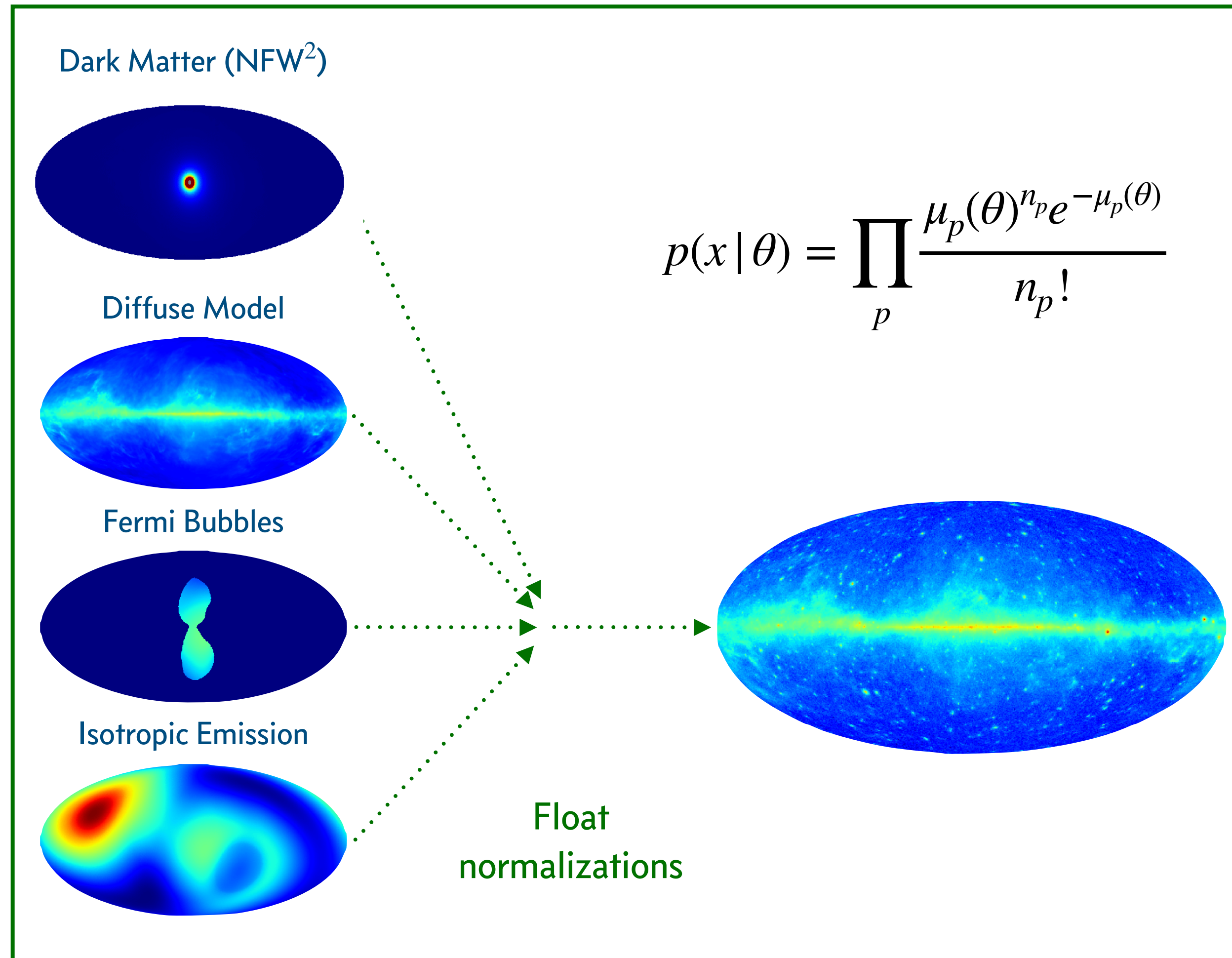
PS counts distribution



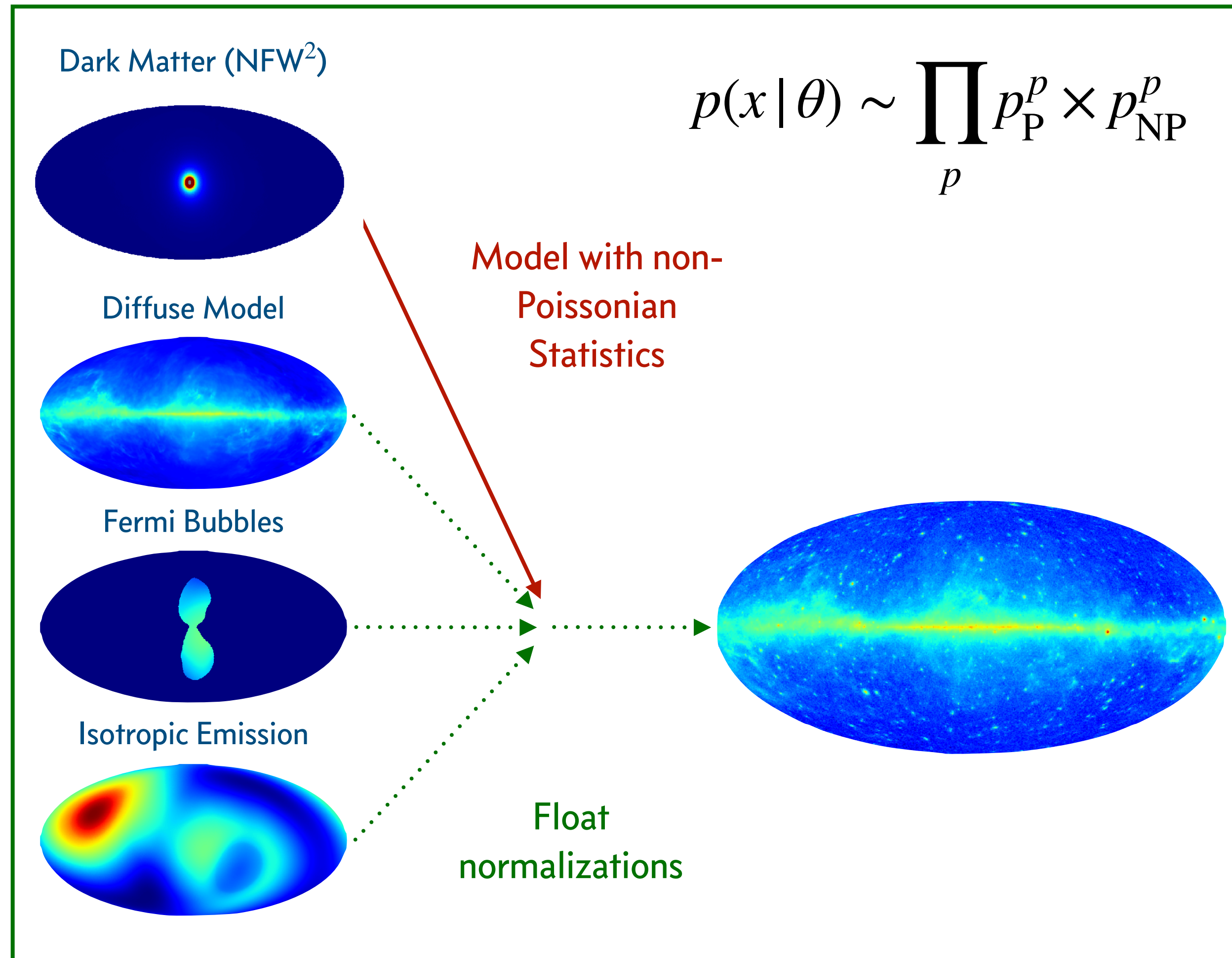
Histogram of photon counts



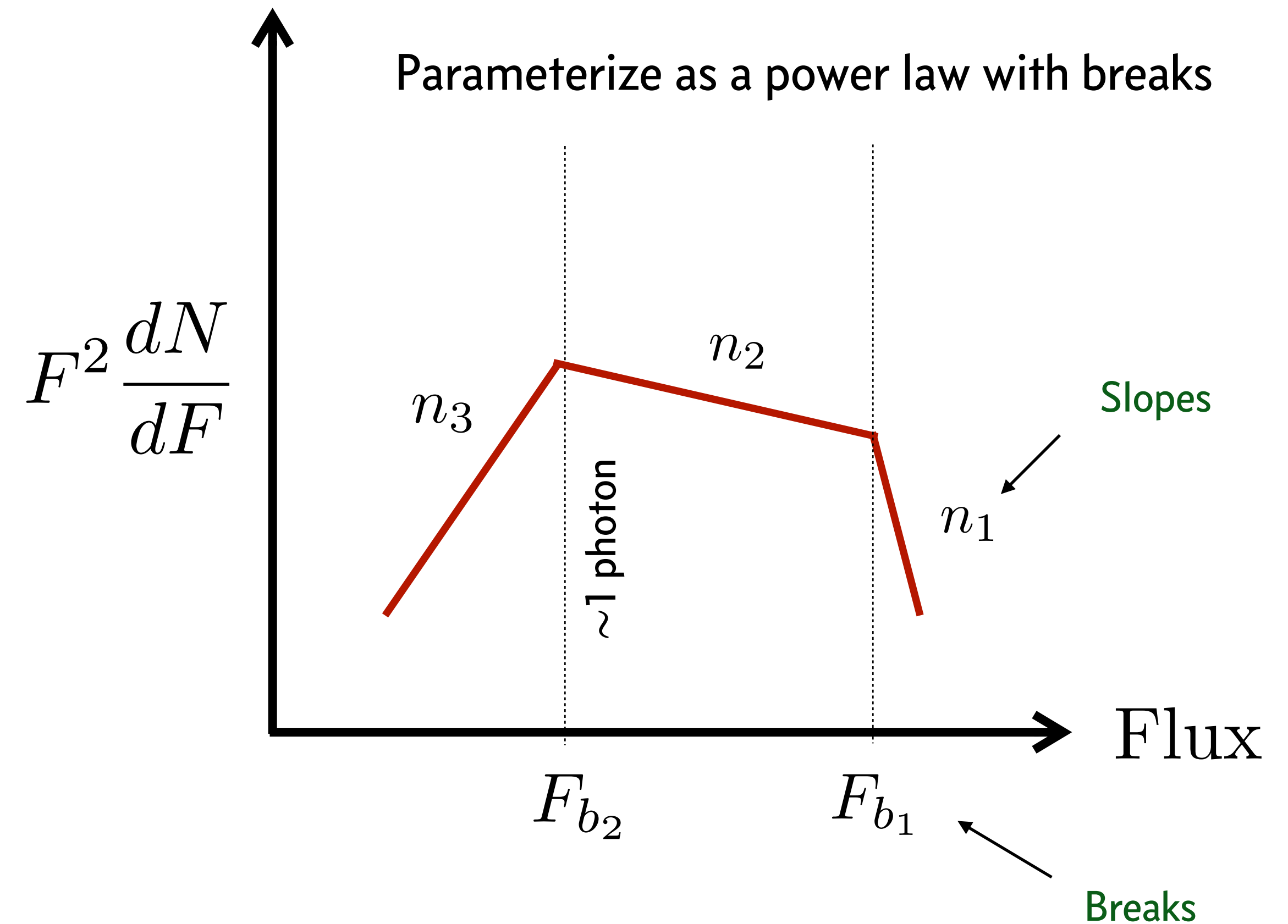
# Poissonian template fitting



# Non-Poissonian Template Fitting (NPTF)

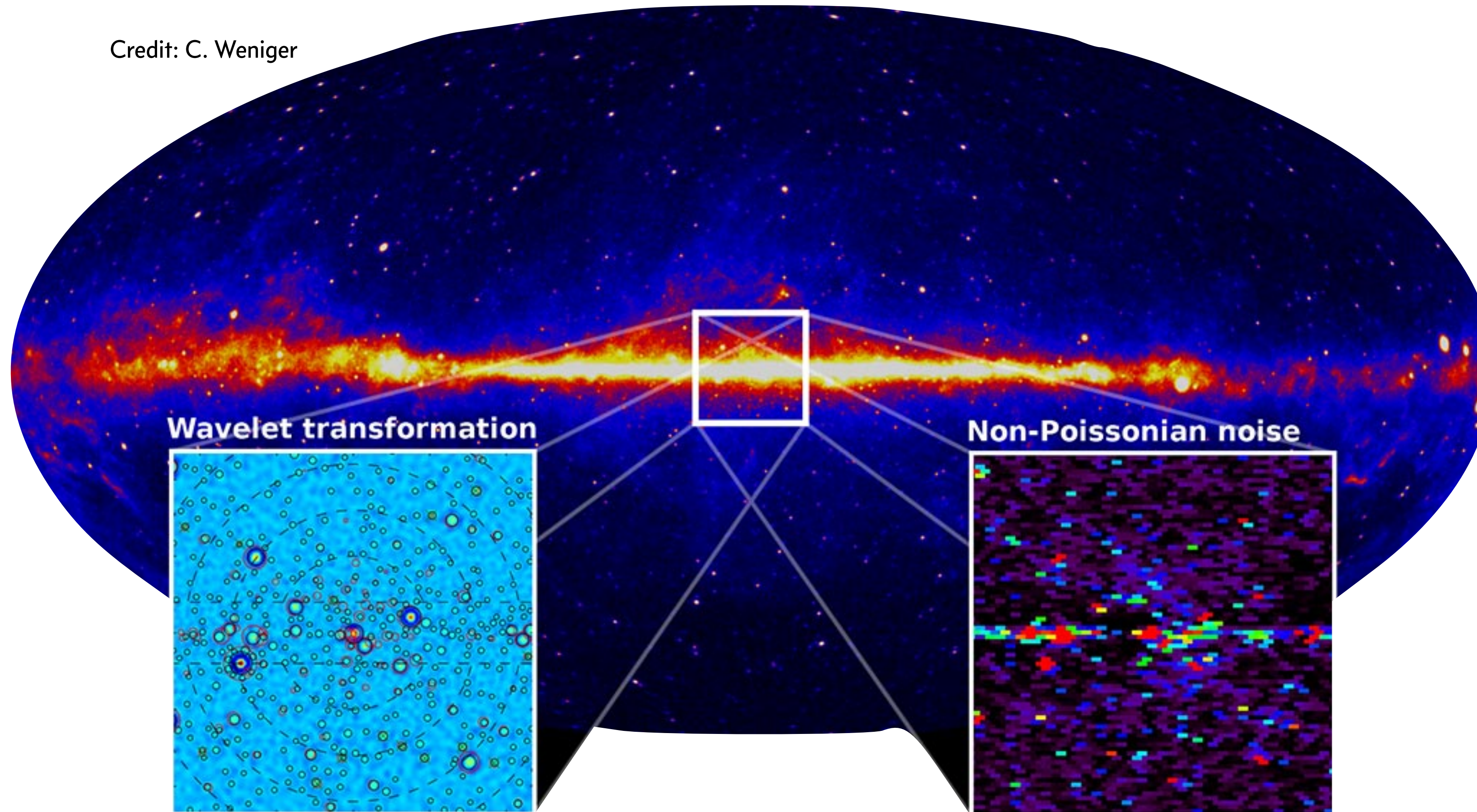


Source-count distribution gives number of sources in a given pixel with a flux between  $F$  and  $F+dF$



# Status c.2015: Evidence for unresolved point sources

Credit: C. Weniger

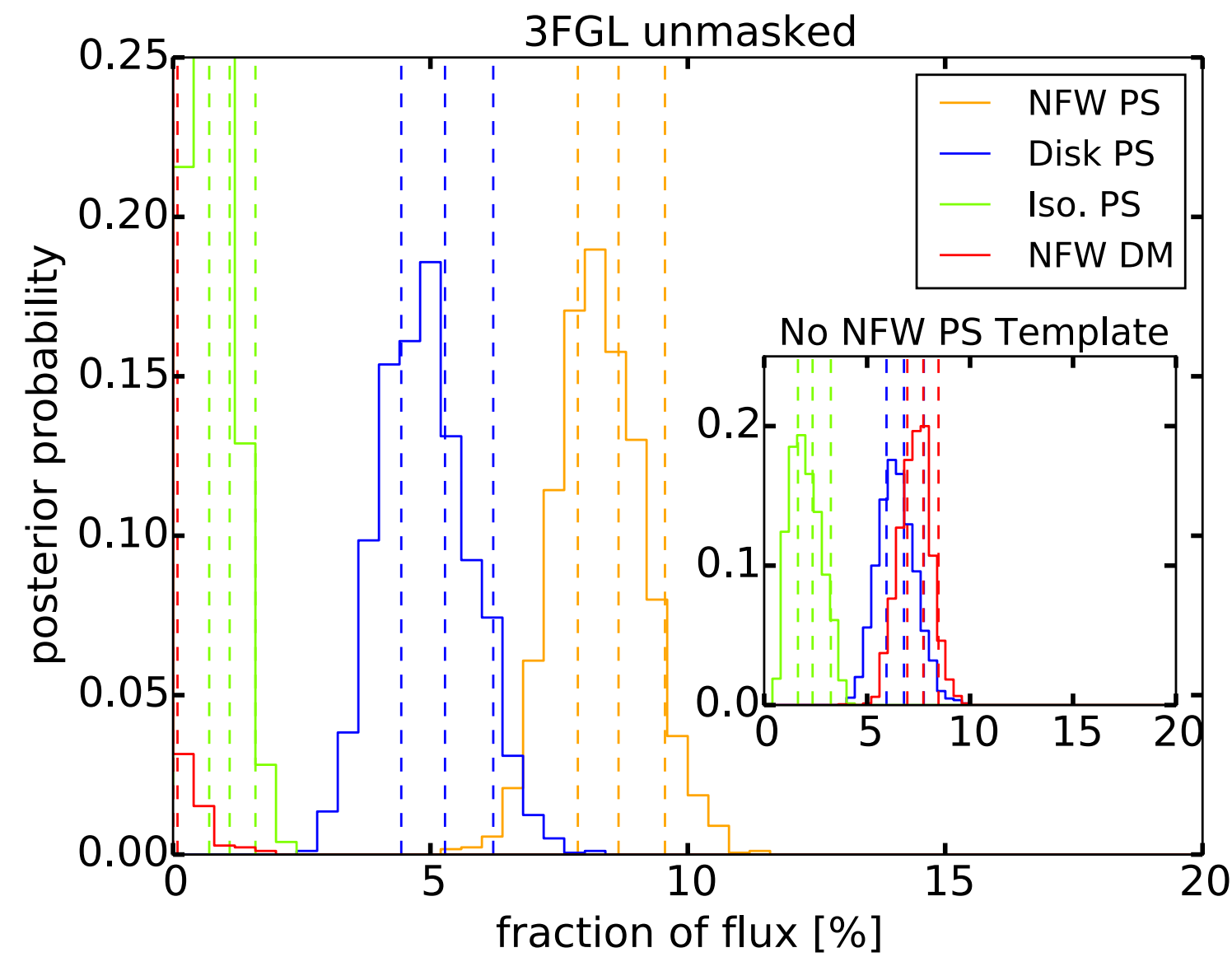
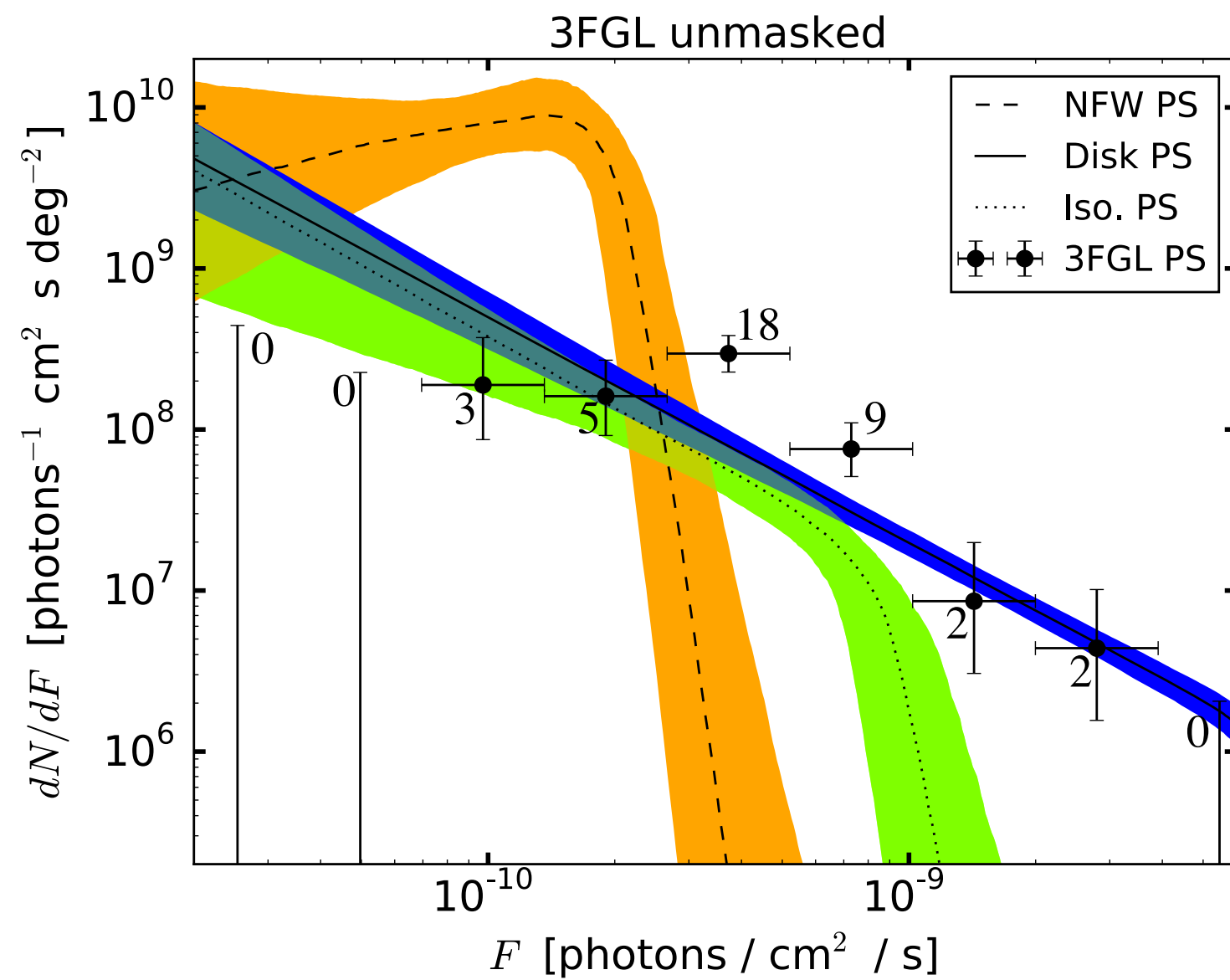
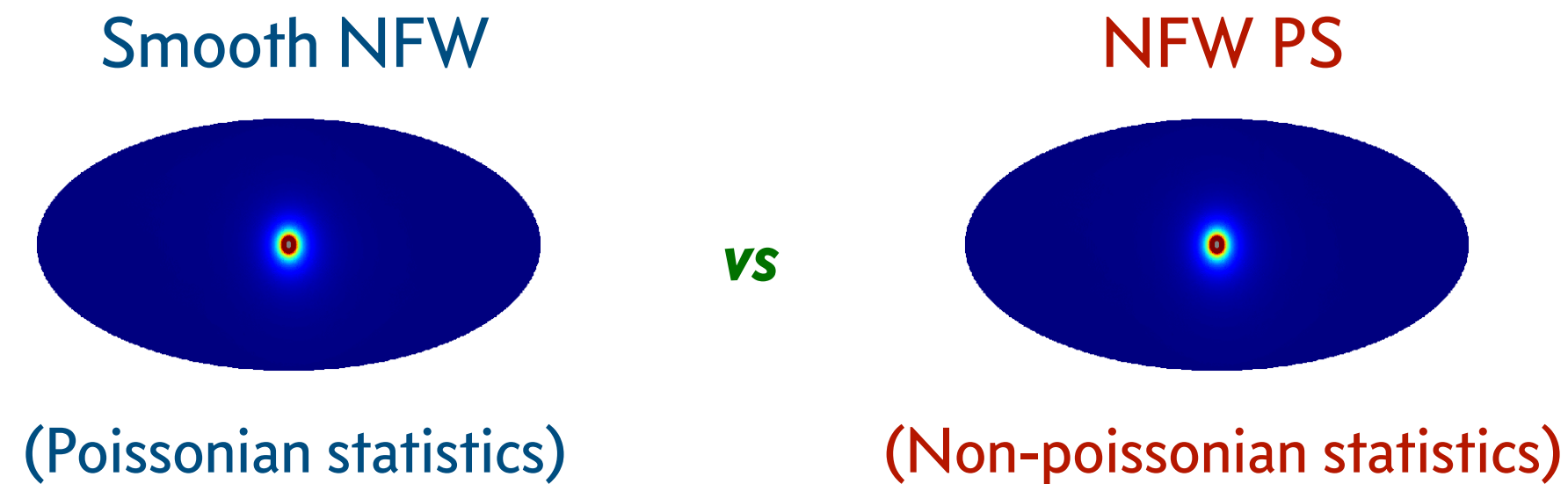


Bartels et al [PRL 2016]

Lee et al [PRL 2016]

# NPTF analysis of Lee et al (c. 2015)

Which model provides a better fit to the data?



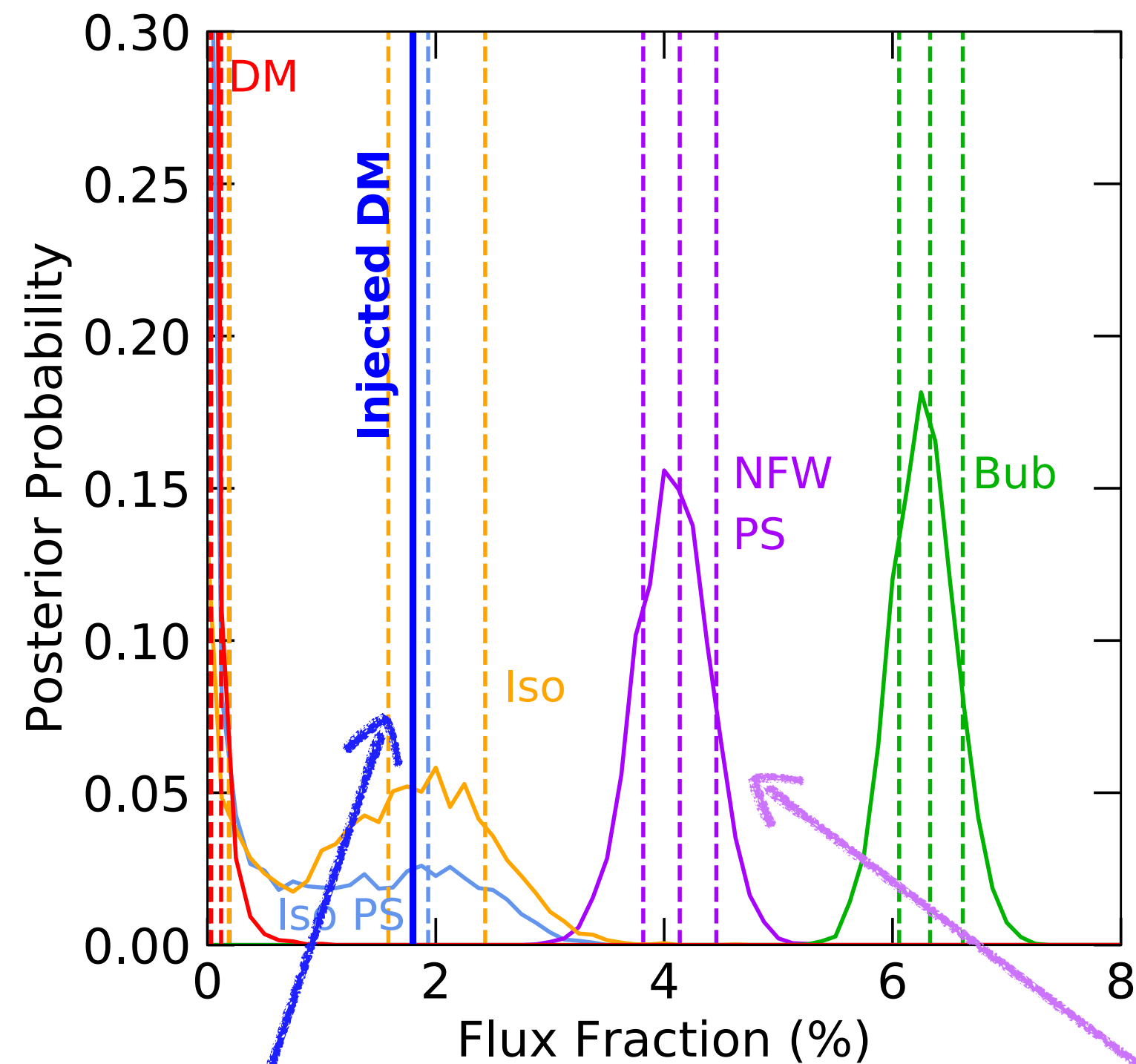
- *Excess flux is entirely accounted for by the NFW PS template*
- *Bayes factor in preference for NFW point sources is  $\sim 10^7$*

Lee et al [PRL 2016]

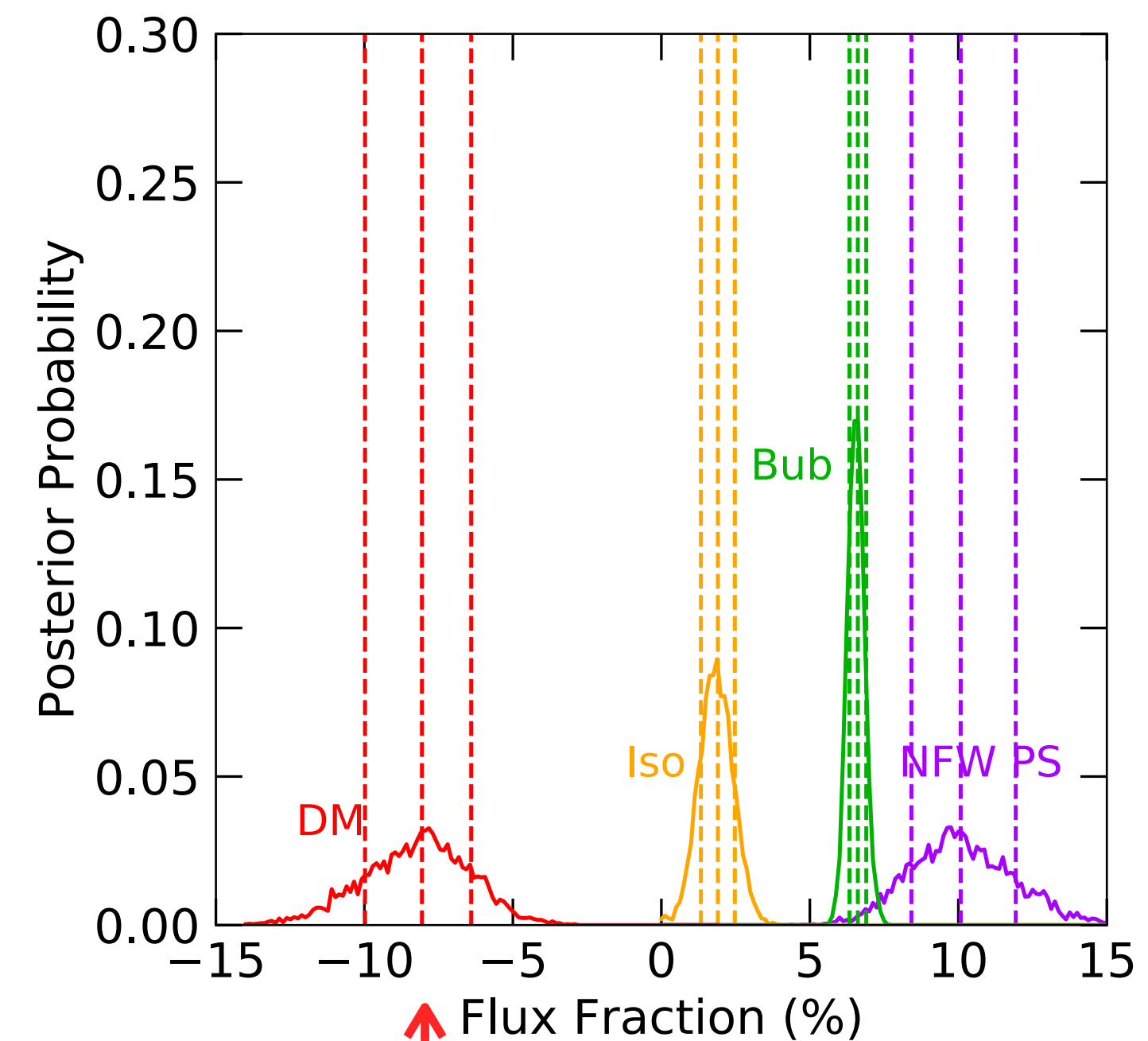
# Dark matter strikes back? (c. 2019)

Performed a closure test:

*Inject a DM signal onto the real data, then try to recover it with the NPTF pipeline*

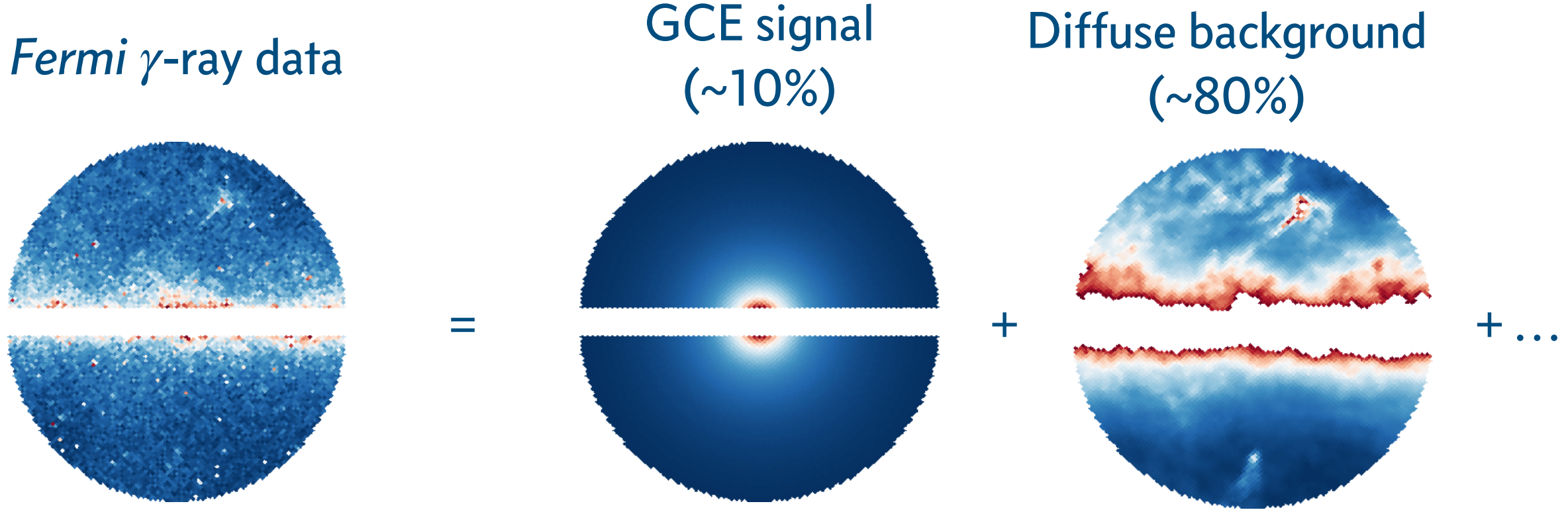


*Injected DM flux gets reconstructed as PSs*

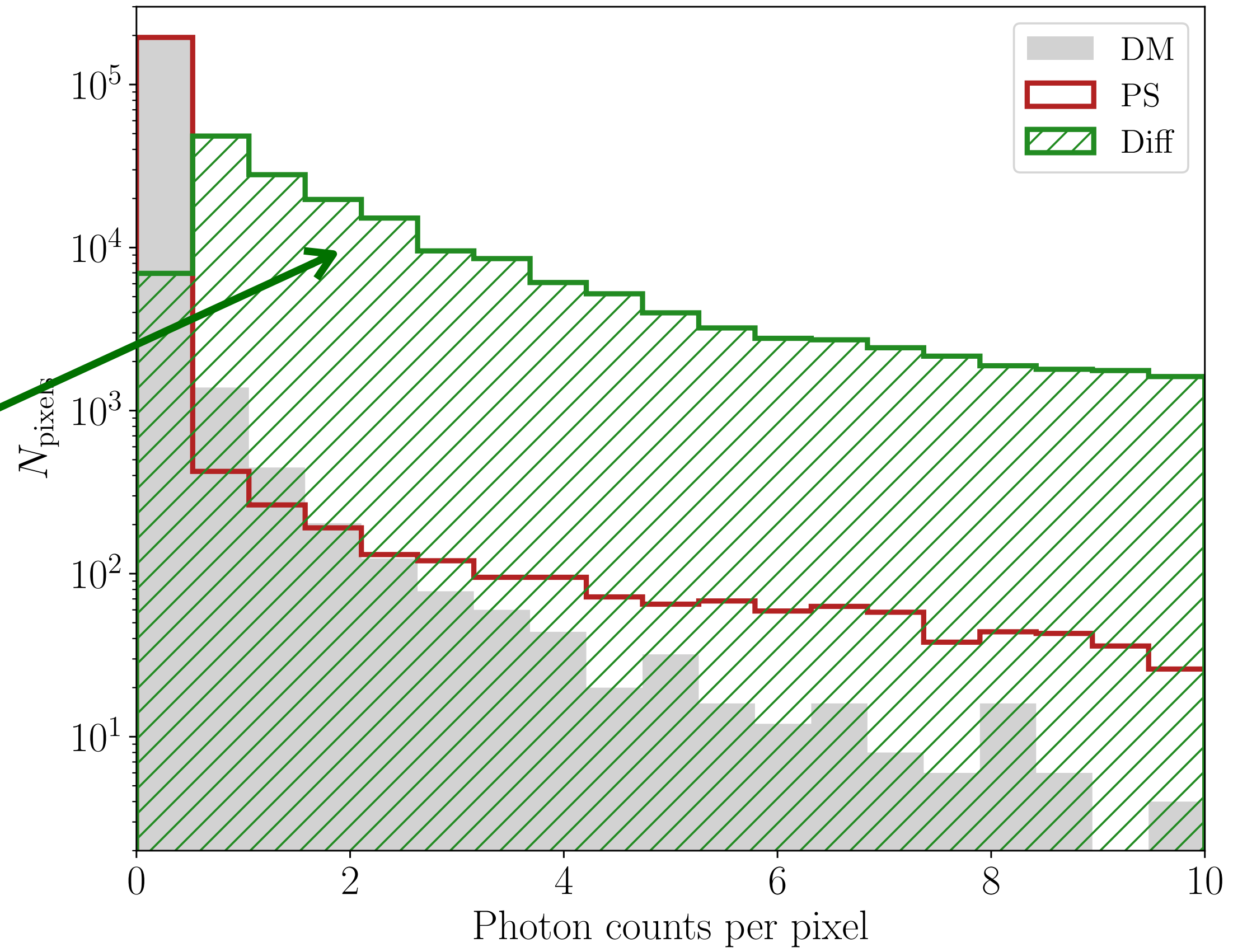


*DM flux can go negative if allowed to*

# What could go wrong?

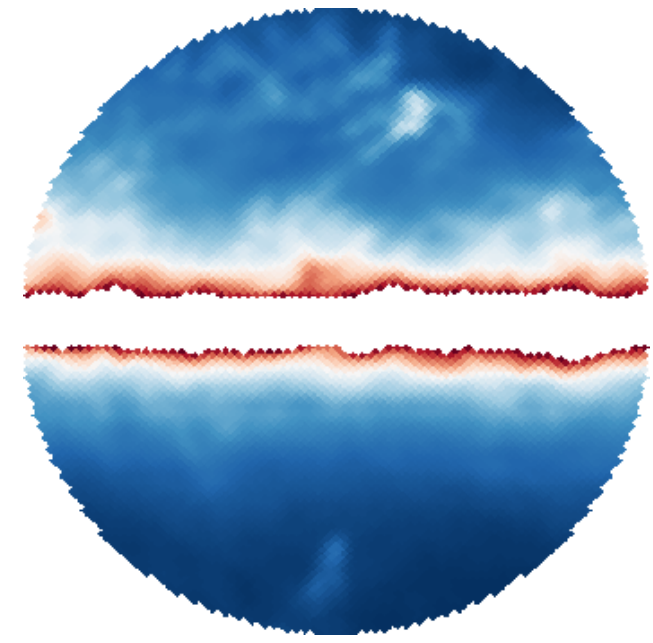


Diffuse foregrounds make up most of the observed emission in the Galactic Center

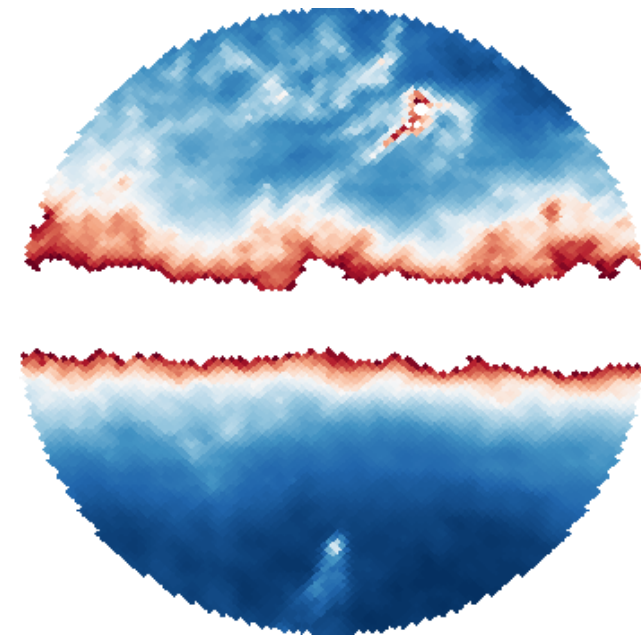


Not an error in the NPTF method!

# Better diffuse models



Background  
Model p6v11



Background  
"Model O"

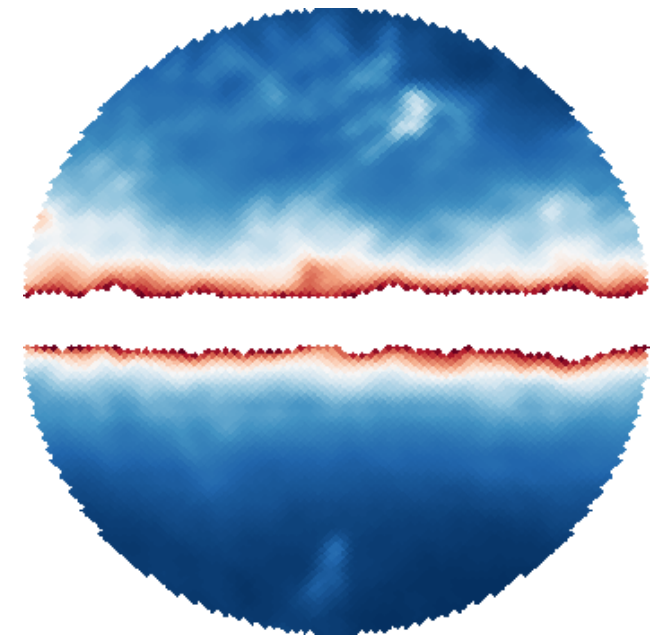
- *Updated gas tracers*
- *3D radiation field for IC*
- *Components fit in several Galactocentric rings*

Macias et al [JCAP 2019]

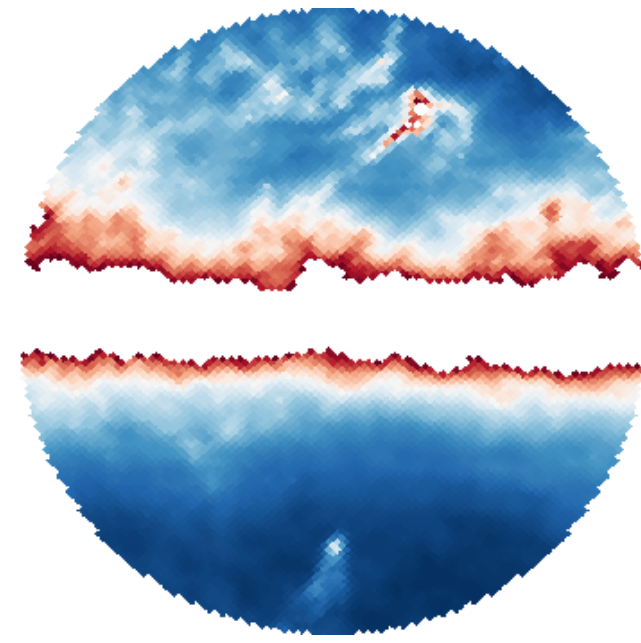
Macias et al [Nat. Ast. 2017]



# Better diffuse models



Background  
Model p6v11



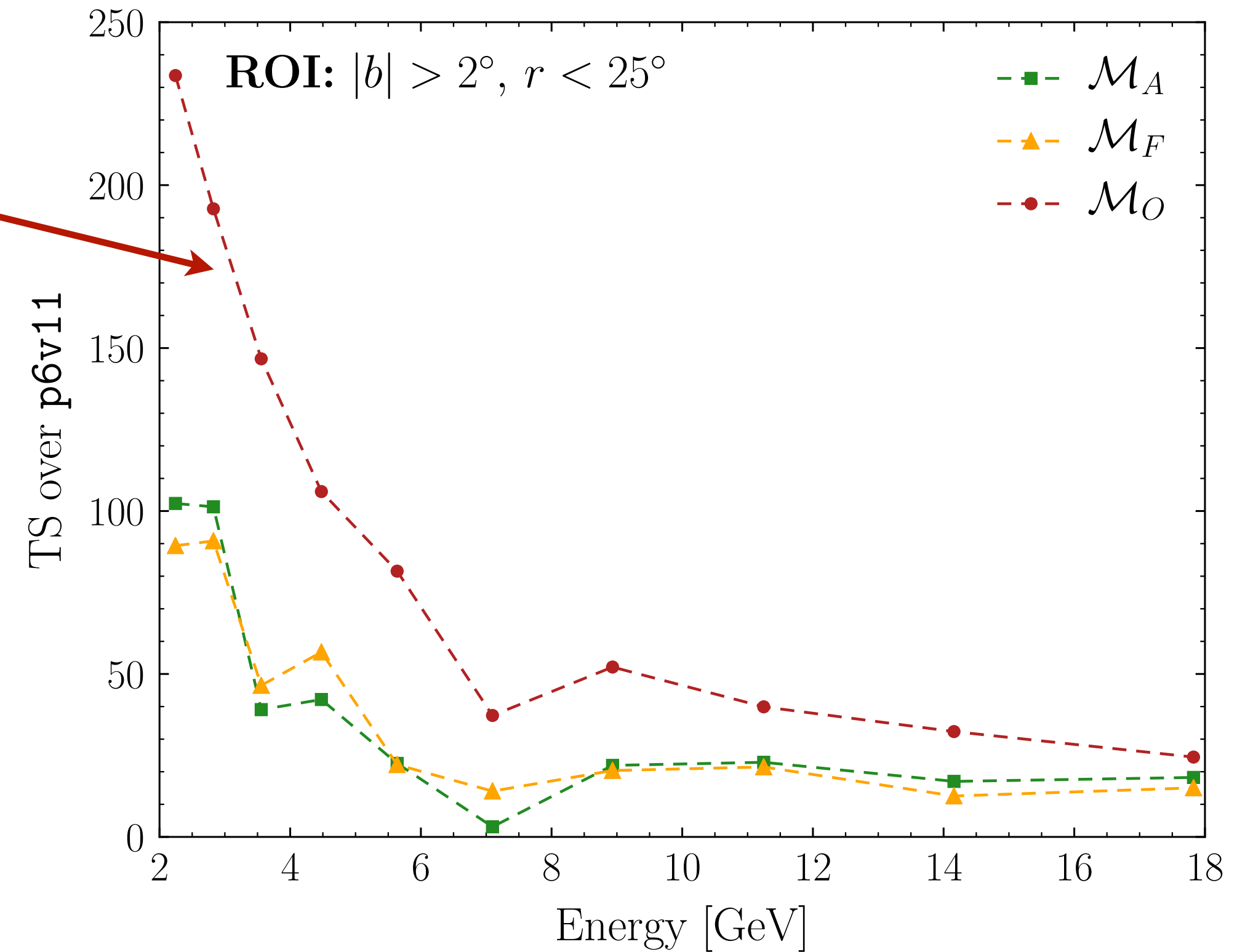
Background  
"Model O"

- Updated gas tracers
- 3D radiation field for IC
- Components fit in several Galactocentric rings

Macias et al [JCAP 2019]

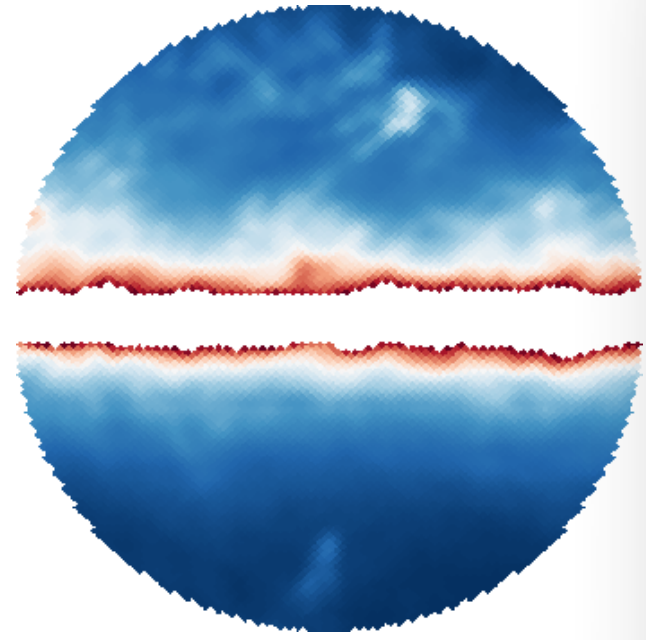
Macias et al [Nat. Ast. 2017]

## TS improvement over previous models



Buschmann et al incl. SM [PRD 2020]

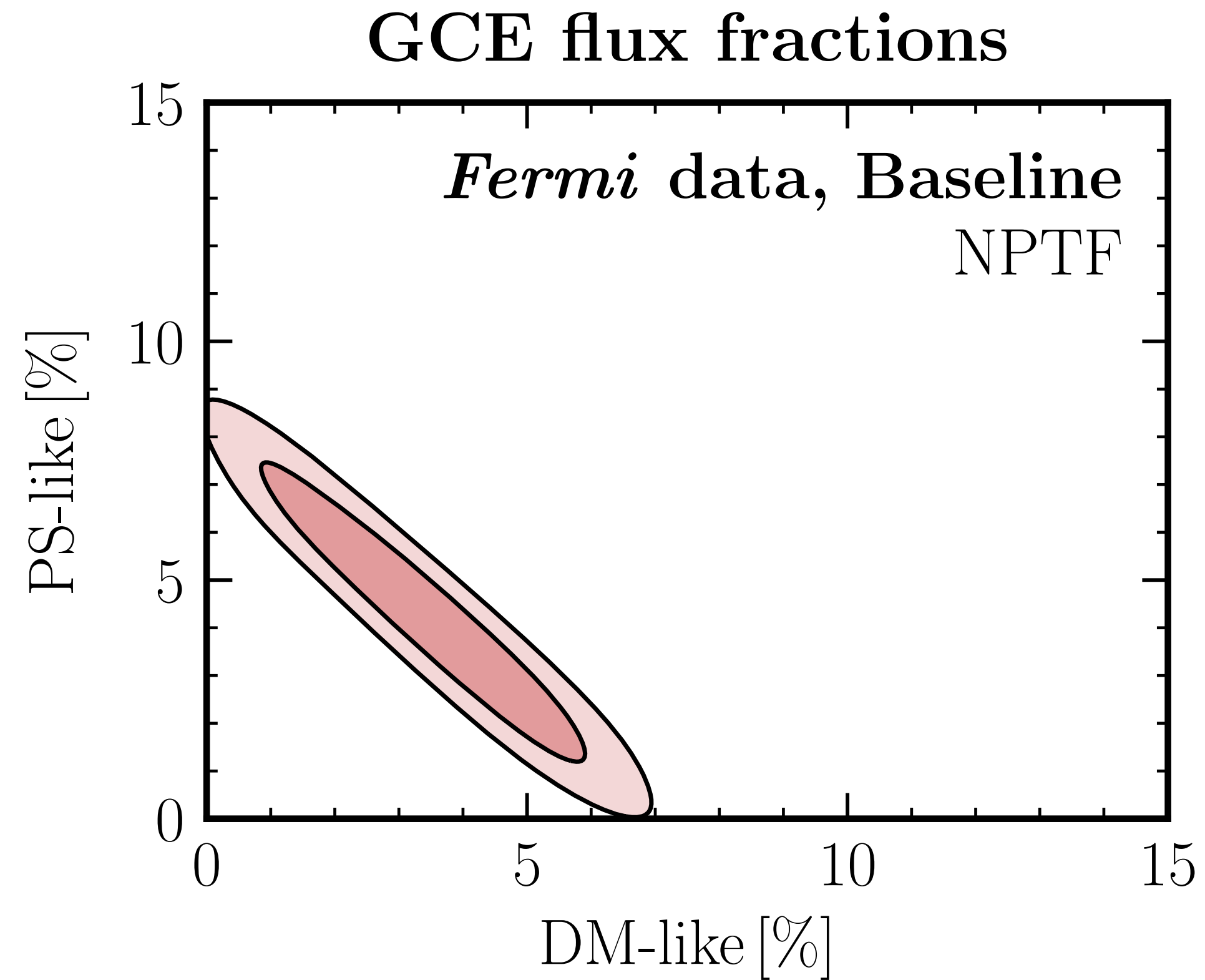
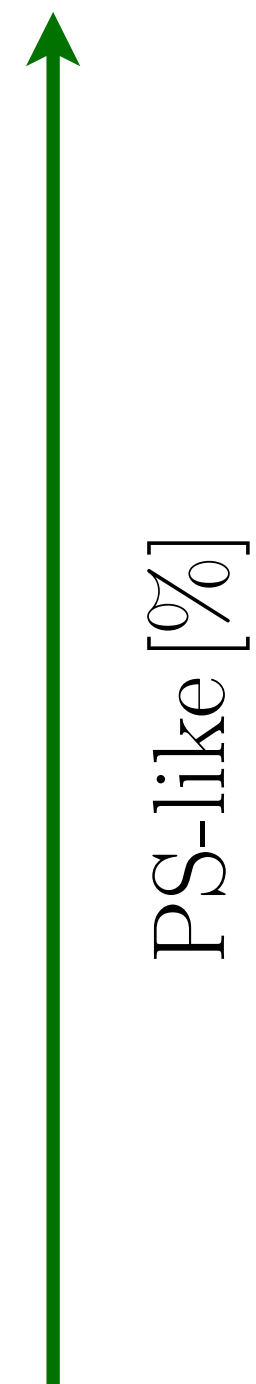
# Better diffuse models



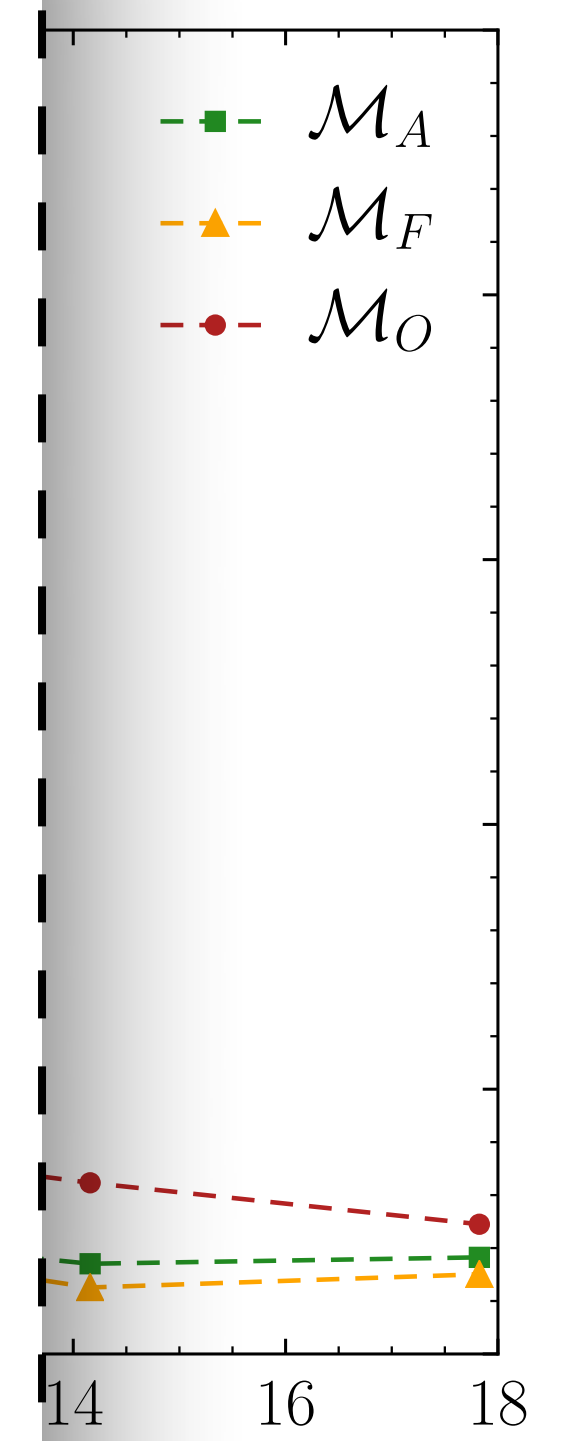
Background  
Model p6v11

- Updated gas tracers
- 3D radiation field for IC
- Components fit in several

Macias et al [JCAP 2019]  
Macias et al [Nat. Ast. 2017]



models



[D 2020]

*The use of updated diffuse models shows a reduced but still significant preference for unresolved points sources*

# Giving the diffuse background mode freedom

*Less freedom*

*More freedom*



*Less conservative*

*More conservative*

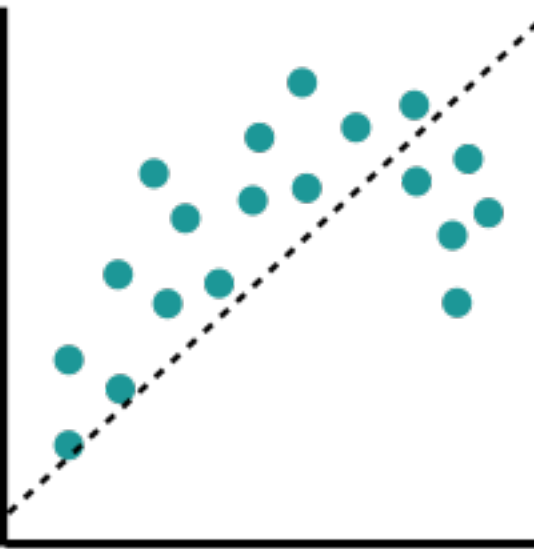
*More information about signal*

*Less extractable information about signal*

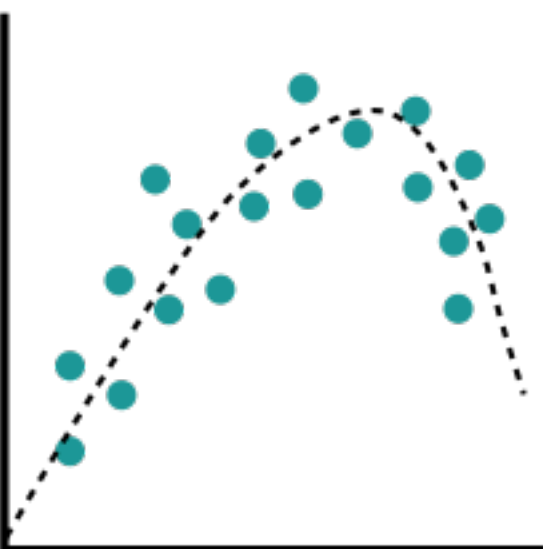
*Contingent on background model*

*"Background model-independent"*

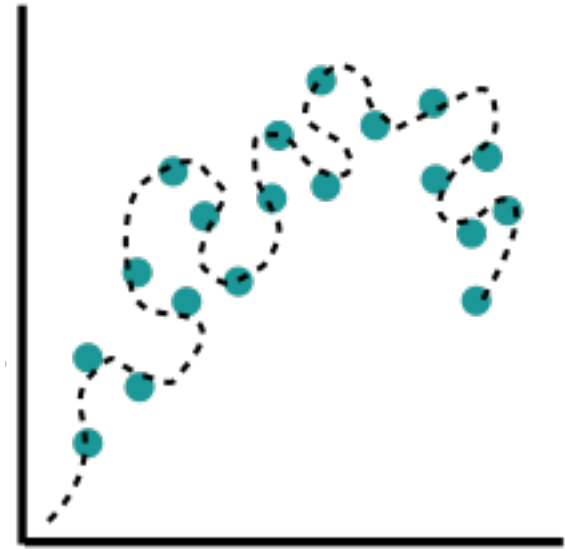
*Underfit*



*Balanced*

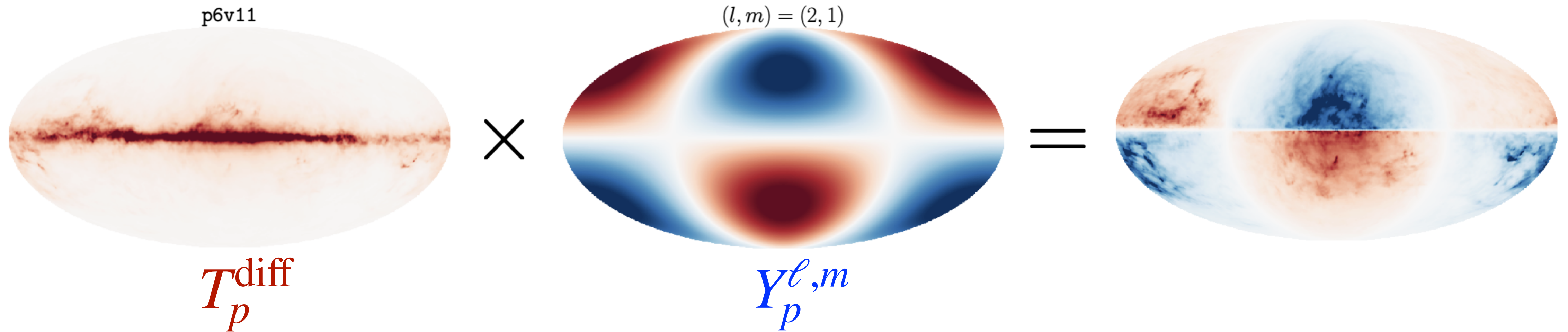


*Overfit*



# (Large-scale) harmonic marginalization

Extract large-scale harmonic components of diffuse model



$$T_p^{\text{harm}} \propto \underbrace{\hat{A}_{\text{diff}} T_p^{\text{diff}}}_{\text{Base model}} + \underbrace{\sum_{\ell, m} \hat{A}_{\ell, m} Y_p^{\ell, m} T_p^{\text{diff}}}_{\text{Modulation of large scales}}$$

*Give each large-scale component an independent degree of freedom*

# Gaussian process-augmented diffuse models

Traditional template fitting

Augment background template with a GP

The diagram illustrates the decomposition of a galaxy image into templates for traditional fitting and an augmented model with a Gaussian Process. The equation is:

$$\text{Galaxy Image} = \text{Pois} \left( A_{\text{bub}} \times \text{Bubble Template} + A_{\text{iso}} \times \text{Isothermal Template} + A_{\text{PS}} \times \text{Point Source Template} + A_{\text{DM}} \times \text{Dark Matter Template} + \exp(\text{GP}) \times \text{GP-Augmented Template} \right)$$

The traditional template fitting part (left) shows a galaxy image being decomposed into a sum of templates: bubble-like structures, an isothermal background, point sources, and dark matter. The augmented model part (right) adds a Gaussian Process (GP) component to the background template, represented by a template with a red and blue gradient.

# Gaussian process-augmented diffuse models

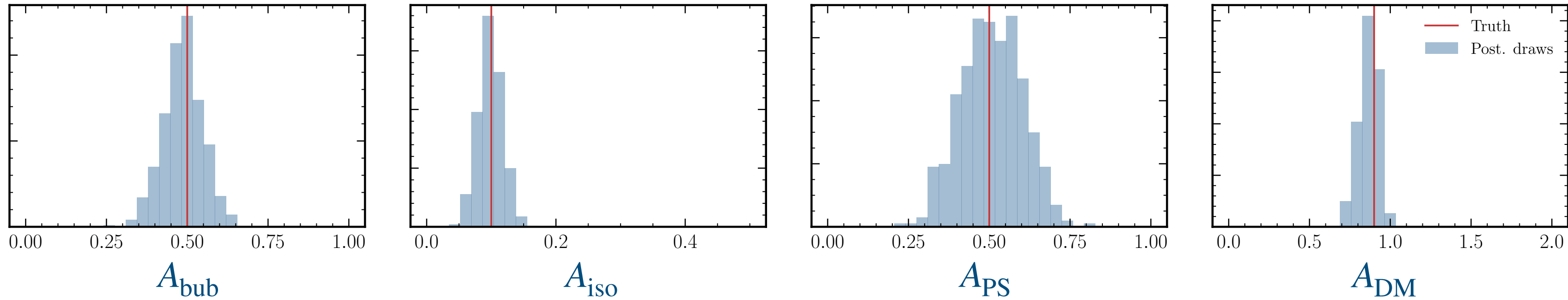
Traditional template fitting

$$\text{Observed Map} = \text{Pois} \left( A_{\text{bub}} \times \text{Bubbles} + A_{\text{iso}} \times \text{Isotropic} + A_{\text{PS}} \times \text{Point Sources} + A_{\text{DM}} \times \text{DM} \right)$$

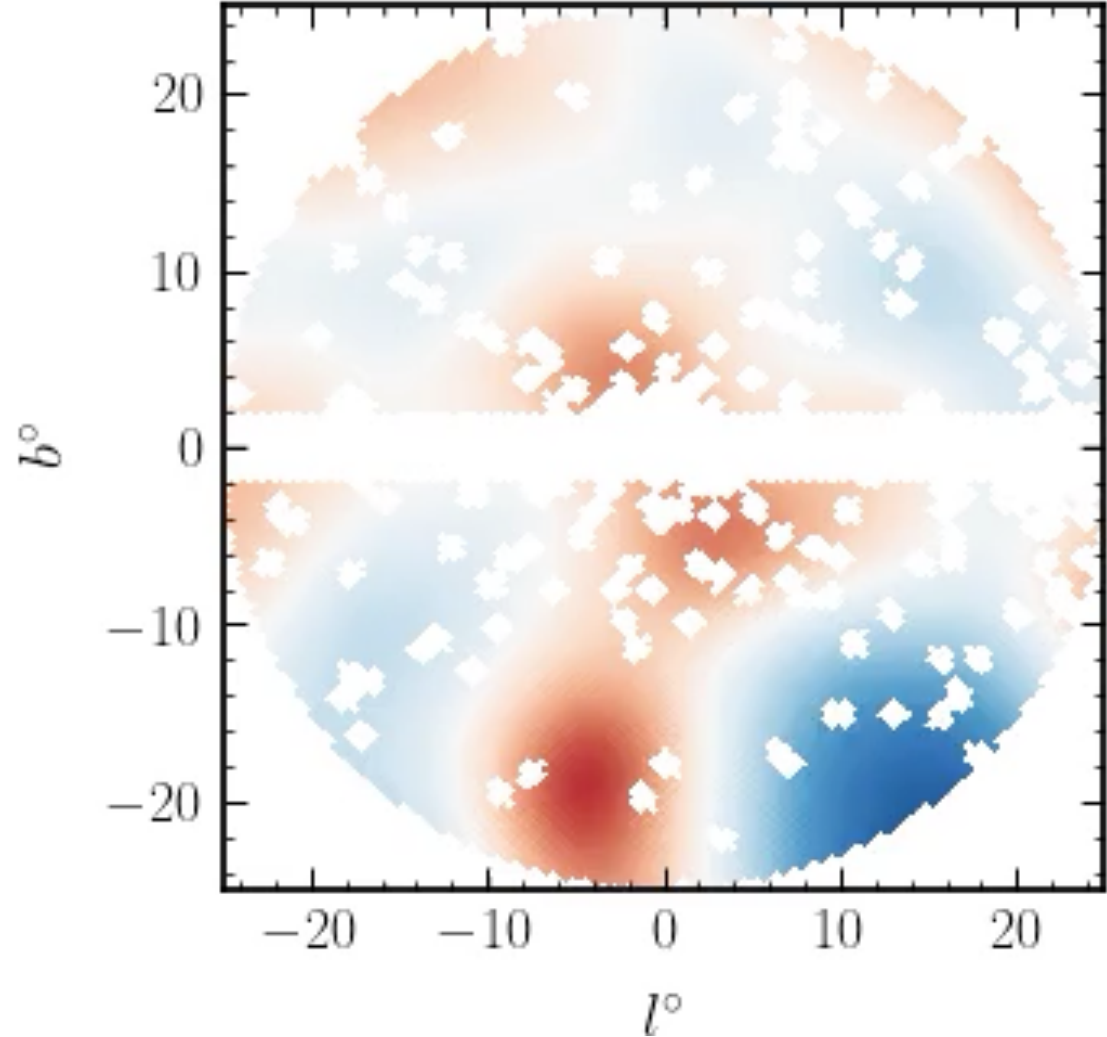
Augment background template with a GP

$$+ \exp(\text{GP}) \times \text{Background Template}$$

Component norm posteriors



GP posterior



# Gaussian process-augmented diffuse models

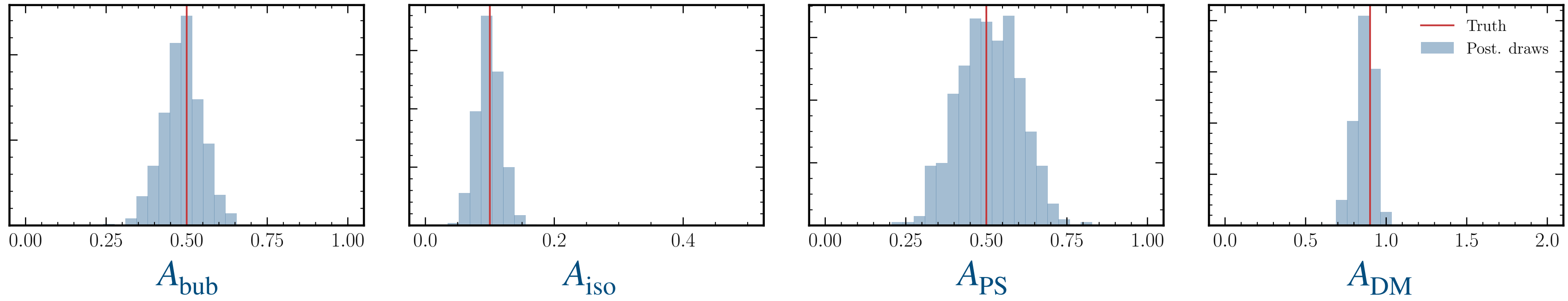
Traditional template fitting

$$\text{Observed Map} = \text{Pois} \left( A_{\text{bub}} \times \text{Bubbles} + A_{\text{iso}} \times \text{Isotropic} + A_{\text{PS}} \times \text{Point Sources} + A_{\text{DM}} \times \text{DM} \right)$$

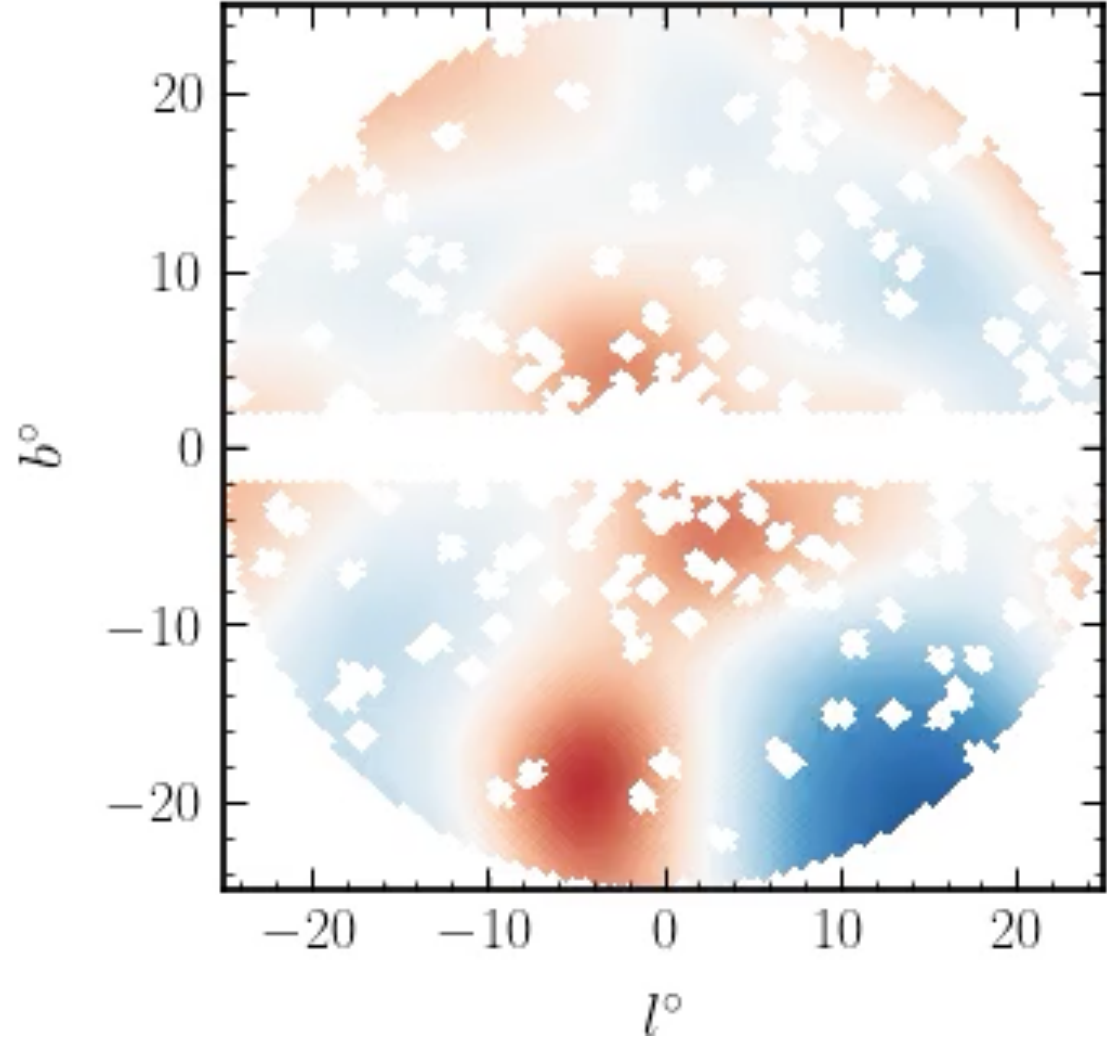
Augment background template with a GP

$$+ \exp(\text{GP}) \times \text{Background Template}$$

Component norm posteriors



GP posterior

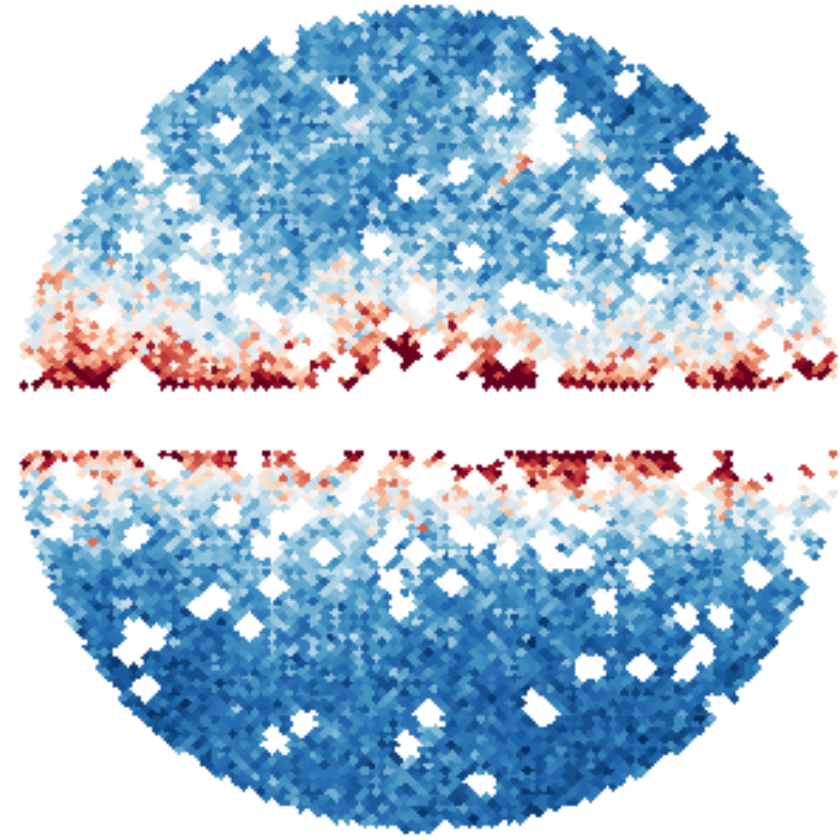


Sparse variational GPs in GPpyTorch

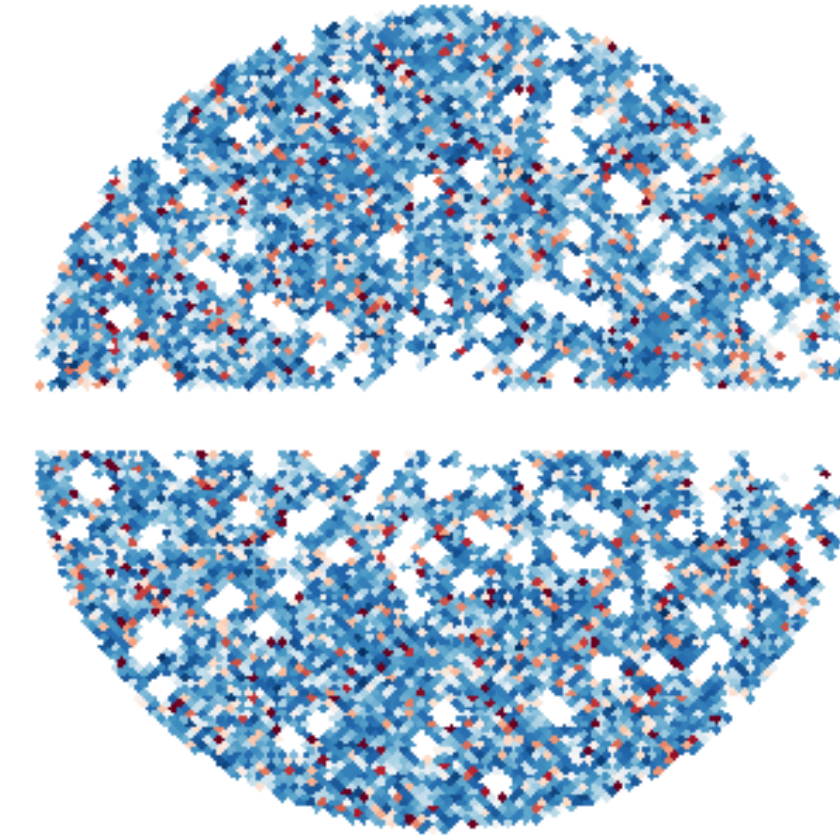
SM, Cranmer [NeurIPS ML4PS Workshop 2020]

# Information content in the 1-point PDF

Original data map

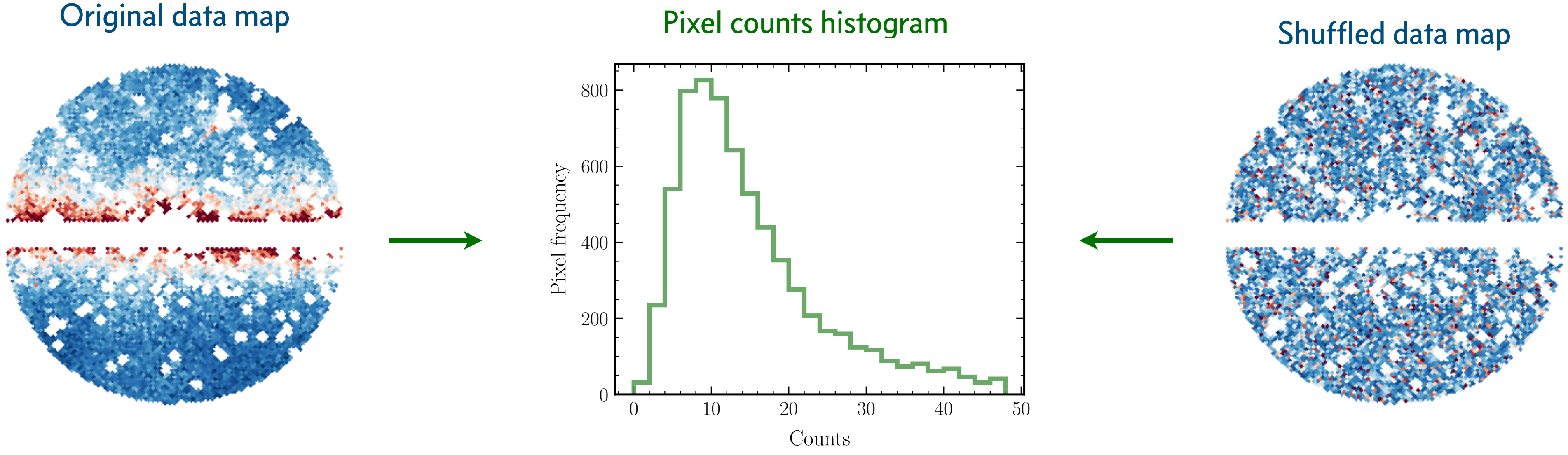


Shuffled data map

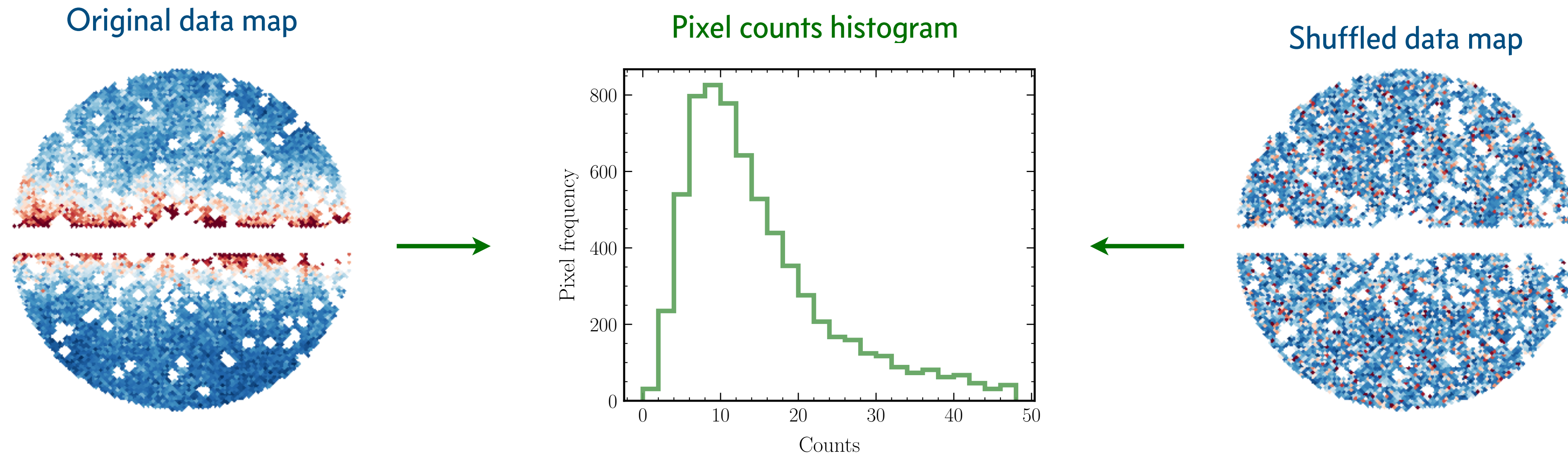




# Information content in the 1-point PDF



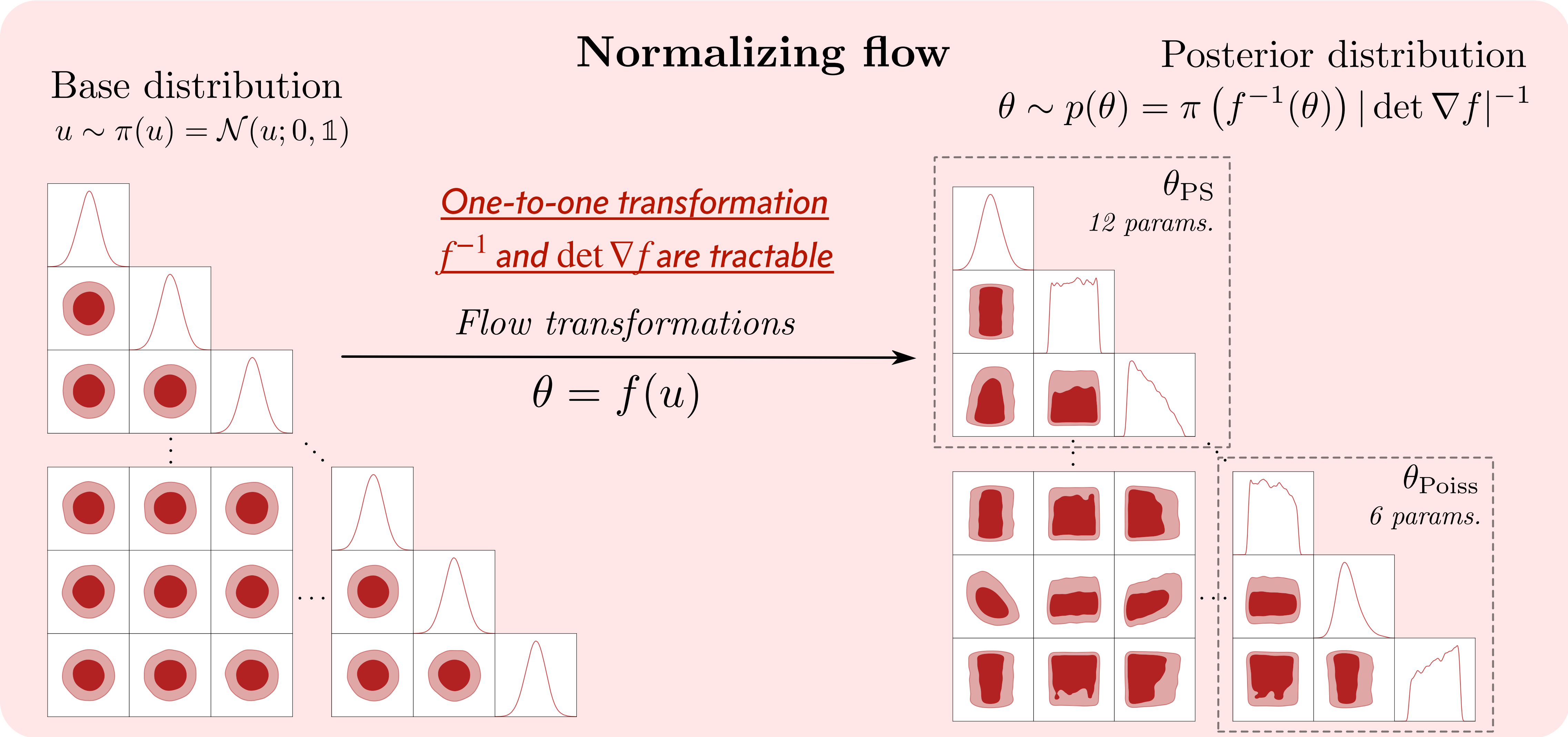
# Information content in the 1-point PDF



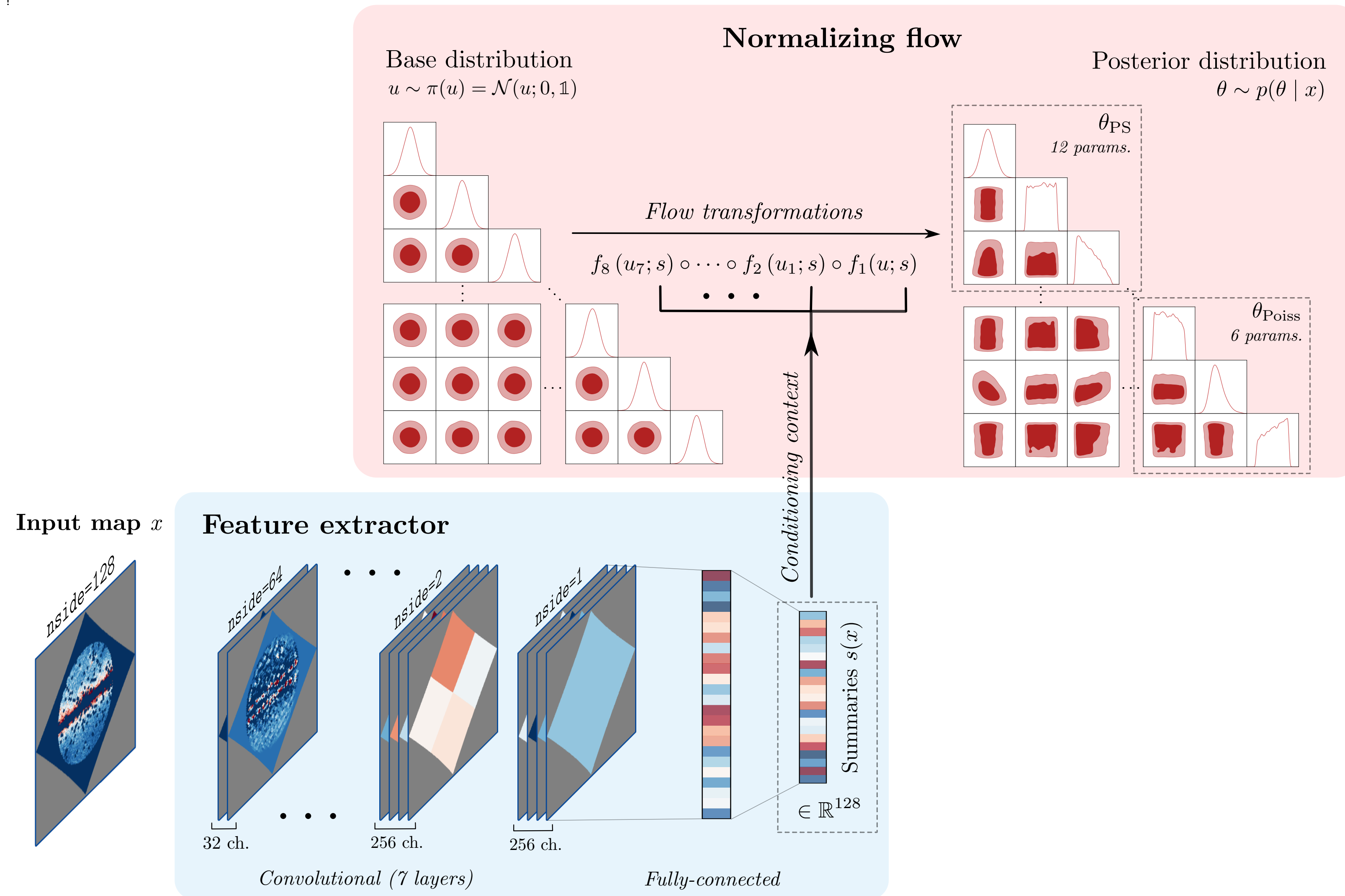
Can we model the full likelihood  $p(x | \theta)$  instead of the per-pixel likelihood  $\prod_p p(x^p | \theta)$  ?

*Exploiting higher-order statistics can “regularize” issues associated with model misspecification*

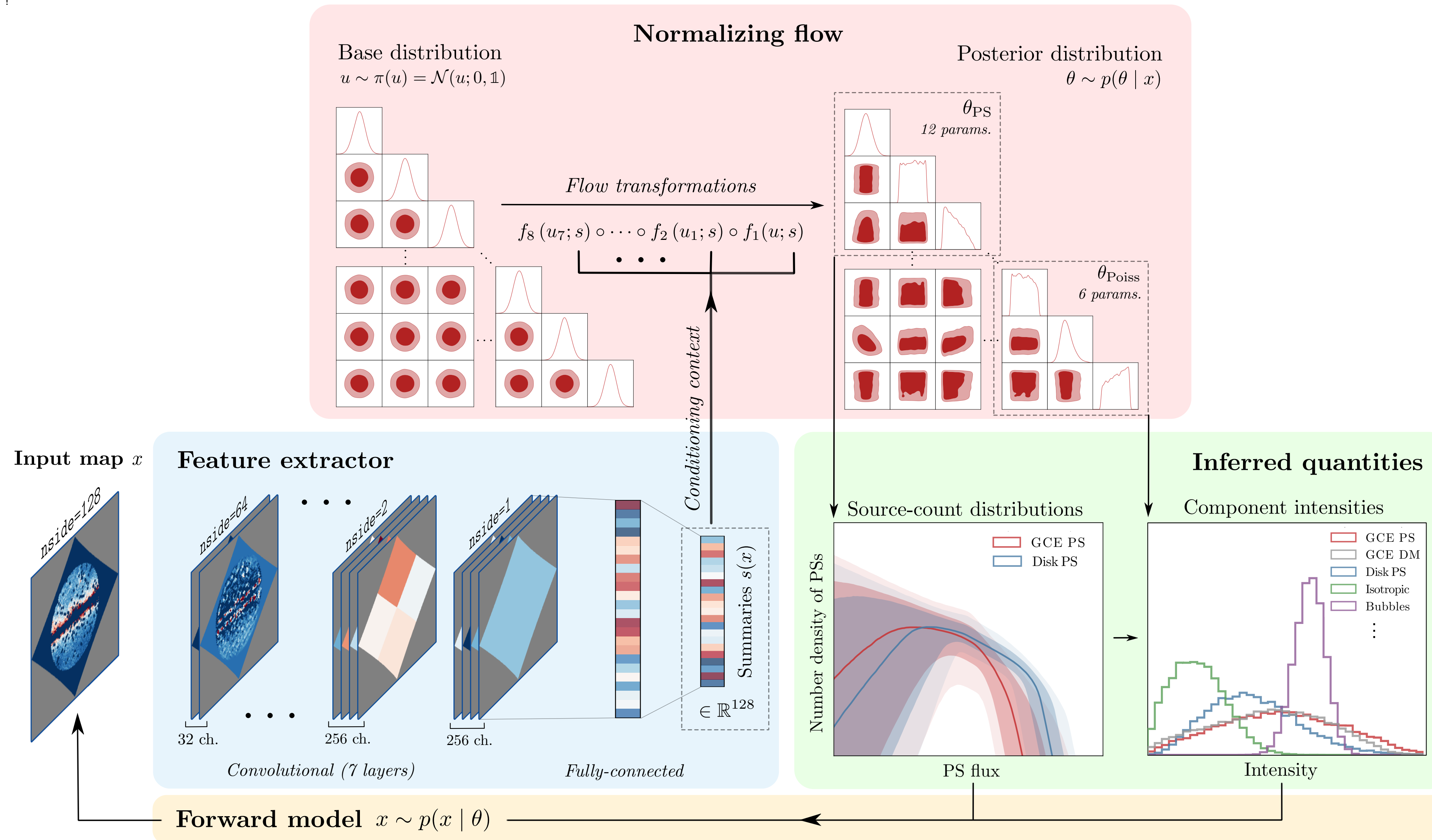
# Modeling the posterior with normalizing flows



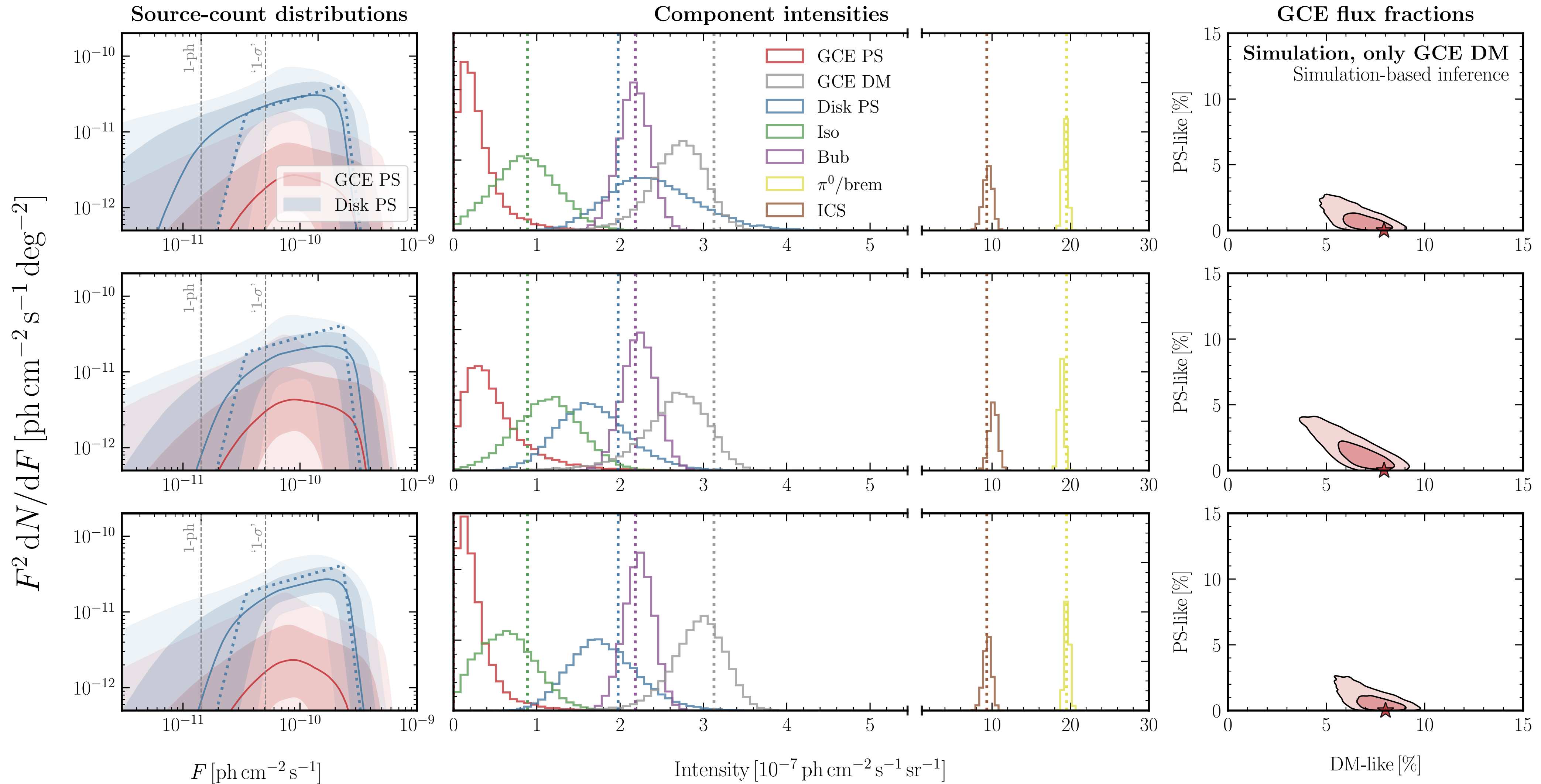
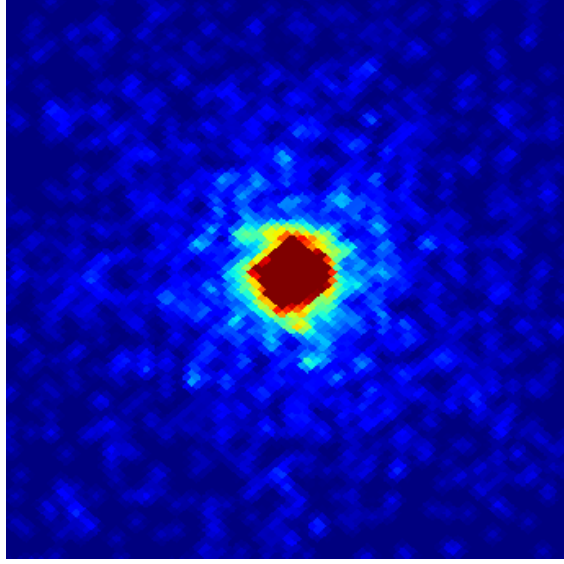
# Going beyond the 1-point PDF with SBI



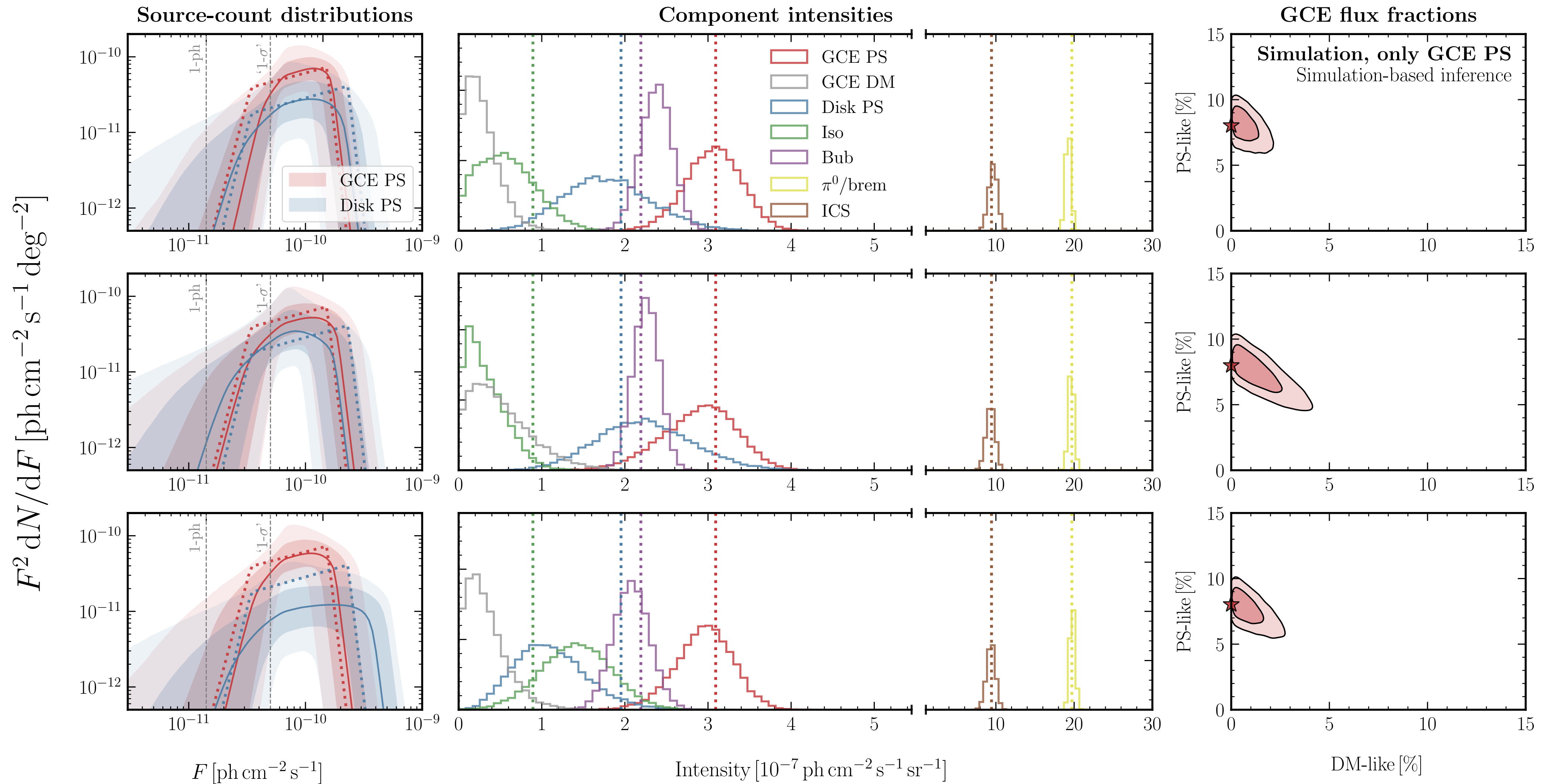
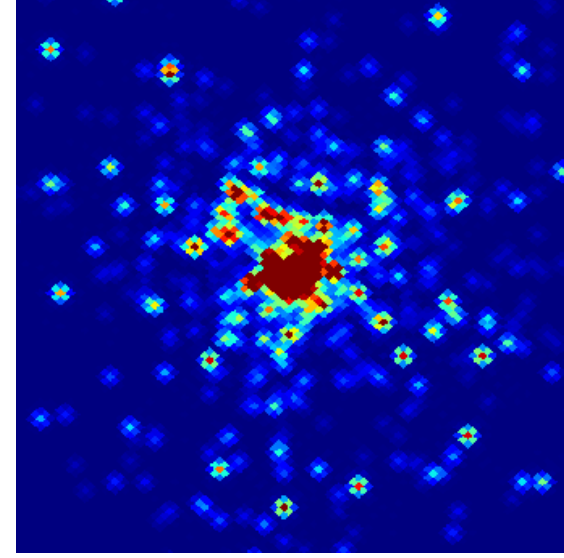
# Going beyond the 1-point PDF with SBI



# Tests on simulations: DM only

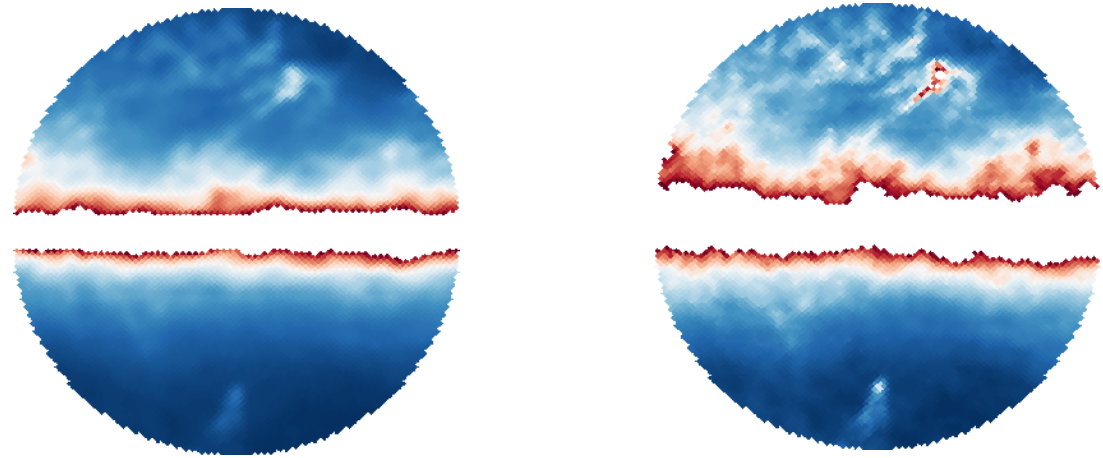


# Tests on simulations: PS only

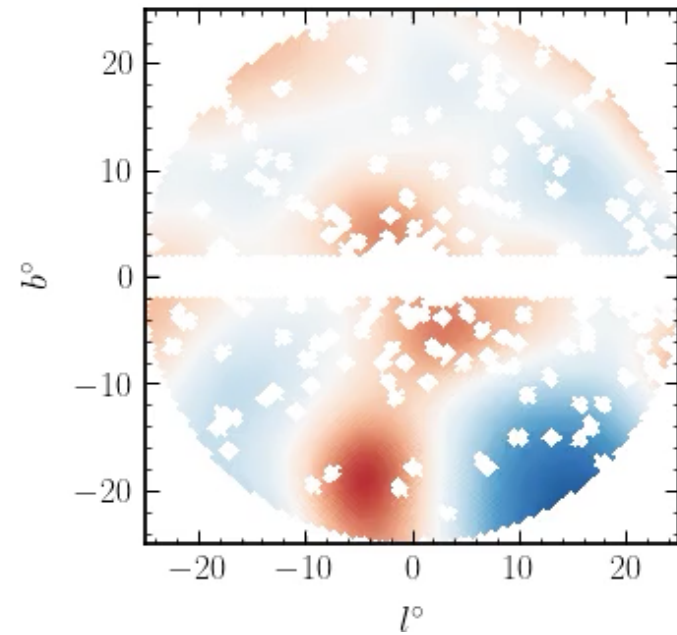


# Robustness test: mismodeling with DM

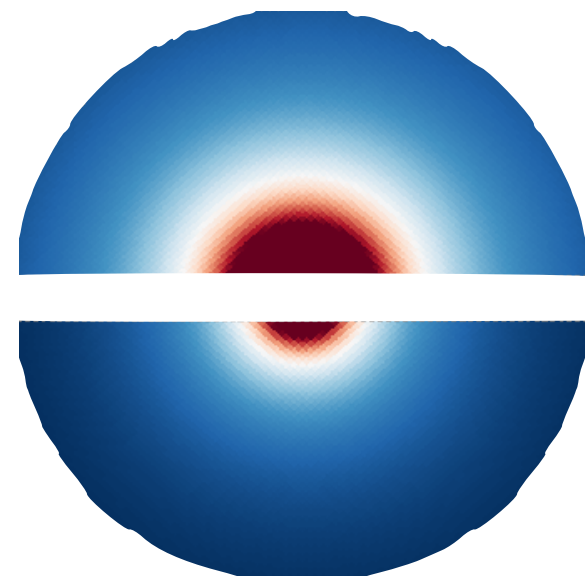
Train with one diffuse model /  
test with another



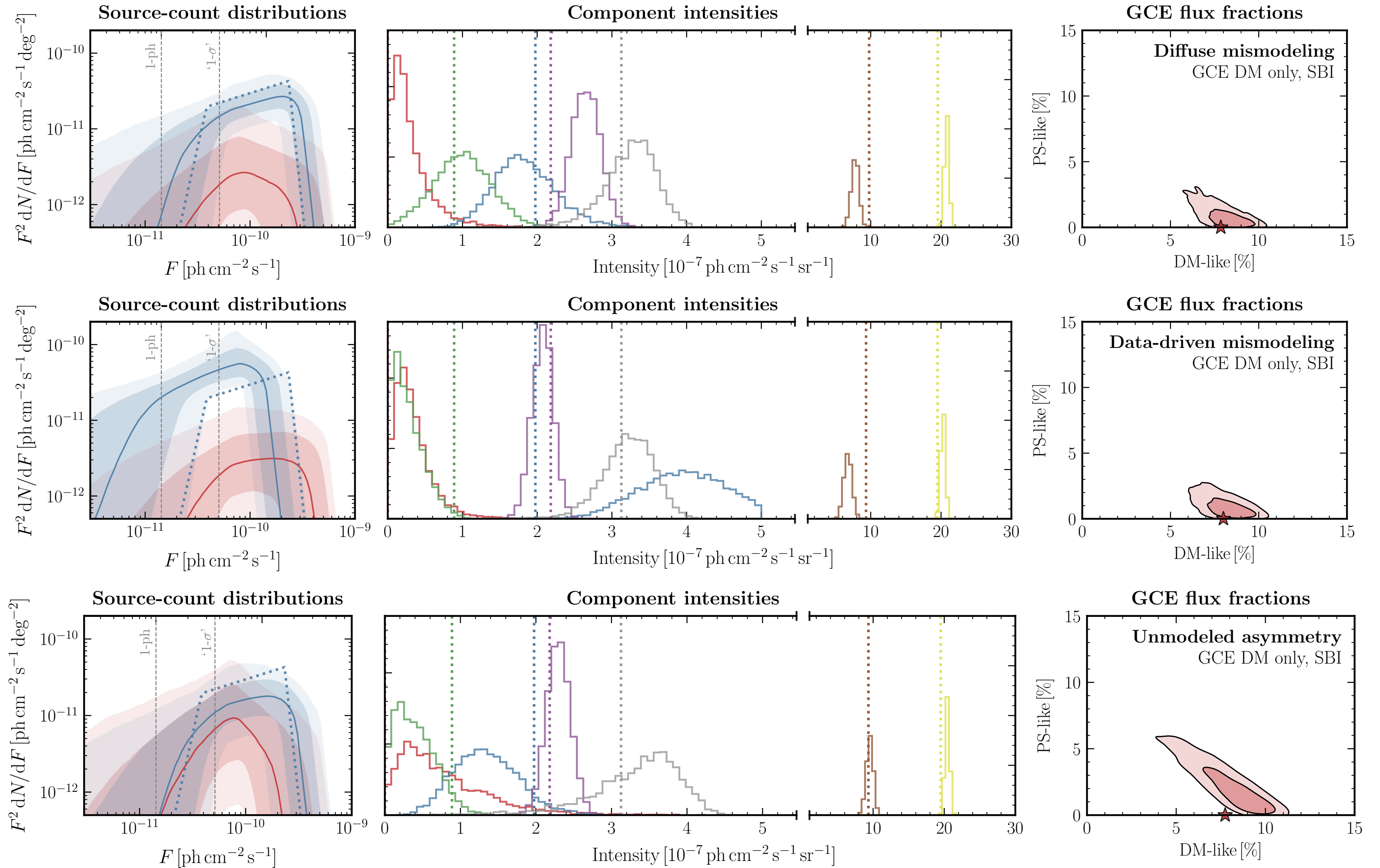
Test on  
GP-modulated  
background



Test on  
Substantially-  
asymmetric  
signal



(cf. Leane & Slatyer [PRL 2020, PRD 2020])

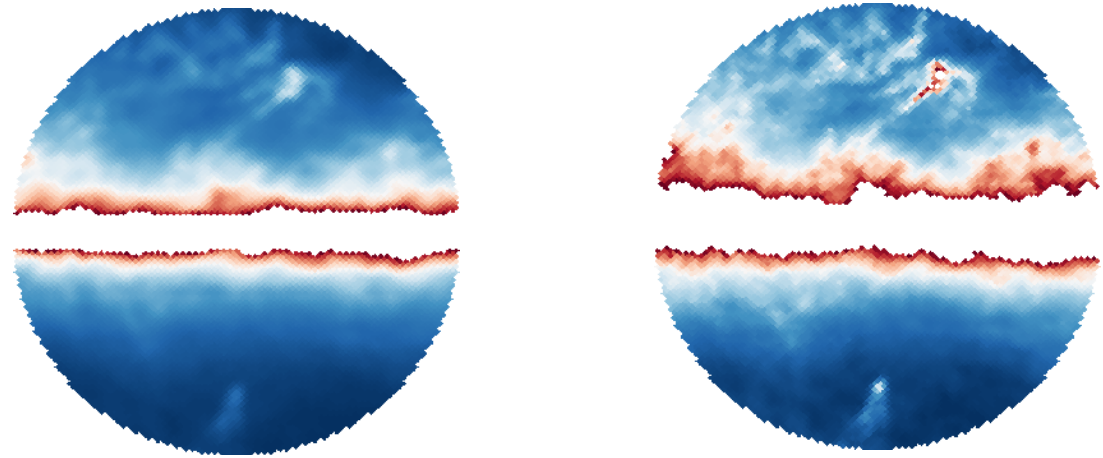


*Generally well-behaved under known forms of systematic mismodeling*

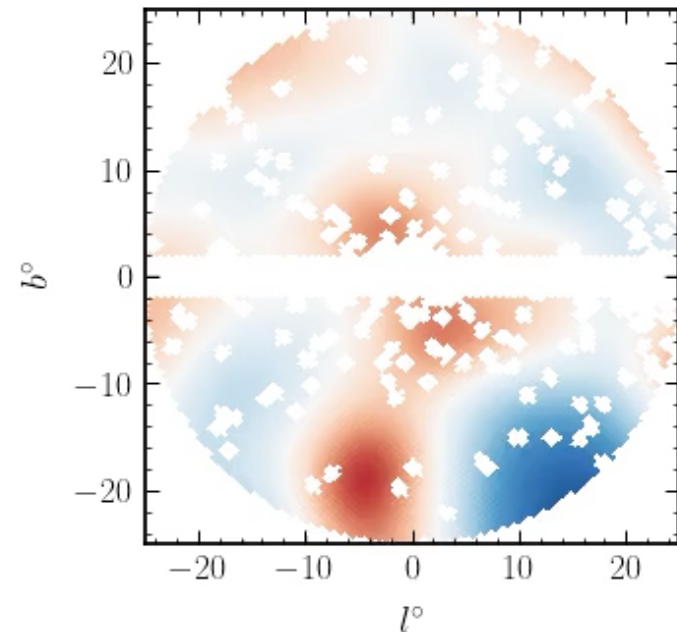


# Robustness test: mismodeling with DM

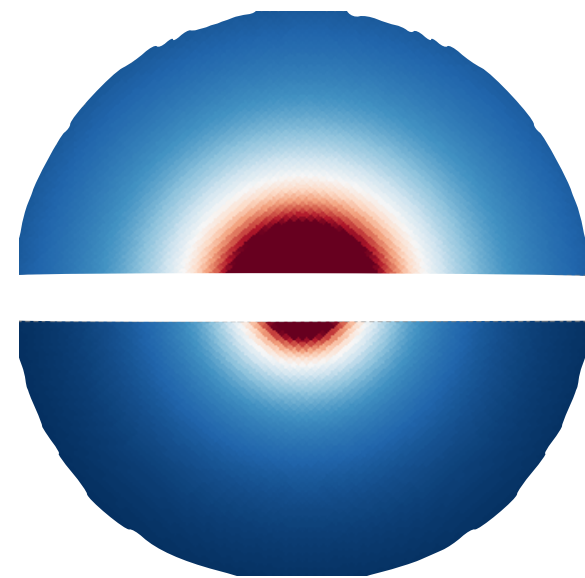
Train with one diffuse model /  
test with another



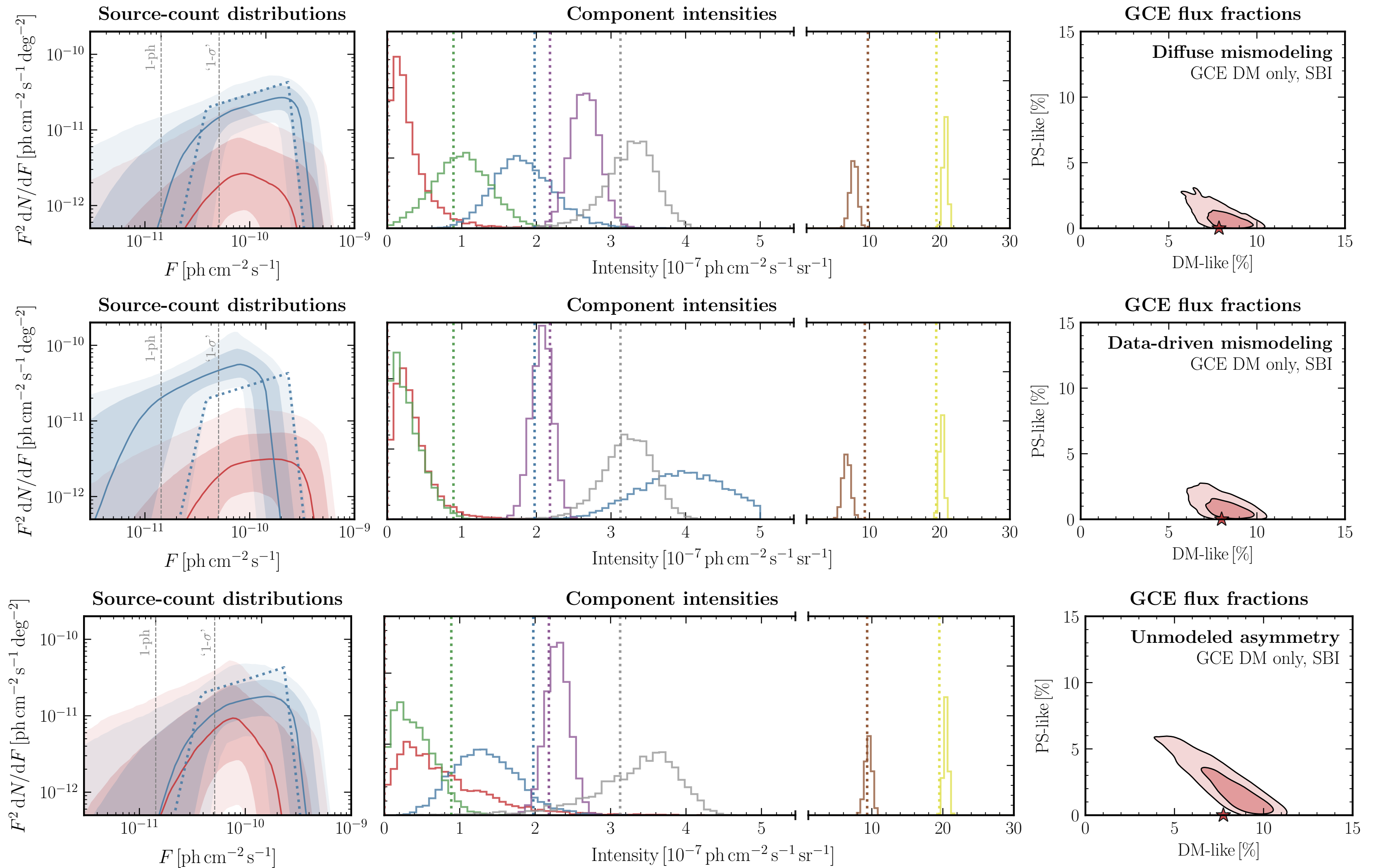
Test on  
GP-modulated  
background



Test on  
Substantially-  
asymmetric  
signal



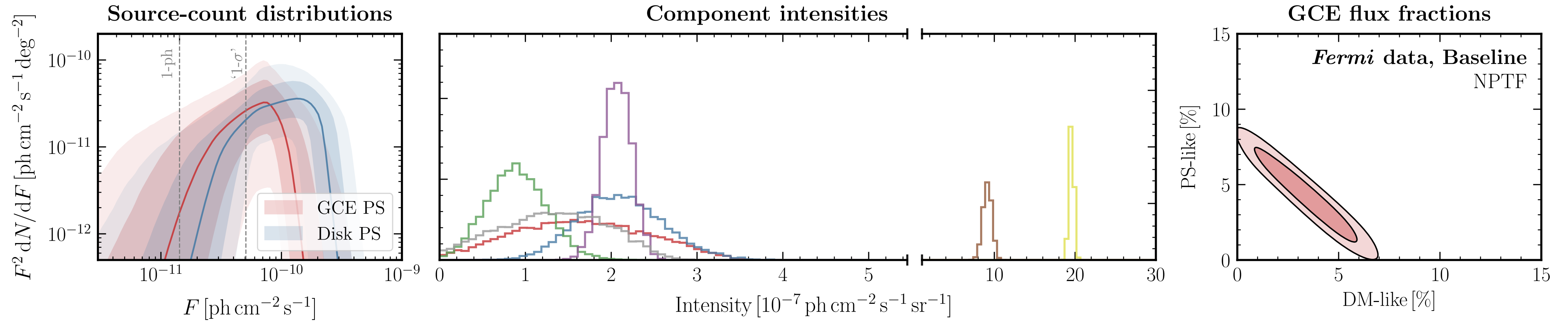
(cf. Leane & Slatyer [PRL 2020, PRD 2020])



*Generally well-behaved under known forms of systematic mismodeling*

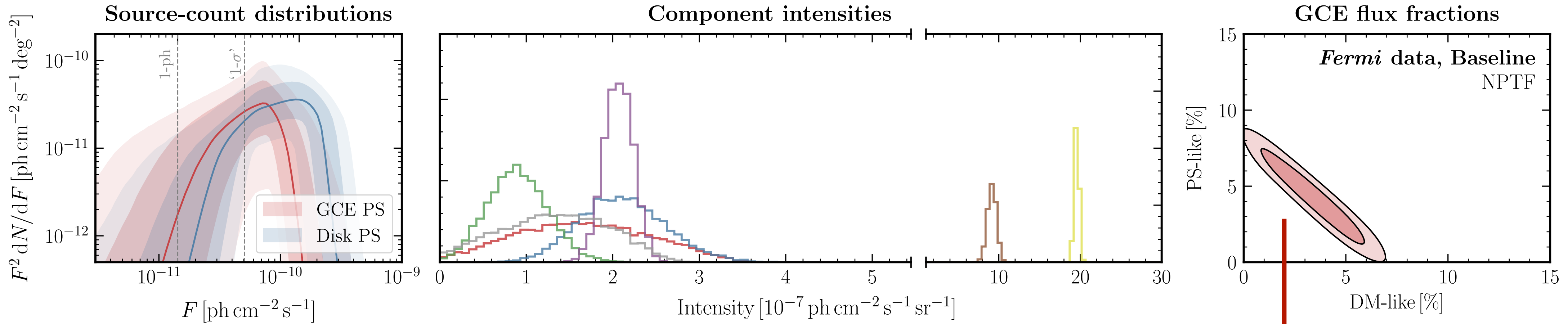
# Application to *Fermi* $\gamma$ -ray data

NPTF

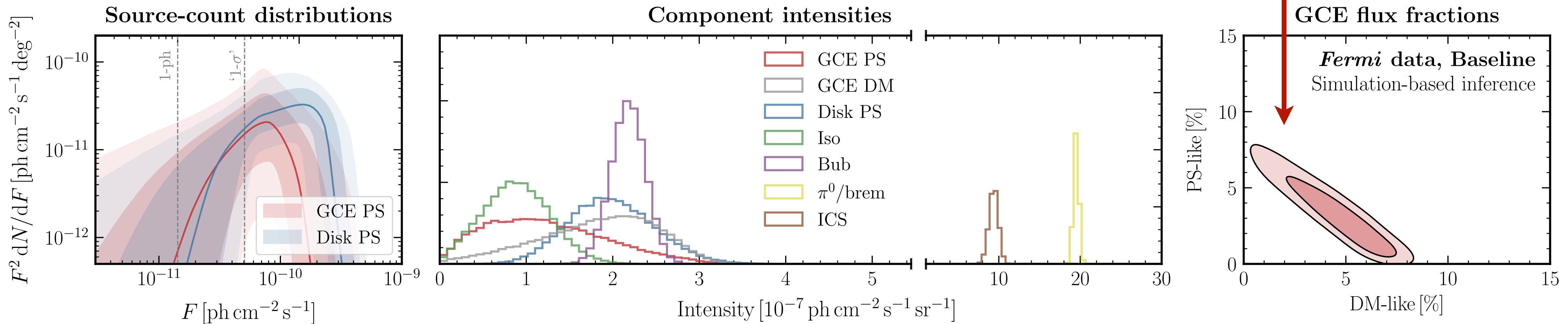


# Application to *Fermi* $\gamma$ -ray data

NPTF

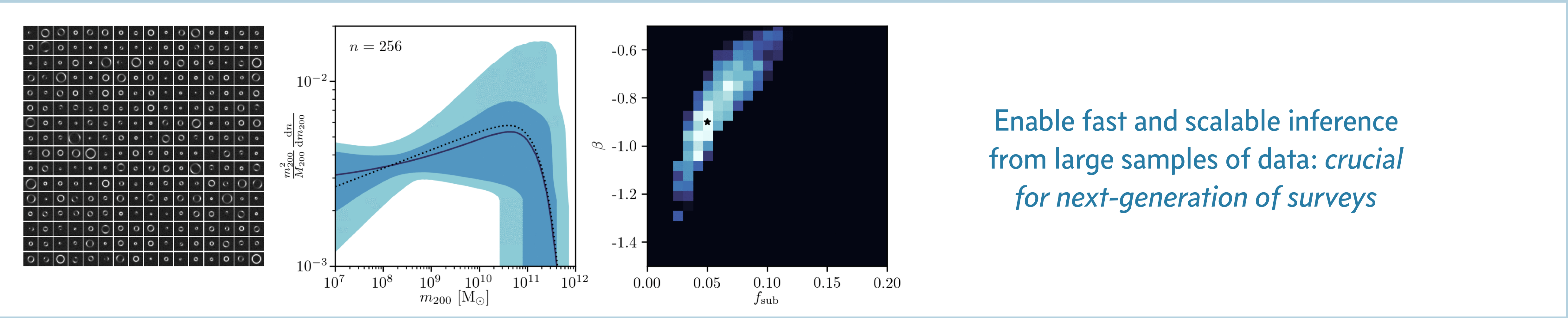


SBI

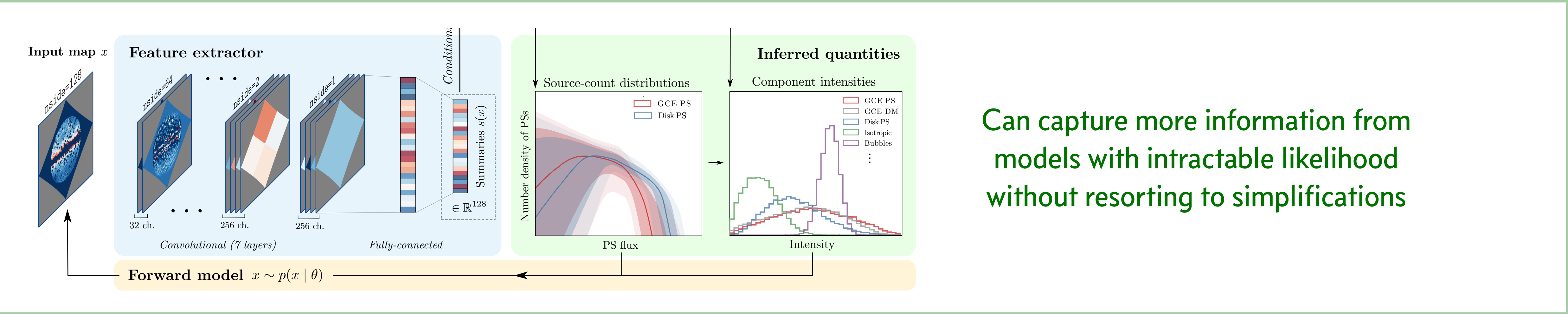


**Exploiting more information in the  $\gamma$ -ray maps results in smaller, but still significant PS-like component**


# Conclusions



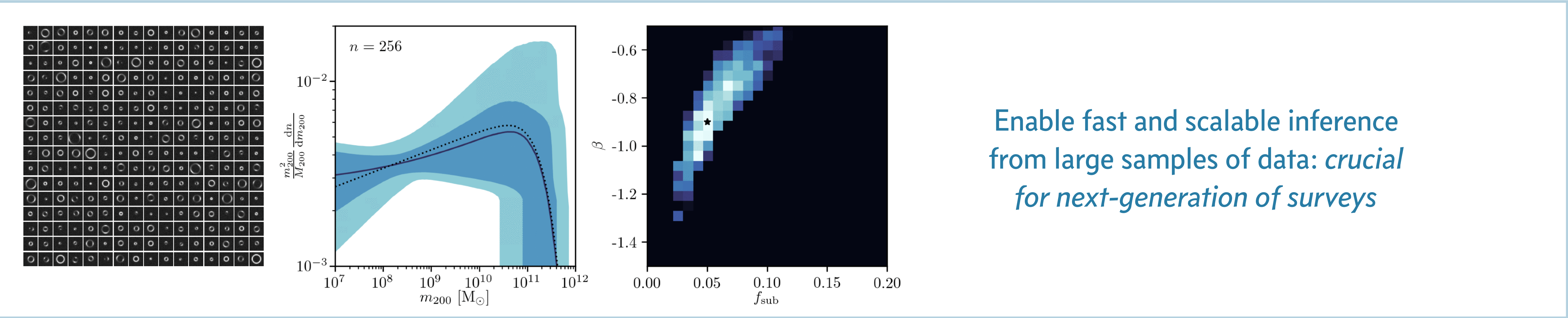
Enable fast and scalable inference from large samples of data: *crucial for next-generation of surveys*



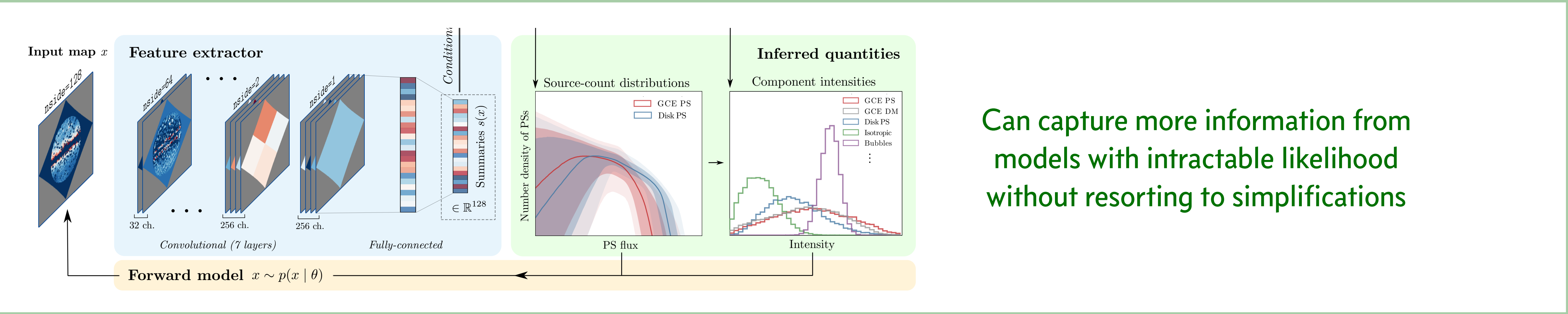
Can capture more information from models with intractable likelihood without resorting to simplifications

 [github.com/smsharma/mining-for-substructure-lens](https://github.com/smsharma/mining-for-substructure-lens)  
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# Conclusions



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